

Two dialects for KZB equations: generating one-loop open-string integrals

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Abstract

Two different constructions generating the low-energy expansion of genus-one configuration-space integrals appearing in one-loop open-string amplitudes have been put forward in refs. [1, 2]. We are going to show that both approaches can be traced back to an elliptic system of Knizhnik–Zamolodchikov–Bernard(KZB) type on the twice-punctured torus.

We derive an explicit all-multiplicity representation of the elliptic KZB system for a vector of iterated integrals with an extra marked point and explore compatibility conditions for the two sets of algebra generators appearing in the two differential equations.

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1 Introduction and summary

During the last years we have been experiencing a significant growth in understanding the mathematical concepts leading to recursion relations for scattering amplitudes in quantum field and string theory. A multitude of languages and approaches is available for various quantum field theories, see for instance [3–10] and references therein. Recent progress on string amplitudes in turn was driven by disentangling their polarization degrees of freedom from moduli-space integrals over punctured worldsheets and finding separate recursions for both types of building blocks. The low-energy expansion of string amplitudes exposed by such recursions at tree and loop level contains a wealth of information on relations between gauge theories and gravity, string

dualities and counterterms including their non-renormalization theorems. For the moduli-space integrals in open-string tree-level amplitudes, a recursion based on the Knizhnik-Zamolodchikov equation was already identified in ref. [11] based on refs. [12, 13] and later complemented by other methods put forward in refs. [14, 15].

The problem of finding a one-loop (or genus-one) analogue of the open-string tree-level recursions was long-standing. A first mathematical challenge was to thoroughly understand iterated integrals on the elliptic curve and their associated special values, elliptic multiple zeta values [16–19]. Then, the cooperation of mathematicians and physicists was instrumental to investigate and understand the relation of those iterated integrals to one-loop open-string amplitudes and their differential equations [20–22]. The closed-string counterparts of these genus-one integrals lead to an intriguing system of non-holomorphic modular forms [23, 24] that inspired mathematical research lines including refs. [25–29].

These structural considerations paved the way for two recent methods [1, 2] to systematically evaluate the integrals over punctures on the boundary of a genus-one surface order by order in the inverse string tension α' . These integrals to be referred to as genus-one configuration-space integrals¹ form the backbone of one-loop open-string amplitudes. Both algorithms rely on differential equations of Knizhnik–Zamolodchikov–Bernard(KZB) type on a genus-one surface with boundaries.

- In ref. [1], a KZB-type differential equation with respect to the modular parameter τ , which encodes the geometry of genus-one surfaces, was established. Acting on a vector of generating functions for one-loop configuration-space integrals, the τ -derivative can be expressed as a linear operator that mixes the components in different vector entries. In particular, this exposes finite-dimensional conjectural matrix representations of a special derivation algebra with corresponding generators ϵ_k . Using Picard iteration, the equation can be solved starting from a particular value which is conveniently chosen as the limit $\tau \rightarrow i\infty$ where the genus-one configuration-space integrals degenerate to their genus-zero counterparts with two additional legs.
- In ref. [2], a KZB-type differential equation with respect to the position of an auxiliary point z_0 was identified. Facilitating a vector of configuration-space integrals with the auxiliary point (genus-one Selberg integrals), a solution can be obtained using the KZB associator: it relates two regularized boundary values, which emerge when sending the auxiliary point to the poles of the differential equation in two distinct ways. At one boundary value one obtains the one-loop configuration-space integrals, while at the other boundary one recovers again genus-zero configuration-space integrals with two additional legs. The main players in the construction are infinite-dimensional matrix representations of an algebra with generators x_k , which can be cut off to finite size when calculating up to a certain order in the α' -expansion of the string amplitudes.

The two algorithms relate open-string tree-level and one-loop amplitudes in the same way: both are capable of determining the n -point configuration-space integrals at genus one from $(n+2)$ -point configuration-space integrals at genus zero. On the contrary, the representations of the KZB equations and underlying algebra generators are quite distinct. The relation between the two approaches can be best understood and investigated by considering a formalism combining the advantages of each of the previous methods: the central object to be considered in this

¹We distinguish *moduli-space integrals* over both the punctures z_i and the modular parameter τ of a genus-one surface from the *configuration-space integrals* over the z_i which are still functions of τ .

article is a length- $n!$ vector of generating functions for planar n -point one-loop configuration-space integrals to be denoted by $\mathbf{Z}_{0,n}^\tau$ with an auxiliary point z_0 : In particular

- a) we will find an all-multiplicity expression for the τ -derivative of $\mathbf{Z}_{0,n}^\tau$ in order to connect with the approach in ref. [1]. This will be an equation of the form

$$2\pi i \partial_\tau \mathbf{Z}_{0,n}^\tau = \left(D_{0,n}^\tau(\{\epsilon_k\}) + B_{0,n}^\tau(\{x_j\}) \right) \mathbf{Z}_{0,n}^\tau, \quad k = 0, 4, 6, 8, \dots, \quad j = 1, 2, 3, \dots, \quad (1.1)$$

where the operators $D_{0,n}^\tau$ and $B_{0,n}^\tau$ are $n! \times n!$ matrices with entries proportional to α' .

- b) we will rewrite the formalism of ref. [2] in terms of the vector of generating series $\mathbf{Z}_{0,n}^\tau$, leading to finite-size matrix representations and an all-multiplicity expression for the z_0 -derivative of $\mathbf{Z}_{0,n}^\tau$ of the form

$$\partial_{z_0} \mathbf{Z}_{0,n}^\tau = X_{0,n}^\tau(\{x_k\}) \mathbf{Z}_{0,n}^\tau, \quad k = 0, 1, 2, \dots, \quad (1.2)$$

where $X_{0,n}^\tau$ is a $n! \times n!$ matrix proportional to α' as well. The constituents x_k are related to the braid matrices that govern the genus-zero counterparts of $\mathbf{Z}_{0,n}^\tau$ [30].

Hence, the generating functions $\mathbf{Z}_{0,n}^\tau$ of genus-one configuration-space integrals to be introduced in this work furnish integral representations for solutions to the elliptic KZB system. Having two differential equations (1.1) and (1.2) at our disposal, we can demand commutativity of the two derivatives. This implies consistency conditions for the two classes of algebra generators involved. We have checked on a case-by-case basis that our realizations of the generators satisfy these relations.

In section 2 we are going to provide the mathematical and physical setting: we will discuss genus-zero and genus-one configuration-space integrals contributing to tree-level and one-loop open-string scattering amplitudes, respectively. This will set our conventions and incorporate a review of general properties of configuration-space integrals, iterated integrals and (elliptic) multiple zeta values. Section 3 is devoted to the discussion of several types of differential equations allowing for recursive solutions: in subsection 3.1 we review the genus-zero recursion from ref. [11] and bring it into the context of the later genus-one results. In subsections 3.2 and 3.3 we discuss the τ -based and z_0 -based genus-one recursions from ref. [1] and ref. [2], respectively. The central object to be discussed in section 4 is the vector of configuration-space integrals $\mathbf{Z}_{0,n}^\tau$ with an auxiliary point. After introducing the vector, we will perform the two steps a) and b) lined out above, resulting in an all-multiplicity representation of the elliptic KZB system on the twice-punctured torus. By considering the regularized boundary values for the elliptic KZB system, we will relate the different approaches in section 5, before we conclude in section 6.

2 Open-string scattering amplitudes and configuration-space integrals

In this review section we will introduce several mathematical objects and concepts necessary for the description of open-string scattering amplitudes at genus zero and genus one. Rather than providing yet another thorough and detailed introduction, we will just mention and collect the key concepts here and provide numerous links to elaborate discussions.

The structure of scattering amplitudes in open-string theories can be most easily captured and understood when disentangling the results from evaluation of a conformal worldsheet cor-

relator: the latter depends on the external polarizations through a *kinematical part* which we will separate from the *moduli-space integrals* that encode string corrections to field-theory amplitudes through their series expansion in α' . Moduli-space integrals are dimensionless as they depend on dimensionless Mandelstam variables

$$s_{i_1 i_2 \dots i_r} = -\alpha' (k_{i_1} + k_{i_2} + \dots + k_{i_r})^2, \quad 1 \leq i_k \leq n, \quad (2.1)$$

where n denotes the number of external particles. Their integrands are calculated as conformal correlators of vertex positions z_i on Riemann surfaces, whose genus refers to the loop order in question. In the next two subsections, we are going to collect the basic formalism for the integration over open-string punctures at genus zero and one: tree level and one loop, respectively. Since we do not perform the integral over the modular parameter τ of genus-one surfaces in this work, the integrals over the z_i will be referred to as *configuration-space integrals* in contradistinction to the full *moduli-space integrals* entering one-loop string amplitudes.

The Mandelstam variables defined above in eq. (2.1) are going to take a role as (complex) parameters in the configuration-space integrals to be considered in this article. Naturally, the convergence behavior of those integrals depends on the values of the Mandelstam variables. Convergent integrals are obtained, when the Mandelstam variables are taken to satisfy the conditions listed below, though one can analytically continue to different regions. The conditions are formulated in terms of Mandelstam variables whose indices are related to *consecutive* insertion points on the disk or cylinder boundary.

- For genus-zero configuration-space integrals, the issue of convergence was discussed at various places, see e.g. refs. [31, 32]: tree-level configuration-space integrals converge, if

$$\text{Re}(s_{i_1 i_2 \dots i_r}) < 0 \text{ for all consecutive labels } i_1, i_2, \dots, i_r, \quad (2.2)$$

unless $s_{i_1 i_2 \dots i_r}$ vanishes by momentum conservation.

- For the augmented genus-one configuration-space integrals $\mathbf{Z}_{0,n}^\tau$, we relax momentum conservation and consider all the s_{ij} with $i < j$ as independent. Still, the above condition (2.2) for convergence carries over to the genus-one configuration-space integrals, where the notion of consecutive insertion points is adapted to an auxiliary puncture z_0 between z_n and z_1 . The associated auxiliary Mandelstam invariant s_{01} is furthermore taken to obey

$$\text{Re}(s_{i_1 i_2 \dots i_r}) < \text{Re}(s_{01}) < 0 \text{ for all consecutive labels } (i_1, i_2, \dots, i_r) \neq (0, 1), \quad (2.3)$$

which is no restriction in the applications to one-loop open-string amplitudes since s_{01} will drop out from the final results. In the context of one-loop open-string amplitudes, integrals of the type in $\mathbf{Z}_{0,n}^\tau$ are analytically continued from their region of convergence to physically sensible situations. The resulting singularities in the form of poles and branch cuts have been for example explored in [33].

2.1 Tree-level: genus zero

Calculating open-string amplitudes at tree level amounts to the evaluation of configuration-space integrals on a genus-zero surface with boundary. The corresponding genus-zero Green's function is a plain logarithm

$$\mathcal{G}_{ij}^{\text{tree}} = \log |z_{ij}| = G(0; |z_{ij}|) \quad (2.4)$$

of the distance

$$z_{ij} = z_i - z_j \quad (2.5)$$

of two insertion points. The notation G refers to the iterated integrals defined in eq. (2.10) below. In the configuration-space integrals, the Green's function appears in terms of the genus-zero Koba–Nielsen factor

$$\text{KN}_{12\dots n}^{\text{tree}} = \exp\left(-\sum_{1\leq i<j\leq n} s_{ij} \mathcal{G}_{ij}^{\text{tree}}\right) = \prod_{1\leq i<j\leq n} |z_{ij}|^{-s_{ij}}. \quad (2.6)$$

All configuration-space integrals for the calculation of open-string scattering amplitudes at tree level can be expressed as linear combinations of the integrals [34–36]

$$Z_n^{\text{tree}}(a_1, a_2, \dots, a_n | 1, 2, \dots, n) = \int_{-\infty < z_{a_1} < \dots < z_{a_n} < \infty} \frac{dz_1 \cdots dz_n}{\text{vol SL}_2(\mathbb{R})} \frac{\text{KN}_{12\dots n}^{\text{tree}}}{z_{12} z_{23} \cdots z_{n-1} z_n}, \quad (2.7)$$

where the labels a_1, \dots, a_n fix a certain succession of the insertion points on the disk boundary. An independent cyclic ordering selects the permutation of the inverse $z_{12} z_{23} \cdots z_{n-1} z_n$, the so-called Parke–Taylor factor. For a given multiplicity and particular choice of the labels a_i in the first slot, the collection of all integrals obtained for all permutations of the ordering $1, 2, \dots, n$ in the second slot is not independent: integrals over different Parke–Taylor factors are related by partial fraction and integration by parts [34, 35]. A convenient basis choice, which we are going to use throughout this article, consists of fixing the position of three of the labels in the Parke–Taylor factor, for example

$$\mathbf{Z}_n^{\text{tree}} = \left(Z_n^{\text{tree}}(a_1, a_2, \dots, a_n | 1, \sigma, n, n-1) \right) \text{ for } \sigma \in \mathcal{P}(2, 3, \dots, n-2). \quad (2.8)$$

For the choice of fixing the $\text{SL}_2(\mathbb{R})$ redundancy via $(z_1, z_{n-1}, z_n) = (0, 1, \infty)$ and the ordering to $(a_1, a_2, \dots, a_n) = (1, 2, \dots, n)$, the integrals are explicitly given by

$$Z_n^{\text{tree}}(1, 2, \dots, n | 1, \sigma, n, n-1) = - \int_{0 < z_2 < \dots < z_{n-2} < 1} dz_2 \cdots dz_{n-2} \frac{\prod_{1\leq i<j\leq n-1} |z_{ij}|^{-s_{ij}}}{z_{1\sigma(2)} z_{\sigma(2)\sigma(3)} \cdots z_{\sigma(n-3), \sigma(n-2)}}. \quad (2.9)$$

The dimension, that is, the length of the basis vector $\mathbf{Z}_n^{\text{tree}}$ for a fixed integration domain, is $(n-3)!$, which is precisely the number predicted by twisted cohomology and BCJ relations [37]. The basis dimension follows from results in twisted de Rham theory [38], which have been interpreted in a string-theory context recently [39, 30].

After taking its kinematic poles into account [40, 35, 32], a Z -integral as defined in eq. (2.7) above is calculated by expanding the Koba–Nielsen-factor in α' (cf. eq. (2.1)) and then evaluating each iterated integral separately. In particular, each of the Z -integrals can be expressed in terms of iterated integrals (multiple polylogarithms)²

$$G(a_1, a_2, \dots, a_r; z) = \int_0^z \frac{dz_1}{z_1 - a_1} G(a_2, \dots, a_r; z_1) \quad (2.10)$$

with $a_i \in \{0, 1\}$ as well as $G(; z) = 1$ and $z \in \mathbb{C} \setminus \{0, 1\}$. For tree-level open-string integrals, the outermost integration variable, e.g. one of the insertion points, can always be chosen to equal

²Our conventions for multiple polylogarithms agree with refs. [41, 42].

one by fixing the volume of $\mathrm{SL}_2(\mathbb{R})$ in eq. (2.7). Thus we will have to evaluate integrals of type (2.10) at $z = 1$. Fortunately, all integrals appearing can be related to well-known representations of multiple zeta values (MZVs) using the identity:

$$\zeta_{n_1, n_2, \dots, n_r} = \sum_{0 < k_1 < \dots < k_r} k_1^{-n_1} \dots k_r^{-n_r} = (-1)^r G(\underbrace{0, 0, \dots, 0, 1}_{n_r}, \underbrace{0, 0, \dots, 0, 1}_{n_{r-1}}, \dots, \underbrace{0, 0, \dots, 0, 1}_{n_1}; 1). \quad (2.11)$$

The integrals defined in eq. (2.10) exhibit endpoint divergences if $a_r = 0$ or $a_1 = z$. Therefore, they will have to be regularized, which implies corresponding regularizations for MZVs and may have an echo in the kinematic poles of the Z -integrals defined in eq. (2.7). Throughout this article, we will always assume to work with regularized iterated integrals. For instance, the multiple polylogarithms $G(1, \dots; 1)$ and $G(\dots, 0; 1)$ in (2.10) will be shuffle-regularized based on $G(0; 1) = G(1; 1) = 0$ which assigns regularized values to divergent MZVs (2.11) with $n_r = 1$ such as $\zeta_1 = 0$ [43].

As an example, let us state the first couple of orders of the series expansion of a typical integral Z_n^{tree} :

$$\begin{aligned} Z_5^{\mathrm{tree}}(1, 2, 3, 4, 5 | 2, 1, 4, 3, 5) \\ = \frac{1}{s_{12}s_{34}} + \zeta_2 \left(1 - \frac{s_{45}}{s_{12}} - \frac{s_{15}}{s_{34}} \right) \\ - \zeta_3 \left(\frac{s_{45}(s_{34} + s_{45})}{s_{12}} + \frac{s_{15}(s_{12} + s_{15})}{s_{34}} - 2s_{23} - s_{12} - s_{34} \right) + \mathcal{O}(s_{ij}^2). \end{aligned} \quad (2.12)$$

The analogous expressions for arbitrary orders in the α' -expansion of n -point disk integrals can for instance be generated from the Drinfeld associator [11, 44] or Berends–Giele recursions [14].³ The Berends–Giele method in ref. [14] applies to Z -integrals with arbitrary pairs of permutations $Z_n^{\mathrm{tree}}(a_1, \dots, a_n | b_1, \dots, b_n)$ whose decomposition in the $(n-3)!$ bases expanded in [11, 44] can be generated from the techniques in ref. [51].

2.2 One-loop level: genus one

The calculation of one-loop open-string amplitudes requires consideration of configuration-space integrals on a genus-one surface with boundary. The latter can be constructed by starting from a genus-one Riemann surface (an elliptic curve or torus) whose geometry is usually parametrized by a modular parameter $\tau \in \mathbb{C}$ with $\mathrm{Im} \tau > 0$. The two homology cycles of the torus can be mapped to the boundaries of the fundamental domain of a lattice $\mathbb{Z} + \tau\mathbb{Z}$, where τ is the ratio of the length of B - and A -cycle respectively (see figure 1).

Frequently, the modular parameter is used in an exponentiated version,

$$q = e^{2\pi i \tau}, \quad (2.13)$$

which appears in the Fourier expansions of the $\tau \rightarrow \tau + 1$ periodic functions to be used below.

One-loop open-string amplitudes receive contributions from worldsheets of cylinder and Möbius-strip topology which can be obtained from a torus through involutions described for

³Explicit results at $n \leq 7$ points can be downloaded from ref. [45], and explicit all-multiplicity expressions up to and including α'^7 can be generated from the code available to download from ref. [46]. Earlier work on α' -expansions at $n \leq 7$ points including [47–50, 15] took advantage of connections with hypergeometric functions.

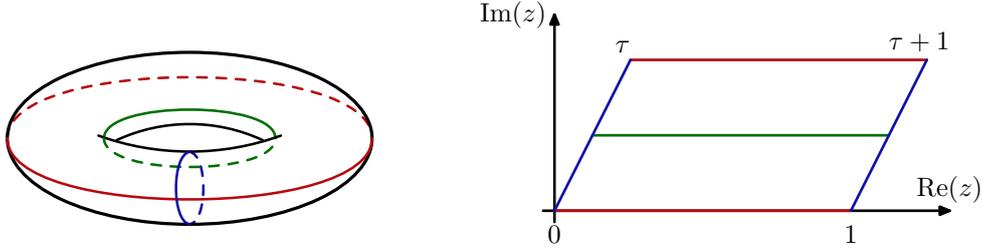


Figure 1: Torus with A - and B -cycle (red and blue) and their images as boundaries of the fundamental domain. The green line marks the additional cut necessary to obtain the cylinder and Möbius-strip worldsheets for the open string as the parallelogram below if $\tau \in i\mathbb{R}$ and $\tau \in i\mathbb{R} + \frac{1}{2}$, respectively.

instance in ref. [52]. The cylinder worldsheet with two boundaries at $\text{Im } z = 0$ and $\text{Im } z = \frac{1}{2} \text{Im } \tau$ then arises from cutting the torus in two parts. When all insertion points z_i are located at one boundary only, the resulting situation is called planar, while insertion points on two boundaries lead to non-planar integrals [53] (see figure 2).

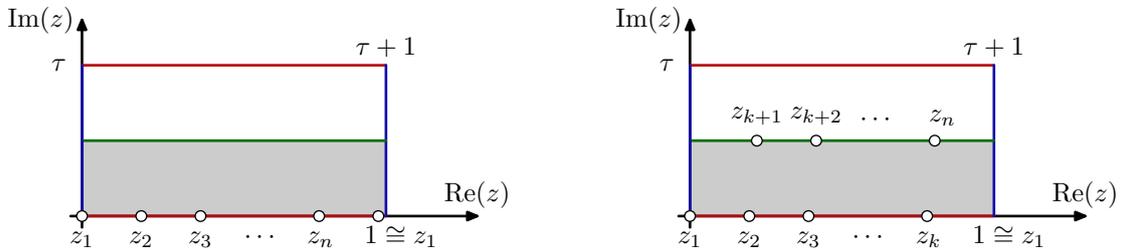


Figure 2: Insertion points for open-string configuration-space integrals on the cylinder can reside either on one boundary only (*planar case*, left panel) or be located at both cylinder boundaries (*non-planar case*, right panel). Following the parametrizations in [53, 52], the cylinder is obtained from a torus with purely imaginary value for τ .

The frameworks of elliptic multiple zeta values (eMZVs) [18] and elliptic polylogarithms [16, 17] allow to systematically perform the integrals over open-string punctures order by order in α' [20]. For this purpose, the genus-one Green's function for planar open-string integrals is written as

$$\mathcal{G}_{ij}^\tau = \Gamma\left(\frac{1}{0}; |z_{ij}| | \tau\right) - \omega(1, 0 | \tau), \quad (2.14)$$

see ref. [21] for their non-planar counterpart⁴. The corresponding Koba–Nielsen factor is given by

$$\text{KN}_{12\dots n}^\tau = \exp\left(-\sum_{1 \leq i < j \leq n} s_{ij} \mathcal{G}_{ij}^\tau\right), \quad (2.15)$$

in direct analogy with (2.6) at genus zero. The elliptic iterated integrals $\Gamma(\dots; z | \tau)$ encoding the

⁴For integration cycles with insertion points on two boundaries, one can as well define a suitable version of eMZVs, which is called twisted eMZVs [21] and described and explored in ref. [54].

z -dependence of the genus-one Green's function (2.14) are generally defined by⁵

$$\Gamma\left(\begin{matrix} k_1 & k_2 & \dots & k_r \\ a_1 & a_2 & \dots & a_r \end{matrix}; z|\tau\right) = \int_0^z dz_1 f^{(k_1)}(z_1 - a_1|\tau) \Gamma\left(\begin{matrix} k_2 & \dots & k_r \\ a_2 & \dots & a_r \end{matrix}; z_1|\tau\right) \quad (2.16)$$

with $\Gamma(; z|\tau) = 1$ and $z \in \mathbb{R}$. In the same way as MZVs can be obtained as special values of iterated integrals on a genus-zero Riemann surface, see (2.11), one can relate Enriquez' A -cycle eMZVs⁶ as special values of the elliptic iterated integrals defined in eq. (2.16):

$$\omega(k_1, k_2, \dots, k_r|\tau) = \Gamma\left(\begin{matrix} k_r & k_{r-1} & \dots & k_1 \\ 0 & 0 & \dots & 0 \end{matrix}; 1|\tau\right). \quad (2.17)$$

The integration kernels $f^{(k)}(z|\tau)$ in (2.16) are generated by a doubly-periodic version of a Kronecker–Eisenstein series [58, 17],

$$\Omega(z, \eta|\tau) = \exp\left(2\pi i \eta \frac{\text{Im } z}{\text{Im } \tau}\right) \frac{\theta'(0|\tau)\theta(z + \eta|\tau)}{\theta(z|\tau)\theta(\eta|\tau)} = \sum_{k=0}^{\infty} \eta^{k-1} f^{(k)}(z|\tau), \quad (2.18)$$

where θ is the odd Jacobi theta function and $\theta'(0|\tau)$ its derivative in the first argument. The double-periodicities of the series and the integration kernels are

$$\Omega(z, \eta|\tau) = \Omega(z+1, \eta|\tau) = \Omega(z+\tau, \eta|\tau), \quad f^{(k)}(z|\tau) = f^{(k)}(z+1|\tau) = f^{(k)}(z+\tau|\tau). \quad (2.19)$$

Given the simple pole of $f^{(1)}(z|\tau) = \partial_z \log \theta(z|\tau) + 2\pi i \frac{\text{Im } z}{\text{Im } \tau}$ at $z \in \mathbb{Z} + \tau\mathbb{Z}$, the integrals in eq. (2.16) and thus eMZVs exhibit endpoint divergences analogous to those in the tree-level scenario. Throughout this work, we will employ shuffle-regularization based on the prescription in section 2.2.1 of [20] which assigns the following q -expansion to the constituents of the Green's function (2.14),

$$\omega(1, 0|\tau) = -\frac{i\pi}{2} + 2 \sum_{k,l=1}^{\infty} \frac{q^{kl}}{k}, \quad (2.20)$$

$$\Gamma\left(\frac{1}{0}; z|\tau\right) = \log(1 - e^{2\pi iz}) - i\pi z + 2 \sum_{k,l=1}^{\infty} \frac{1 - \cos(2\pi kz) q^{kl}}{k}, \quad z \in \mathbb{R}. \quad (2.21)$$

From this q -expansion, the asymptotic behaviour for $0 < z < 1$ can be read off: the limit $z \rightarrow 0$ yields the logarithmic divergence

$$\Gamma\left(\frac{1}{0}; z|\tau\right) = \log(-2\pi iz) + \mathcal{O}(z) \quad (2.22)$$

while for $z \rightarrow 1$

$$\Gamma\left(\frac{1}{0}; z|\tau\right) = \log(-2\pi i(1-z)) + \mathcal{O}(1-z). \quad (2.23)$$

Apart from the constant $f^{(0)}(z|\tau) = 1$ and $f^{(1)}(z|\tau)$ with a simple pole, the Kronecker–Eisenstein series (2.18) generates an infinity of kernels $f^{(k \geq 2)}(z|\tau)$ that do not have any poles in z . Hence,

⁵Because of the non-holomorphic terms $\sim \frac{\text{Im } z}{\text{Im } \tau}$ appearing in $f^{(k)}(z|\tau)$, the iterated integrals (2.16) by themselves are not homotopy-invariant but can be lifted to homotopy-invariant iterated integrals by the methods of [17] (also see section 3.1 of ref. [20]).

⁶Changing the integration path in eq. (2.17) to $(0, \tau)$ in the place of $(0, 1)$ gives rise to B -cycle eMZVs [18] whose properties have for instance been discussed in refs. [55–57].

the genus-one case involves an infinite number of differentials instead of the differential $\frac{dz_i}{z_{ij}}$ referring to finitely many z_j in the genus-zero scenario. Partial fraction, omnipresent for manipulating products of $\frac{1}{z_{ij}}$ in genus-zero integrands, is now replaced by the so-called Fay identity [59]

$$\Omega(z_{ki}, \eta_a | \tau) \Omega(z_{kj}, \eta_b | \tau) = \Omega(z_{ki}, \eta_a + \eta_b | \tau) \Omega(z_{ij}, \eta_b | \tau) + \Omega(z_{kj}, \eta_a + \eta_b | \tau) \Omega(z_{ji}, \eta_a | \tau). \quad (2.24)$$

The three partial derivatives of the Kronecker–Eisenstein series (2.18) are related through the mixed heat equation

$$2\pi i \partial_\tau \Omega(z, \eta | \tau) = \partial_z \partial_\eta \Omega(z, \eta | \tau), \quad z \in \mathbb{R}. \quad (2.25)$$

2.2.1 Z^τ -integrals at genus one

In analogy to the genus-zero integrals Z_n^{tree} defined in eq. (2.7), let us now define a suitable class of integrals at genus one [1],

$$\begin{aligned} Z_n^\tau(1, a_2, \dots, a_n | 1, 2, \dots, n) &= \int_{0=z_1 < z_{a_2} < \dots < z_{a_n} < 1} dz_2 \cdots dz_n \text{KN}_{12\dots n}^\tau \\ &\times \Omega_{12}(\eta_{23\dots n}) \Omega_{23}(\eta_{3\dots n}) \cdots \Omega_{n-1n}(\eta_n), \end{aligned} \quad (2.26)$$

where we will always fix translation invariance by setting $z_1 = 0$. When writing a Kronecker–Eisenstein series where the first argument is of the form z_{ij} , we use the shorthand notation

$$\Omega(z_{ij}, \eta | \tau) = \Omega_{ij}(\eta) \quad (2.27)$$

as well as

$$\eta_{ij\dots k} = \eta_i + \eta_j + \dots + \eta_k \quad (2.28)$$

both of which will prove very handy below. Similar to the genus-zero case, the labels $1, a_2, \dots, a_n$ in the first slot refer to an integration domain. We have adapted (2.26) to planar genus-one integrals (cf. eq. (2)), where $(1, a_2, \dots, a_n)$ specifies a cyclic ordering of insertion points on a single cylinder boundary⁷.

As a genus-one analogue of the so-called Parke–Taylor factor $(z_{12} \cdots z_{n-1,n} z_{n1})^{-1}$ in eq. (2.7), the labels in the second slot of eq. (2.26) indicate products of the form

$$f_{12}^{(k_1)} f_{23}^{(k_2)} \cdots f_{n-1,n}^{(k_{n-1})}, \quad f_{ij}^{(k)} = f^{(k)}(z_{ij} | \tau). \quad (2.29)$$

The absence of a factor $f_{n,1}^{(k_n)}$ to close the cycle is reminiscent of Parke–Taylor factors in an SL_2 -frame with $z_n \rightarrow \infty$, where they reduce to open chains like $(z_{12} z_{23} \cdots z_{n-2,n-1})^{-1}$ as in eq. (2.9). Instead of individual products (2.29), the integrands in (2.26) involve their generating series (2.18) where the combinations $\sum_{j=i}^n \eta_j$ of expansion variables are chosen for later convenience.

As a major advantage of the generating-series approach, the relations between different permutations of (2.26) take a simple form: by analogy with the genus-zero case, a basis of integrands can be found by taking the genus-one analogue of partial fraction⁸ into account, the

⁷The integration domain in the non-planar situation is encoded by one cyclic ordering for both cylinder boundaries which can for instance be addressed by two-line labels $Z_n^\tau(\frac{b_1, b_2, \dots, b_r}{c_1, c_2, \dots, c_s} | 1, 2, \dots, n)$ as in [1].

⁸The genus-one analogue of integration-by-parts relations among Parke–Taylor factors in (2.7) does not relate permutations of the products (2.29) for generic choices of k_i . Instead, integration by parts at genus one will play an important role in later sections to find differential equations for various Koba–Nielsen integrals.

Fay identity (2.24).

While the Fay identities among the products in (2.29) shift the overall weight $k_1 + k_2$ between the two factors,

$$f^{(k_1)}(t-x)f^{(k_2)}(t) = -(-1)^{k_1}f^{(k_1+k_2)}(x) + \sum_{j=0}^{k_2} \binom{k_1-1+j}{j} f^{(k_2-j)}(x)f^{(k_1+j)}(t-x) \\ + \sum_{j=0}^{k_1} \binom{k_2-1+j}{j} (-1)^{k_1+j} f^{(k_1-j)}(x)f^{(k_2+j)}(t), \quad (2.30)$$

their series in (2.26) are simply related via eq. (2.24). After performing a simultaneous expansion of (2.26) in α' and η_j , specific string integrals corresponding to particular integrands in eq. (2.29) can be retrieved by isolating suitable coefficients.

2.2.2 Graphical notation

All configuration-space integrals for string amplitudes appearing in this article exhibit the following features: they have a Koba–Nielsen-factor and a collection of integration kernels, which are labeled by (at least) the difference of two vertex positions: z_{ij} . Furthermore, there are vertex positions z_i , which are integrated over, and others, which remain unintegrated. For the discussion to follow, it is useful to define a graphical representation for the corresponding integrands, extending the graphical notation of ref. [44] to genus one: we are going to represent each occurring label as a vertex and each integration kernel as a directed edge

$$\frac{1}{z_{ij}} = i \bullet \longleftarrow j, \quad \Omega_{ij}(\eta) = i \bullet \xrightarrow{\eta} j, \quad (2.31)$$

respectively.

In this graphical notation, both SL_2 -fixed Parke–Taylor factors (cf. eq. (2.7)) and the integrals Z_n^τ with fixed cyclic symmetry at genus one (cf. eq. (2.26)) exhibit a chain structure. As will be elaborated on below, partial-fraction relations and their one-loop analogue, the Fay relation (2.24), allow to reduce tree-structures to chain-structures. The Fay identity (2.24), for example, takes the following graphical form

$$\begin{array}{c} i \bullet \quad j \bullet \\ \eta_a \searrow \quad \nearrow \eta_b \\ \bullet k \end{array} = \begin{array}{c} i \bullet \quad j \bullet \\ \eta_b \searrow \quad \nearrow \eta_a \\ \bullet k \end{array} + \begin{array}{c} i \bullet \quad j \bullet \\ \eta_a \searrow \quad \nearrow \eta_{ab} \\ \bullet k \end{array} \quad (2.32)$$

which is – not surprisingly – equivalent to the graphical representation of partial fraction (here: $(z_{ki}z_{kj})^{-1} = (z_{ji}z_{kj})^{-1} + (z_{ij}z_{ki})^{-1}$):

$$\begin{array}{c} i \bullet \quad j \bullet \\ \searrow \quad \nearrow \\ \bullet k \end{array} = \begin{array}{c} i \bullet \quad j \bullet \\ \longleftarrow \quad \searrow \\ \bullet k \end{array} + \begin{array}{c} i \bullet \quad j \bullet \\ \longrightarrow \quad \nearrow \\ \bullet k \end{array}. \quad (2.33)$$

The graphical representation of Kronecker–Eisenstein integrands described above will play a major role in the calculations of section 4.

2.2.3 eMZVs versus iterated Eisenstein integrals

For the A -cycle eMZVs (2.17), another representation as iterated integrals of holomorphic Eisenstein series is available which exposes their relations over $\mathbb{Q}[\text{MZV}, (2\pi i)^{-1}]$. While eMZVs have

been defined in eq. (2.17) in terms of special values of iterated integrals, which featured repeated integration in insertion points z_i , it is possible to write them in terms of τ -iterated integrals. This is possible, because τ -derivatives and z -derivatives of their integration kernels are related by the mixed-heat equation (2.25). Further details in converting the integrals into each other including integration constants at $\tau \rightarrow i\infty$ can be found in ref. [19]. Here we would like to limit our attention to writing down the basic definitions and properties of two types of iterated Eisenstein integrals, which will be made use of below [19],

$$\begin{aligned}
& \gamma(k_1, k_2, \dots, k_r | q) \\
&= \frac{1}{4\pi^2} \int_{0 \leq q' \leq q} d\log q' \gamma(k_1, \dots, k_{r-1} | q') G_{k_r}(q') \\
&= \frac{1}{(4\pi^2)^r} \int_{0 \leq q_i < q_{i+1} \leq q} d\log q_1 G_{k_1}(q_1) d\log q_2 G_{k_2}(q_2) \dots d\log q_r G_{k_r}(q_r) \quad (2.34)
\end{aligned}$$

and for $k_1 \neq 0$

$$\begin{aligned}
& \gamma_0(k_1, k_2, \dots, k_r | q) \\
&= \frac{1}{4\pi^2} \int_{0 \leq q' \leq q} d\log q' \gamma_0(k_1, \dots, k_{r-1} | q') G_{k_r}^0(q') \\
&= \frac{1}{(4\pi^2)^r} \int_{0 \leq q_i < q_{i+1} \leq q} d\log q_1 G_{k_1}^0(q_1) d\log q_2 G_{k_2}^0(q_2) \dots d\log q_r G_{k_r}^0(q_r), \quad (2.35)
\end{aligned}$$

where $\gamma(|q) = \gamma_0(|q) = 1$ and the number r of integrations will be referred to as the *length* of either γ and γ_0 . The integration kernels are holomorphic Eisenstein series⁹

$$G_0(\tau) = -1, \quad G_{2k}(\tau) = \sum_{\substack{m, n \in \mathbb{Z} \\ (m, n) \neq (0, 0)}} \frac{1}{(m + n\tau)^k}, \quad G_{2k+1} = 0 \text{ for } k \in \mathbb{N} \quad (2.36)$$

or their modifications G^0 with the constant term $2\zeta_{2k}$ removed for $k \neq 0$,

$$G_0^0(\tau) = -1, \quad G_{2k}^0(\tau) = G_{2k}(\tau) - 2\zeta_{2k}, \quad G_{2k+1}^0 = 0 \text{ for } k \in \mathbb{N}, \quad (2.37)$$

respectively. We will interchangeably refer to the arguments of G_k , G_k^0 and related objects as τ or q .

For both of the iterated Eisenstein integrals defined in eqs. (2.34) and (2.35) as well as for the eMZVs defined in eq. (2.17), shuffle relations (of regularized objects such as $\gamma(0|\tau) = \frac{\tau}{2\pi i}$, obtained by the tangential-base-point prescription [60]) follow from the iterative definitions immediately:

$$\begin{aligned}
& \omega(n_1, n_2, \dots, n_r | \tau) \omega(m_1, m_2, \dots, m_s | \tau) = \omega((n_1, n_2, \dots, n_r) \sqcup (m_1, m_2, \dots, m_s) | \tau), \\
& \gamma(n_1, n_2, \dots, n_r | q) \gamma(k_1, k_2, \dots, k_s | q) = \gamma((n_1, n_2, \dots, n_r) \sqcup (k_1, k_2, \dots, k_s) | q), \\
& \gamma_0(n_1, n_2, \dots, n_r | q) \gamma_0(k_1, k_2, \dots, k_s | q) = \gamma_0((n_1, n_2, \dots, n_r) \sqcup (k_1, k_2, \dots, k_s) | q). \quad (2.38)
\end{aligned}$$

⁹The case of G_2 requires the Eisenstein summation prescription

$$\sum_{m, n \in \mathbb{Z}} a_{m, n} = \lim_{N \rightarrow \infty} \lim_{M \rightarrow \infty} \sum_{n=-N}^N \sum_{m=-M}^M a_{m, n}.$$

Further identities implied by Fay relations as well as the precise relation between the spaces spanned by the respective iterated integrals have been investigated and spelt out in refs. [19, 61, 62].

2.2.4 Two-point example

In order to wrap up this section, let us provide an example of a genus-one Z -integral (2.26) and express the leading orders of its expansion in α' and $\eta = \eta_2$ in two of the languages above:

$$\begin{aligned}
Z_2^\tau(1, 2|1, 2) &= \int_0^1 dz_2 \text{KN}_{12}^\tau \Omega_{12}(\eta) \\
&= \frac{1}{\eta} \left[1 + s_{12}^2 \left(\frac{\omega(0, 0, 2|\tau)}{2} + \frac{5\zeta_2}{12} \right) + s_{12}^3 \left(\frac{\omega(0, 0, 3, 0|\tau)}{18} - \frac{4\zeta_2}{3} \omega(0, 0, 1, 0|\tau) + \frac{\zeta_3}{12} \right) + \mathcal{O}(s_{12}^4) \right] \\
&\quad + \eta \left[-2\zeta_2 + s_{12} \omega(0, 3|\tau) + s_{12}^2 \left(3\zeta_2 \omega(0, 0, 2|\tau) - \frac{\omega(0, 0, 4|\tau)}{2} + \frac{13\zeta_4}{12} \right) + \mathcal{O}(s_{12}^3) \right] \\
&\quad + \eta^3 \left[-2\zeta_4 + s_{12} \left(\omega(0, 5|\tau) - 2\zeta_2 \omega(0, 3|\tau) \right) + \mathcal{O}(s_{12}^2) \right] + \mathcal{O}(\eta^5) \\
&= \frac{1}{\eta} \left[1 + s_{12}^2 \left(\frac{\zeta_2}{4} - 3\gamma_0(4, 0|q) \right) + s_{12}^3 \left(\frac{\zeta_3}{4} + 24\zeta_2 \gamma_0(4, 0, 0|q) - 10\gamma_0(6, 0, 0|q) \right) + \mathcal{O}(s_{12}^4) \right] \\
&\quad + \eta \left[-2\zeta_2 + 3s_{12} \gamma_0(4|q) + s_{12}^2 \left(-\frac{5\zeta_4}{4} - 18\zeta_2 \gamma_0(4, 0|q) + 10\gamma_0(6, 0|q) \right) + \mathcal{O}(s_{12}^3) \right] \\
&\quad + \eta^3 \left[-2\zeta_4 + s_{12} \left(-6\zeta_2 \gamma_0(4|q) + 5\gamma_0(6|q) \right) + \mathcal{O}(s_{12}^2) \right] + \mathcal{O}(\eta^5) \tag{2.39}
\end{aligned}$$

it does contain MZVs as well as eMZVs, which are still a function of the modular parameter τ . This will be crucial for the constructions to be reviewed and discussed below.

3 Differential equations for one-loop open-string integrals

In the last section, Z -integrals for tree-level and one-loop open-string amplitudes have been introduced. Most importantly, these integrals can be expressed in terms of iterated integrals G and Γ over punctures z_i (cf. eqs. (2.10) and (2.16)), which – if evaluated at special points – lead to MZVs and eMZVs, respectively (cf. eqs. (2.11), (2.17) and (2.35)).

For iterated integrals with a particular class of differential forms, it is straightforward to infer differential equations - for example does eq. (2.34) immediately imply

$$2\pi i \partial_\tau \gamma(k_1, k_2, \dots, k_r|q) = -G_{k_r}(q) \gamma(k_1, k_2, \dots, k_{r-1}|q) \tag{3.1}$$

while eq. (2.16) leads to

$$\partial_z \Gamma \left(\begin{matrix} k_1 & k_2 & \dots & k_r \\ a_1 & a_2 & \dots & a_r \end{matrix} ; z|\tau \right) = f^{(k_1)}(z - a_1|\tau) \Gamma \left(\begin{matrix} k_2 & \dots & k_r \\ a_2 & \dots & a_r \end{matrix} ; z|\tau \right). \tag{3.2}$$

Starting from those simple equations, one can consider differential equations for complete Z -integrals. In particular, we will study augmented variants of Z -integrals where an additional unintegrated puncture z_0 serves as a differentiation variable. This will require the evaluation of the action of derivatives on the integrands and in particular on the Koba–Nielsen factor. Suitable manipulations, partial fraction and integration by parts for Z_n^{tree} integrals as well as Fay identities and integration by parts for the one-loop integrals Z_n^τ , allow to frame differential equations as matrix equations, acting on a vector $\mathbf{Z}_{\text{basis}}$ whose elements form a (sometimes

conjectural) basis of Z -type integrals and their augmented versions to be defined below:

$$d\mathbf{Z}_{\text{basis}} = \sum_i \nu_i r(D_i) \mathbf{Z}_{\text{basis}} . \quad (3.3)$$

Here ν_i are suitable differential forms in the alphabet for the iterated integrals that occur in the α' -expansion of the respective Z -integral, whereas $r(D_i)$ denotes a particular square matrix representation of the coefficients of ν_i , tailored to the basis choice. The most crucial point of the game is the following: for all Z -type integrals we are going to consider, the representations $r(D_i)$ turn out to be *linear* in the parameters s_{ij} , and thus in α' , entering the Koba–Nielsen factors in eqs. (2.6) and (2.15). This will allow to solve the differential equation of the above form order by order in α' , leading to the α' -expansion of the Z -integrals. Note that the linear appearance of α' in the above $r(D_i)$ is analogous to the ϵ -form of differential equations for Feynman integrals, see e.g. [63, 64], with α' taking the role of the dimensional-regularization parameter ϵ .

Considering the integrals Z_n^{tree} defined in eq. (2.7), the final result, i.e. the α' -expansion, will contain numbers exclusively. In turn, a differential equation with respect to a variable which disappears during the evaluation of the iterated integral, is not very useful. The solution to this problem has been spelt out in both mathematics [12, 13] and physics [11, 44] literature: one can introduce an additional auxiliary insertion point z_0 and establish a differential equation with respect to z_0 for a basis vector of augmented integrals $\mathbf{Z}_{0,n}^{\text{tree}}$. For the integrals Z_n^τ at genus one, a similar augmentation can be introduced leading to augmented one-loop integrals $\mathbf{Z}_{0,n}^\tau$ whose constituents will be reviewed in subsection 3.3 and whose differential equations in section 4 are a central result of this work. However, since the result in eq. (2.39) does still depend on the modular parameter τ , one can readily use τ as a variable for differentiation when considering a vector \mathbf{Z}_n^τ of one-loop integrals eq. (2.26) without z_0 .

By the choice of differential forms ν_i on the right-hand side of eq. (3.3), the resulting system of differential equations is of Fuchsian type. Even more, on closer inspection one will find the equations to be of Knizhnik–Zamolodchikov(KZ) or Knizhnik–Zamolodchikov–Bernard type for $\mathbf{Z}_{0,n}^{\text{tree}}$ and $\mathbf{Z}_{0,n}^\tau$, respectively, whose solution theory is well known [65, 12, 66, 13, 67–69]. By solving these differential equations along with suitable boundary conditions, one can then evaluate Z -integrals Z_n^{tree} and Z_n^τ at tree-level and one-loop order by order in α' .

Moreover, the matrix representations $r(D_i)$ we will encounter are linear in the Mandelstam variables s_{ij} each of which comes with a parameter α' (cf. eq. (2.1)). Hence, one can obtain solutions to all Z -type integrals in eq. (3.3) in terms of regularized iterated integrals, where the number of integrations is correlated with the power of α' .¹⁰ A major advantage of this concept is that the series expansion in α' follows from simple matrix algebra for the $r(D_i)$. Once the initial value for some limit of the differentiation variable is known, no integral has to be solved and the recursive nature of the solution algorithms allows to infer all higher-multiplicity Z -integrals at tree-level and one-loop from the knowledge of a single trivial tree-level three-point Z -integral.

In the following subsections, we are going to review the main structural points of three languages and corresponding algorithms: the z_0 -language at genus zero in subsection 3.1 and τ - and z_0 -languages at genus one in subsections 3.2 and 3.3. For each one, there is a basis of (augmented) Z -type integrals, a differential equation of type (3.3) with suitable matrix representations and boundary values, which together allow to solve the differential equation recursively.

¹⁰This property is often referred to as *uniform transcendentality* and a common theme of the α' -expansion of configuration-space integrals in string amplitudes, see e.g. refs. [13, 11, 15, 70, 1, 2, 71], and the ϵ -expansion of dimensionally regularized Feynman integrals [72, 73, 63, 64, 74].

3.1 z_0 -language at genus zero

The simplest instance of the algorithm described above is the recursive formalism for the evaluation of tree-level configuration-space integrals Z_n^{tree} . It has been put forward in refs. [11, 44] and is based on refs. [12, 13]. At $n = 4, 5$ points, the augmented versions of tree-level integrals eq. (2.7) with an extra marked point z_0 are given by

$$\mathbf{Z}_{0,4}^{\text{tree}} = \int_0^{z_0} dz_2 |z_2|^{-s_{12}} |1-z_2|^{-s_{23}} |z_{02}|^{-s_{02}} \begin{pmatrix} z_{12}^{-1} \\ z_{32}^{-1} \end{pmatrix}, \quad (z_1, z_3) = (0, 1) \quad (3.4)$$

$$\mathbf{Z}_{0,5}^{\text{tree}} = \int_{0 < z_2 < z_3 < z_0} \left(\prod_{j=2}^3 dz_j |z_j|^{-s_{1j}} |z_{j4}|^{-s_{j4}} |z_{0j}|^{-s_{0j}} \right) |z_{23}|^{-s_{23}} \begin{pmatrix} (z_{12} z_{23})^{-1} \\ (z_{13} z_{32})^{-1} \\ (z_{12} z_{43})^{-1} \\ (z_{13} z_{42})^{-1} \\ (z_{43} z_{32})^{-1} \\ (z_{42} z_{23})^{-1} \end{pmatrix}, \quad (z_1, z_4) = (0, 1),$$

see the references for higher-multiplicity generalizations. One can write down a differential equation with two types of poles:

$$\partial_{z_0} \mathbf{Z}_{0,n}^{\text{tree}} = \left(\frac{r_{0,n}^{\text{tree}}(e_0)}{z_0} + \frac{r_{0,n}^{\text{tree}}(e_1)}{z_0 - 1} \right) \mathbf{Z}_{0,n}^{\text{tree}}. \quad (3.5)$$

The above differential equation is of KZ-type and can be solved by considering regularized boundary values

$$\begin{aligned} \mathbf{C}_{1,n}^{\text{tree}} &= \lim_{z_0 \rightarrow 1} (1-z_0)^{-r_{0,n}^{\text{tree}}(e_1)} \mathbf{Z}_{0,n}^{\text{tree}}, \\ \mathbf{C}_{0,n}^{\text{tree}} &= \lim_{z_0 \rightarrow 0} (z_0)^{-r_{0,n}^{\text{tree}}(e_0)} \mathbf{Z}_{0,n}^{\text{tree}} \end{aligned} \quad (3.6)$$

which are connected by the Drinfeld associator [65, 66]

$$\mathbf{C}_{1,n}^{\text{tree}} = r_{0,n}^{\text{tree}}(\Phi(e_0, e_1)) \mathbf{C}_{0,n}^{\text{tree}}. \quad (3.7)$$

The Drinfeld associator can be expanded in terms of shuffle-regularized MZVs with $\zeta_1 = 0$ [75],

$$\begin{aligned} \Phi(e_0, e_1) &= \sum_{w \geq 0} \sum_{k_1, \dots, k_w \geq 1} e_0^{k_w-1} e_1 \dots e_0^{k_2-1} e_1 e_0^{k_1-1} e_1 \zeta_{k_1, k_2, \dots, k_w} \\ &= 1 - \zeta_2[e_0, e_1] - \zeta_3([e_0, [e_0, e_1]] - [[e_0, e_1], e_1]) + \dots, \end{aligned} \quad (3.8)$$

where¹¹ $r_{0,n}^{\text{tree}}(e_i e_j) = r_{0,n}^{\text{tree}}(e_i) r_{0,n}^{\text{tree}}(e_j)$ and $r_{0,n}^{\text{tree}}(e_i + e_j) = r_{0,n}^{\text{tree}}(e_i) + r_{0,n}^{\text{tree}}(e_j)$. As discussed in ref. [11], the vector $\mathbf{C}_{0,n}^{\text{tree}}$ can be shown to contain the integrals Z_{n-1}^{tree} defined in eq. (2.7) for the $(n-1)$ -point amplitude, while $\mathbf{C}_{1,n}^{\text{tree}}$ contains integrals Z_n^{tree} for the n -point amplitude. In this formalism, the size of the matrix representations $r_{0,n}^{\text{tree}}(e_i)$ is $(n-2)!$.

In order to calculate for example the four-point disk integral, one would use the differential equation

$$\partial_{z_0} \mathbf{Z}_{0,4}^{\text{tree}} = - \left(\frac{\begin{pmatrix} s_{12} + s_{02} & s_{23} \\ 0 & 0 \end{pmatrix}}{z_0} + \frac{\begin{pmatrix} 0 & 0 \\ s_{12} & s_{23} + s_{02} \end{pmatrix}}{z_0 - 1} \right) \mathbf{Z}_{0,4}^{\text{tree}}. \quad (3.9)$$

¹¹Below, we will consider further representations r_n , $r_{0,n}$ and $r_{0,n}^E$ of certain Lie algebra generators. Any such representation r of generators x_i will be assumed to form an algebra homomorphism such that $r(x_i x_j) = r(x_i) r(x_j)$ and $r(x_i + x_j) = r(x_i) + r(x_j)$.

In the kinematic limit $s_{0i} \rightarrow 0$ employed for the recursions of ref. [11], one can read off

$$r_{0,4}^{\text{tree}}(e_0) = - \begin{pmatrix} s_{12} & s_{23} \\ 0 & 0 \end{pmatrix}, \quad r_{0,4}^{\text{tree}}(e_1) = - \begin{pmatrix} 0 & 0 \\ s_{12} & s_{23} \end{pmatrix} \quad (3.10)$$

by matching eq. (3.9) with eq. (3.5), and the regularized boundary values turn out to be

$$\begin{aligned} \mathbf{C}_{1,4}^{\text{tree}} &= \begin{pmatrix} \int_0^1 dz_2 |z_2|^{-s_{12}} |1-z_2|^{-s_{23}} z_{12}^{-1} \\ * \end{pmatrix}, \\ \mathbf{C}_{0,4}^{\text{tree}} &= \begin{pmatrix} s_{12}^{-1} \\ 0 \end{pmatrix}. \end{aligned} \quad (3.11)$$

The first entry of $\mathbf{C}_{1,4}^{\text{tree}}$ may be recognized as the SL_2 -fixed disk integral $-Z_4^{\text{tree}}(1, 2, 3, 4|1, 2, 4, 3)$ via eq. (2.9), and the more subtle computation of the second entry $*$ will not be needed here. The first entry of $\mathbf{C}_{0,4}^{\text{tree}}$ combines the kinematic poles s_{12}^{-1} from the integration region $z_2 \rightarrow 0$ in eq. (3.4) with the three-point integral $Z_3^{\text{tree}}(1, 2, 3|1, 2, 3) = 1$ at its residue. With the leading orders of the Drinfeld associator in eq. (3.8) and the matrix representations in eq. (3.10), one is indeed led to the known four-point α' -expansion at tree level in the first component of the vector $\mathbf{C}_{1,4}^{\text{tree}}$:

$$\begin{aligned} \int_0^1 dz_2 |z_2|^{-s_{12}} |1-z_2|^{-s_{23}} z_{12}^{-1} &= (\mathbf{C}_{1,4}^{\text{tree}})_1|_{s_{0i}=0} \\ &= \frac{1}{s_{12}} [r_{0,n}^{\text{tree}}(\Phi(e^0, e^1))]_{1,1}|_{s_{0i}=0} \\ &= \frac{1}{s_{12}} - \zeta_2 s_{23} - \zeta_3 s_{23}(s_{12} + s_{23}) + \mathcal{O}(s_{ij}^3). \end{aligned} \quad (3.12)$$

Similarly, the $(n-3)!$ bases (2.8) of n -point disk integrals can be retrieved from the first $(n-3)!$ entries of the $(n-2)!$ -component vectors $\mathbf{C}_{1,n}^{\text{tree}}$.

3.2 τ -language at genus one

In this subsection, we are going to review the differential equation of a vector \mathbf{Z}_n^τ of genus-one Z -integrals eq. (2.26) without augmentation through an extra puncture. The basis of these Kronecker–Eisenstein-type integrals w.r.t. Fay relations and integration by parts is $(n-1)!$ dimensional and spanned by [1]

$$\mathbf{Z}_n^\tau = Z_n^\tau(\mathbb{I}_n|1, \rho(2, 3, \dots, n)). \quad (3.13)$$

The permutations $\rho \in S_{n-1}$ of $\{2, 3, \dots, n\}$ act on both the punctures z_j and the expansion variables η_j in the factors of $\Omega_{i-1,i}(\eta_{i\dots n}|\tau)$ in eq. (2.26). The ordering $\mathbb{I}_n = 1, 2, \dots, n$ in the first slot refers to a fixed planar integration domain $0 = z_1 < z_2 < \dots < z_n < 1$ on the A -cycle of the torus (see figure 1). We will usually sort the permutations in lexicographic order, e.g.

$$\mathbf{Z}_2^\tau = Z_2^\tau(1, 2|1, 2), \quad \mathbf{Z}_3^\tau = \begin{pmatrix} Z_3^\tau(\mathbb{I}_3|1, 2, 3) \\ Z_3^\tau(\mathbb{I}_3|1, 3, 2) \end{pmatrix}, \quad \mathbf{Z}_4^\tau = \begin{pmatrix} Z_4^\tau(\mathbb{I}_4|1, 2, 3, 4) \\ Z_4^\tau(\mathbb{I}_4|1, 2, 4, 3) \\ Z_4^\tau(\mathbb{I}_4|1, 3, 2, 4) \\ Z_4^\tau(\mathbb{I}_4|1, 3, 4, 2) \\ Z_4^\tau(\mathbb{I}_4|1, 4, 2, 3) \\ Z_4^\tau(\mathbb{I}_4|1, 4, 3, 2) \end{pmatrix}. \quad (3.14)$$

The $(n-1)!$ -component vector eq. (3.13) was conjectured to generate an integral basis for arbitrary massless one-loop open-string amplitudes [1] as supported by its closure under τ -derivatives to be reviewed below.

3.2.1 Differential equation

Based on the mixed heat equation (2.25) and the differential equation of the Koba–Nielsen factor

$$2\pi i \partial_\tau \text{KN}_{12\dots n}^\tau = - \sum_{1 \leq i < j \leq n} s_{ij} (f_{ij}^{(2)}) + 2\zeta_2 \text{KN}_{12\dots n}^\tau \quad (3.15)$$

one can perform the τ -derivative at the level of the integrand in eq. (2.26), see eq. (2.29) for the shorthand $f_{ij}^{(k)}$. The z_i -derivatives of the $\Omega_{i-1,i}(\eta_{i\dots n})$ generated by the mixed heat equation can be integrated by parts to act on

$$\partial_{z_i} \text{KN}_{12\dots n}^\tau = - \sum_{\substack{j=1 \\ j \neq i}}^n s_{ij} f_{ij}^{(1)} \text{KN}_{12\dots n}^\tau. \quad (3.16)$$

Finally, the combination of $f_{ij}^{(2)}$ and $f_{ij}^{(1)}$ due to the Koba–Nielsen derivatives can be rewritten via

$$(\partial_\eta + \partial_\xi) \Omega_{12}(\eta) \Omega_{21}(\xi) = (\wp(\eta) - \wp(\xi)) \Omega_{12}(\eta - \xi) \quad (3.17)$$

such that the integrand of the τ -derivative only depends on z_i via Kronecker–Eisenstein series. Moreover, repeated use of the Fay identity (2.26) allows to rearrange their first arguments such that the τ -derivatives are expressed in terms of the $(n-1)!$ components in eq. (3.13).

As a result, the vector of genus-one Z -integrals in eq. (3.13) obeys the linear and homogeneous differential equation [1]

$$2\pi i \partial_\tau \mathbf{Z}_n^\tau = D_n^\tau \mathbf{Z}_n^\tau \quad (3.18)$$

with an $(n-1)! \times (n-1)!$ matrix D_n^τ . The entries of the latter are linear in α' by the Mandelstam invariants in the Koba–Nielsen derivatives in eqs. (3.15), (3.16) and may comprise second derivatives in η_j from an expansion of eq. (3.17) around $\xi = 0$. Most importantly, the matrix D_n^τ solely depends on τ via holomorphic Eisenstein series eq. (2.36) and can therefore be uniquely decomposed into

$$D_n^\tau = \sum_{k=0}^{\infty} (1-k) G_k(\tau) r_n(\epsilon_k), \quad (3.19)$$

where $G_0 = -1$ has been introduced for the τ -independent piece. The appearance of the G_k can be traced back to the expansion of the Weierstraß \wp -function in eq. (3.17),

$$\wp(\eta|\tau) = \frac{1}{\eta^2} + \sum_{k=4}^{\infty} (k-1) \eta^{k-2} G_k(\tau). \quad (3.20)$$

The $(n-1)! \times (n-1)!$ matrices $r_n(\epsilon_k)$ are still linear in α' , comprise second derivatives in η_j at $k = 0$ and are conjectured to furnish matrix representations of Tsunogai’s derivation algebra [76]. By the appearance of these derivations in the τ -derivative of the KZB associator [67–69], their commutator relations encode the combinations of iterated Eisenstein integrals eq. (2.34) that occur among eMZVs [19]. The relations in the derivation algebra have been studied in [77, 78, 19] and were checked to be preserved by the $r_n(\epsilon_k)$ in eq. (3.19) for a wide range of n and k . An all-multiplicity proposal for $r_n(\epsilon_k)$ (with a detailed derivation in [79]) can be found in section 4

of [1], and its explicit form is encoded in the later eq. (4.25).

Note that the matrix D_n^τ does not depend on the choice of planar or non-planar integration cycle, i.e. it takes a universal form for any $\mathbb{I}_n \rightarrow a_1, a_2, \dots, a_n$ in eq. (3.13).

3.2.2 Solution via Picard iteration

Given that the matrix D_n^τ in eq. (3.18) is linear in α' , the α' -expansion of the entire \mathbf{Z}_n^τ can be conveniently organized by iterative use of

$$\mathbf{Z}_n^\tau = \mathbf{Z}_n^{i\infty} + \frac{1}{2\pi i} \int_{i\infty}^\tau d\tau' D_n^{\tau'} \mathbf{Z}_n^{\tau'}. \quad (3.21)$$

Picard iteration of eq. (3.21) leads to a perturbative solution to eq. (3.18) with matrix products of order $(\alpha')^\ell$ in the ℓ 'th term of

$$\mathbf{Z}_n^\tau = \sum_{\ell=0}^{\infty} \left(\frac{1}{2\pi i} \right)^\ell \int_{i\infty}^\tau d\tau_1 \int_{i\infty}^{\tau_1} d\tau_2 \dots \int_{i\infty}^{\tau_{\ell-1}} d\tau_\ell D_n^{\tau_\ell} \dots D_n^{\tau_2} D_n^{\tau_1} \mathbf{Z}_n^{i\infty}. \quad (3.22)$$

By the decomposition (3.19) of the $D_n^{\tau_j}$ into holomorphic Eisenstein series, all the integrals in eq. (3.22) line up with the definition of $\gamma(k_1, \dots, k_\ell | q)$ in eq. (2.34). Hence, the entire τ -dependence in the α' -expansion of \mathbf{Z}_n^τ enters via iterated Eisenstein integrals, and their coefficients are governed by matrix products $r_n(\epsilon_{k_1} \epsilon_{k_2}) = r_n(\epsilon_{k_1}) r_n(\epsilon_{k_2})$ [1],

$$\mathbf{Z}_n^\tau = \sum_{\ell=0}^{\infty} \sum_{\substack{k_1, k_2, \dots, k_\ell \\ = 0, 4, 6, 8, \dots}} \left(\prod_{j=1}^{\ell} (k_j - 1) \right) \gamma(k_1, k_2, \dots, k_\ell | q) r_n(\epsilon_{k_\ell} \dots \epsilon_{k_2} \epsilon_{k_1}) \mathbf{Z}_n^{i\infty}. \quad (3.23)$$

The choice of summation range for the k_j already incorporates the vanishing of $r_n(\epsilon_k)$ at odd k and $k = 2$ for any $n \geq 2$. Generating functions of torus integrals in closed-string one-loop amplitudes obey differential equations similar to eq. (3.19) [79] which can be solved via combinations of derivations similar to eq. (3.23) [71].

3.2.3 Initial value at the cusp

In order to extract the complete α' -expansion of \mathbf{Z}_n^τ from eq. (3.23), it remains to analyze the initial values $\mathbf{Z}_n^{i\infty}$ at the cusp. Given that the torus worldsheet degenerates to a nodal Riemann sphere as $\tau \rightarrow i\infty$, the initial data at n points is expressible in terms of genus-zero integrals with two extra points, i.e. combinations of $(n+2)$ -point disk integrals eq. (2.7) in the open-string case. At $n = 2$ points, for instance, the genus-one Z -integral (2.39) degenerates to

$$Z_2^{i\infty}(1, 2 | 1, 2) = \pi \cot(\pi\eta) \frac{\Gamma(1-s_{12})}{[\Gamma(1-\frac{s_{12}}{2})]^2}, \quad (3.24)$$

where the Γ -functions stem from a kinematic limit $s_{23} \rightarrow -\frac{s_{12}}{2}$ of the Veneziano amplitude

$$Z_4^{\text{tree}}(1, 2, 3, 4 | 1, 2, 4, 3) = -\frac{1}{s_{12}} \frac{\Gamma(1-s_{12})\Gamma(1-s_{23})}{\Gamma(1-s_{12}-s_{23})} \quad (3.25)$$

and yield the following α' -expansion

$$\frac{\Gamma(1-s_{12})}{[\Gamma(1-\frac{s_{12}}{2})]^2} = 1 + \frac{1}{4} s_{12}^2 \zeta_2 + \frac{1}{4} s_{12}^3 \zeta_3 + \frac{19}{160} s_{12}^4 \zeta_2^2 + \frac{1}{16} s_{12}^5 \zeta_2 \zeta_3 + \frac{3}{16} s_{12}^5 \zeta_5 + \mathcal{O}(s_{12}^6). \quad (3.26)$$

The η -dependent factor $\pi \cot(\pi\eta)$ in eq. (3.24) stems from the $\tau \rightarrow i\infty$ limit of $\Omega_{12}(\eta)$. The detailed relation between eqs. (3.24) and (3.25) involving a trigonometric factor $\sin(\frac{\pi}{2}s_{12})$ from contour deformations can be found in section 3.4 of [1], also see section 5 of the reference for an all-multiplicity discussion.

3.2.4 Two-point example

In the two-point instance of the above setup, the target vector has a single component $Z_2^\tau(1, 2|1, 2)$ and the operator D_2^τ in the differential equation (3.18) is the following scalar instead of a matrix

$$2\pi i \partial_\tau Z_2^\tau(1, 2|1, 2) = D_2^\tau Z_2^\tau(1, 2|1, 2), \quad D_2^\tau = s_{12} \left(\frac{1}{2} \partial_\eta^2 - \wp(\eta, \tau) - 2\zeta_2 \right). \quad (3.27)$$

The decomposition (3.19) into holomorphic Eisenstein series allows to read off conjectural scalar representations of the derivation algebra

$$r_2(\epsilon_0) = s_{12} \left(\frac{1}{\eta^2} + 2\zeta_2 - \frac{1}{2} \partial_\eta^2 \right), \quad r_2(\epsilon_k) = s_{12} \eta^{k-2}, \quad k \geq 4 \text{ even}, \quad (3.28)$$

which obey multiplicity-specific relations such as $[r_2(\epsilon_4), r_2(\epsilon_6)] = 0$ that no longer hold at $n \geq 3$ points. With the initial value (3.24) involving a four-point disk integral, the two-point instance of the Picard iteration (3.23) is given by

$$Z_2^\tau(1, 2|1, 2) = \frac{\Gamma(1-s_{12})}{[\Gamma(1-\frac{s_{12}}{2})]^2} \sum_{\ell=0}^{\infty} \sum_{\substack{k_1, k_2, \dots, k_\ell \\ =0, 4, 6, 8, \dots}} \left(\prod_{j=1}^{\ell} (k_j - 1) \right) \gamma(k_1, k_2, \dots, k_\ell | q) r_2(\epsilon_{k_\ell} \dots \epsilon_{k_2} \epsilon_{k_1}) \pi \cot(\pi\eta). \quad (3.29)$$

Based on the expansions (3.26) and $\pi \cot(\pi\eta) = \frac{1}{\eta} - 2 \sum_{k=1}^{\infty} \zeta_{2k} \eta^{2k-1}$, one arrives at the leading orders in α' and η spelt out in eq. (2.39).

3.3 z_0 -language at genus one

In this subsection, we are going to sketch the formalism introduced in ref. [2]. The formalism is the genus-one generalization of the tree-level recursion discussed in subsection 3.1: it utilizes an auxiliary point z_0 such that

$$0 = z_1 < z_2 < \dots < z_n < z_0 < 1. \quad (3.30)$$

In the reference, the differential equation and thus the recursion was formulated for an infinitely long vector of genus-one n -point Selberg integrals, which are defined in terms of a Selberg seed

$$S_n^E(\tau) = S_n^E \left[\right] (z_2, z_3, \dots, z_n, z_0, \tau) = \prod_{0 \leq i < j \leq n} \exp(-s_{ij} \Gamma_{ij}), \quad \Gamma_{ij} = \Gamma\left(\frac{1}{2}; |z_{ij}| | \tau\right) \quad (3.31)$$

with $z_1 = 0$ which agrees with an $(n+1)$ -point Koba–Nielsen factor (2.15) upon multiplication by $e^{s_{012} \dots s_{0n} \omega(1, 0 | \tau)}$. The Selberg seed (3.31) serves as starting point for the recursive definition¹²

$$S_n^E \left[\begin{matrix} k_\ell, \dots, k_2 \\ i_\ell, \dots, i_2 \end{matrix} \right] (z_{\ell+1}, \dots, z_n, z_0) = \int_0^{z_{\ell+1}} dz_\ell f_{\ell, i_\ell}^{(k_\ell)} S_n^E \left[\begin{matrix} k_{\ell-1}, \dots, k_2 \\ i_{\ell-1}, \dots, i_2 \end{matrix} \right] (z_\ell, z_{\ell+1}, \dots, z_n, z_0) \quad (3.32)$$

¹²On the locus of the purely real integration paths considered here and in ref. [2], the integration kernels $g^{(k)}$ in the reference equal $f^{(k)}$ here. Furthermore, in the reference the auxiliary point is called z_2 and the insertion points are labeled differently, close to the notation and the notion of *admissible* integrals in ref. [38].

with $\ell = 2, 3, \dots, n$ as well as $z_{n+1} = z_0$ and

$$i_\ell \in \{0, 1, \ell+1, \ell+2, \dots, n\}, \quad (3.33)$$

where the shorthand notation for the integration kernels $f_{ij}^{(k)}$ was defined in eq. (2.29).

3.3.1 Differential equation and boundary values

The differential equation of the (infinitely long) vector of Selberg integrals

$$\mathbf{S}_n^{\text{E}}(z_0|\tau) = \left(\mathbf{S}_n^{\text{E}} \left[\begin{matrix} k_n, \dots, k_2 \\ i_n, \dots, i_2 \end{matrix} \right] (z_0) \right) \text{ for } k_\ell \geq 0, i_\ell \in \{0, 1, \ell+1, \ell+2, \dots, n\} \quad (3.34)$$

can formally be brought into the KZB form

$$\partial_{z_0} \mathbf{S}_n^{\text{E}}(z_0|\tau) = \sum_{k=0}^{\infty} f_{01}^{(k)} r_{0,n}^{\text{E}}(x_k) \mathbf{S}_n^{\text{E}}(z_0|\tau), \quad (3.35)$$

where the representations $r_{0,n}^{\text{E}}$ of x_k are block-(off-)diagonal and proportional to α' . Similar to the tree-level scenario described in subsection 3.1, one now considers the two regularized boundary values

$$\begin{aligned} \mathbf{C}_{1,n}^{\text{E}}(\tau) &= \lim_{z_0 \rightarrow 1} (-2\pi i(1-z_0))^{-r_{0,n}^{\text{E}}(x_1)} \mathbf{S}_n^{\text{E}}(z_0|\tau), \\ \mathbf{C}_{0,n}^{\text{E}}(\tau) &= \lim_{z_0 \rightarrow 0} (-2\pi i z_0)^{-r_{0,n}^{\text{E}}(x_1)} \mathbf{S}_n^{\text{E}}(z_0|\tau) \end{aligned} \quad (3.36)$$

which turn out to contain n -point one-loop integrals Z_n^τ in $\mathbf{C}_{1,n}^{\text{E}}$ and $(n+2)$ -point tree-level integrals Z_{n+2}^{tree} in $\mathbf{C}_{0,n}^{\text{E}}$. As shown in the next subsection, these two boundary values can be related to each other, such that knowing $\mathbf{C}_{0,n}^{\text{E}}$ from the tree-level recursion described above, allows to infer the α' -expansion of all one-loop Selberg integrals and thus – as will be elaborated on below – all integrals Z_n^τ .

3.3.2 The elliptic KZB associator

As argued in sec. 3.3 of [2] for a general solution of the elliptic KZB equation of the form (3.35), the regularized boundary values $\mathbf{C}_{0,n}^{\text{E}}$ and $\mathbf{C}_{1,n}^{\text{E}}$ are related according to

$$\mathbf{C}_{1,n}^{\text{E}} = r_{0,n}^{\text{E}}(\Phi^\tau) \mathbf{C}_{0,n}^{\text{E}} \quad (3.37)$$

by the elliptic KZB associator [80]

$$\begin{aligned} \Phi^\tau &= \sum_{w \geq 0} \sum_{k_1, k_2, \dots, k_w \geq 0} x_{k_1} x_{k_2} \dots x_{k_w} \omega(k_w, \dots, k_2, k_1|\tau) \\ &= 1 + x_0 - 2\zeta_2 x_2 + \frac{1}{2} x_0 x_0 - [x_0, x_1] \omega(0, 1|\tau) - \zeta_2 \{x_0, x_2\} \\ &\quad + [x_1, x_2] (\omega(0, 3|\tau) - 2\zeta_2 \omega(0, 1|\tau)) - [x_0, x_3] \omega(0, 3|\tau) \\ &\quad + \zeta_4 (-\{x_0, x_4\} + 5x_2 x_2 - 2x_4) + \dots \end{aligned} \quad (3.38)$$

Since the matrices $r_{0,n}^{\text{E}}(x_k)$ are proportional to α' , the associator eq. (3.37) yields the α' -expansion of $\mathbf{C}_{1,n}^{\text{E}}$. Furthermore, by the lower triangular block structure of the matrices $r_{0,n}^{\text{E}}(x_k)$ with $k \geq 2$, only finitely many terms of $r_{0,n}^{\text{E}}(\Phi^\tau)$ contribute to each order of α' .

Instead of reviewing the formalism in detail here, we will rephrase and discuss it in the next section: therein we are going to replace the infinite-dimensional vector $\mathbf{S}^E(z_0)$ by a finite-dimensional vector $\mathbf{Z}_{0,n}^\tau$ of integrals $Z_{0,n}^\tau$ that serve as a generating series of Selberg integrals (see appendix D for details). These vectors $\mathbf{Z}_{0,n}^\tau$ augment the vectors \mathbf{Z}_n^τ of section 3.2 by an auxiliary point z_0 . The detailed discussion of the differential equation and boundary values will be performed for vectors $\mathbf{Z}_{0,n}^\tau$. While being already closer to the formalism to be spelt out in subsection 4.2 below, rewriting in terms of the generating series $Z_{0,n}^\tau$ renders the representation of the matrices x_k finite-dimensional.

3.3.3 Two-point example

The two-point example elaborated in [2] can be summarized as follows: the genus-one Selberg integrals (3.32) for $n = 2$ are

$$S_2^E \left[\begin{matrix} k_2 \\ i_2 \end{matrix} \right] (z_0) = \int_0^{z_0} dz_2 S_2^E f_{2,i_2}^{(k_2)}, \quad S_2^E = \exp(-s_{12}\Gamma_{12} - s_{01}\Gamma_{01} - s_{02}\Gamma_{02}), \quad (3.39)$$

where $k_2 \geq 0$ and $i_2 \in \{0, 1\}$. Note that not all of these integrals are independent: due to the triviality of $f^{(0)} = 1$ for $k_2 = 0$ and integration by parts for $k_2 = 1$, there are the relations

$$S_2^E \left[\begin{matrix} 0 \\ 0 \end{matrix} \right] (z_0) = S_2^E \left[\begin{matrix} 0 \\ 1 \end{matrix} \right] (z_0), \quad S_2^E \left[\begin{matrix} 1 \\ 0 \end{matrix} \right] (z_0) = -\frac{s_{12}}{s_{02}} S_2^E \left[\begin{matrix} 1 \\ 1 \end{matrix} \right] (z_0). \quad (3.40)$$

The corresponding vector of independent integrals

$$\mathbf{S}_2^E(z_0) = \begin{pmatrix} S_2^E \left[\begin{matrix} 0 \\ 1 \end{matrix} \right] (z_0) \\ S_2^E \left[\begin{matrix} 1 \\ 1 \end{matrix} \right] (z_0) \\ S_2^E \left[\begin{matrix} 2 \\ 1 \end{matrix} \right] (z_0) \\ S_2^E \left[\begin{matrix} 2 \\ 0 \end{matrix} \right] (z_0) \\ \vdots \end{pmatrix} \quad (3.41)$$

satisfies the differential equation (3.35) with the block-off-diagonal matrices

$$r_{0,2}^E(x_0) = \begin{pmatrix} 0 & -s_{12} & 0 & 0 & \dots \\ 0 & 0 & s_{02} & s_{02} & \dots \\ 0 & 0 & 0 & 0 & \dots \\ 0 & 0 & 0 & 0 & \dots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}, \quad r_{0,2}^E(x_2) = \begin{pmatrix} 0 & 0 & 0 & 0 & \dots \\ s_{02} & 0 & 0 & 0 & \dots \\ 0 & -s_{12} & 0 & 0 & \dots \\ 0 & -s_{12} & 0 & 0 & \dots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}, \quad \dots \quad (3.42)$$

and the block-diagonal one

$$r_{0,2}^E(x_1) = \begin{pmatrix} -s_{01} & 0 & 0 & 0 & \dots \\ 0 & -s_{012} & 0 & 0 & \dots \\ 0 & 0 & -s_{01} - s_{02} & s_{02} & \dots \\ 0 & 0 & s_{12} & -s_{01} - s_{12} & \dots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}. \quad (3.43)$$

On the one hand, the only non-vanishing entry of the boundary value $\mathbf{C}_{0,2}^E$ is proportional to the tree-level Veneziano amplitude (3.25)

$$\mathbf{C}_{0,2}^E = \begin{pmatrix} 0 \\ -\frac{1}{s_{12}} \frac{\Gamma(1-s_{12})\Gamma(1-s_{02})}{\Gamma(1-s_{12}-s_{02})} \\ 0 \\ \vdots \end{pmatrix} \quad (3.44)$$

with the two independent four-point, tree-level Mandelstam variables s_{12} and s_{02} associated to the punctures $0, z_2, 1$ and the well-known gamma function Γ . On the other hand, the first entry of $\mathbf{C}_{1,2}^E$ is proportional to the simplest two-point, one-loop configuration-space integral with Mandelstam variable $\tilde{s}_{12} = s_{12} + s_{02}$

$$\mathbf{C}_{1,2}^E = \begin{pmatrix} \int_0^1 dz_2 \exp(-\tilde{s}_{12}\Gamma_{21}) \\ \vdots \end{pmatrix} \quad (3.45)$$

that occurs at the η^{-1} -order of eq. (2.39). Therefore, due to the block-off-diagonality of $r_{0,2}^E(x_k)$ for $k \geq 2$, the three 4×4 submatrices shown in eqs. (3.42) and (3.43) of $r_{0,2}^E(x_0)$, $r_{0,2}^E(x_1)$ and $r_{0,2}^E(x_2)$ are sufficient to calculate the first entry $\int_0^1 dz_2 \exp(-\tilde{s}_{12}\Gamma_{21})$ of $\mathbf{C}_{1,2}^E$ up to the second order in α' using the associator equation (3.37), which results in the expansion

$$\begin{aligned} \int_0^1 dz_2 \exp(-\tilde{s}_{12}\Gamma_{21}) &= -\frac{1}{s_{12}} \frac{\Gamma(1-s_{12})\Gamma(1-s_{02})}{\Gamma(1-s_{12}-s_{02})} [r_{0,2}^E(\Phi^\tau)]_{1,2} \\ &= 1 - (s_{12}+s_{02})\omega(1, 0|\tau) + (s_{12}+s_{02})^2\omega(1, 1, 0|\tau) + \mathcal{O}(s_{ij}^3). \end{aligned} \quad (3.46)$$

Upon multiplication by $e^{(s_{12}+s_{02})\omega(1,0|\tau)}$, this agrees with the leading orders of eq. (2.39) since $\omega(1, 1, 0|\tau) - \frac{1}{2}\omega(1, 0|\tau)^2 = \frac{1}{2}\omega(0, 0, 2|\tau) + \frac{5\zeta_2}{12}$ [19]. The two-point associator only contributes through its entry $[r_{0,2}^E(\Phi^\tau)]_{1,2}$ because the only non-zero entry of $\mathbf{C}_{0,2}^E$ occurs in the second line of eq. (3.44) and the desired one-loop integral occurs in the first line of $\mathbf{C}_{1,2}^E$ in eq. (3.45).

4 Differential equations for the integrals $Z_{0,n}^\tau$

In order to link the two formalisms described in subsections 3.2 and 3.3 above, we will now introduce genus-one integrals $Z_{0,n}^\tau$ augmented by an auxiliary insertion position z_0 . In particular, we will evaluate their derivatives with respect to both z_0 and the modular parameter τ in closed form. While the integrals $Z_{0,n}^\tau$ contain all genus-one Selberg integrals¹³ from subsection 3.3 in their expansion with respect to the variables η_j , they differ from the integrals Z_n^τ used in subsection 3.2 only by the inclusion of an auxiliary point z_0 : they are ideal to bridge the gap between the different languages, in particular between the KZB-type differential equations in z_0 and τ .

4.1 Integrals with auxiliary point

In order to augment the space spanned by the integrals Z_n^τ defined in eq. (2.26), we introduce an auxiliary point z_0 , which is, however, not integrated over. Thus, we will consider integrals

¹³Strictly speaking, the $Z_{0,n}^\tau$ in this section and the Z_n^τ in eq. (2.26) are genus-one Selberg integrals as well since their definition is not tied to the admissibility condition [38]. Still, we will only refer to the integrals \mathbf{S}_n^E in section 3.3 subject to the admissibility condition as Selberg integrals.

associated to the configuration space of the twice-punctured torus, with punctures $z_1 = 0$ and z_0 . In order to compactly write down a conjectural¹⁴ basis $Z_{0,n}^\tau$ of such integrals, let us define a *chain* of Kronecker–Eisenstein series by

$$\varphi^\tau(1, 2, \dots, p) = \Omega_{12}(\eta_{23\dots p})\Omega_{23}(\eta_{3\dots p}) \dots \Omega_{p-1,p}(\eta_p), \quad (4.1)$$

$$\varphi^\tau(a_1) = 1, \quad (4.2)$$

and $\varphi^\tau(a_1, a_2, \dots, a_p)$ is obtained from simultaneous permutations of $z_i \rightarrow z_{a_i}$ and $\eta_i \rightarrow \eta_{a_i}$. The individual factors of Kronecker–Eisenstein series in such a chain $\varphi^\tau(a_1, a_2, \dots, a_p)$ accumulate their η -variables from right to left and, thus, is said to begin at a_p and end at a_1 . Chains of Kronecker–Eisenstein series will turn out to be a very versatile tool in the description of integrals $Z_{0,n}^\tau$, and already the Z^τ -integrals (2.26) without augmentation feature $\varphi^\tau(1, 2, \dots, n)$ in the integrand.

Using the notation in eq. (4.1), the vector of the $n!$ basis integrals is given by

$$\mathbf{Z}_{0,n}^\tau = \int_{\gamma_{12\dots n0}} dz_2 dz_3 \dots dz_n \text{KN}_{0123\dots n}^\tau \times \begin{pmatrix} \rho[\varphi^\tau(1, 2, \dots, n)] \\ \rho[\varphi^\tau(1, 2, \dots, n-1)\varphi^\tau(0, n)] \\ \rho[\varphi^\tau(1, 2, \dots, n-2)\varphi^\tau(0, n, n-1)] \\ \vdots \\ \rho[\varphi^\tau(1, 2)\varphi^\tau(0, n, n-1, \dots, 3)] \\ \rho[\varphi^\tau(0, n, n-1, \dots, 2)] \end{pmatrix}, \quad (4.3)$$

where we keep on setting $z_1 = 0$, and the permutations $\rho \in \mathcal{P}(2, 3, \dots, n)$ acting on the integrand are again lexicographically ordered. The original Koba–Nielsen-factor eq. (2.15) is extended by additional variables s_{0j} with $j = 1, 2, \dots, n$ as in eq. (3.31),

$$\text{KN}_{012\dots n}^\tau = \exp\left(-\sum_{0 \leq i < j \leq n} s_{ij} \mathcal{G}_{ij}^\tau\right), \quad (4.4)$$

and we use the following shorthand notation for the integration domain,

$$\gamma_{12\dots n0} = \{z_2, z_3, \dots, z_n \in \mathbb{R} \mid 0 = z_1 < z_2 < z_3 < \dots < z_n < z_0\}. \quad (4.5)$$

The basis integrals in the components can be denoted by

$$Z_{0,n}^\tau((1, A), (0, B)) = \int_{\gamma_{12\dots n0}} dz_2 dz_3 \dots dz_n \text{KN}_{0123\dots n}^\tau \varphi^\tau(1, A) \varphi^\tau(0, B), \quad (4.6)$$

where $A = (a_1, a_2, \dots, a_p)$ and $B = (b_1, b_2, \dots, b_q)$ are disjoint sequences without repetitions such that $A \cup B = \{2, 3, \dots, n\}$. For simplicity, we denote $Z_{0,n}^\tau((1, A), (0)) = Z_{0,n}^\tau(1, A)$ for an empty sequence B and similarly $Z_{0,n}^\tau((1), (0, B)) = Z_{0,n}^\tau(0, B)$ for $A = \emptyset$. This notation directly exhibits the chain structure of the products of Kronecker–Eisenstein series: the dictionary of section 2.2.2 assigns two rooted chains – trees without branching points and root vertices 0 and

¹⁴Also in presence of the augmentation by z_0 , Koba–Nielsen-type integrals over cycles of $f_{ij}^{(k)}$ -functions such as $f_{12}^{(k_1)} f_{23}^{(k_2)} f_{31}^{(k_3)}$ are expected to be expressible in terms of chain integrands as in eq. (2.29) and the η_j -expansion of eq. (4.3). Since we do not present a proof of this claim here, the $\mathbf{Z}_{0,n}^\tau$ below are a *conjectural* basis of augmented Koba–Nielsen integrals (with supporting evidence from their closure under z_0 - and τ -derivatives). We will not repeat the word „conjectural” when referring to the $\mathbf{Z}_{0,n}^\tau$ as a basis later on.

1 – to the integrals (4.6) with non-empty A, B .

Similar to the Z^τ -integrals (3.13) without augmentation, we are studying the fixed planar integration domain (4.5) for any choice of A, B throughout this section. Accordingly, the two elements $(1, A), (0, B)$ of notation in eq. (4.6) both refer to the integrand, and we suppress a separate slot $Z_{0,n}^\tau(\cdot|(1, A), (0, B))$ specifying the integration domain to avoid cluttering. Nevertheless, the differential equations to be derived below are universal to all integration domains $0 = z_1 < z_{\sigma(2)} < \dots < z_{\sigma(n)} < z_0 < 1$ with any permutation $\sigma \in \mathcal{P}(2, 3, \dots, n)$.

Not surprisingly, the augmented integrals (4.3) can also be obtained from the $(n+1)$ -point basis \mathbf{Z}_{n+1}^τ in eq. (3.13) by the following formal operations: dropping the integration over the last puncture, identifying $z_{n+1} \rightarrow z_0$ according to the integration domain \mathbb{I}_{n+1} and peeling off a factor of $\Omega_{1,0}$. The latter can be enforced to appear in each component of $\mathbf{Z}_{n+1}^\tau|_{z_{n+1} \rightarrow z_0}^{\eta_{n+1} \rightarrow \eta_0}$ by expanding the permutations $\rho[\varphi^\tau(1, 2, \dots, n, 0)]$ in the integrand in a basis of $\varphi^\tau(\dots, 0, 1, \dots)$ via Fay relations.¹⁵ These operations resemble the construction of fibration bases for configuration-space integrals at genus zero [30].

4.1.1 Further integrals from Fay identities

The main ingredients to the integrals in the basis (4.6) are chains, which can conveniently be associated with a chain graph using the dictionary from section 2.2.2, for example¹⁶ of the form

$$\varphi^\tau(1, 2, 3, 4) = \Omega_{12}(\eta_{234})\Omega_{23}(\eta_{34})\Omega_{34}(\eta_4) = \begin{array}{c} \bullet 4 \\ \downarrow \eta_4 \\ \bullet 3 \\ \downarrow \eta_{34} \\ \bullet 2 \\ \downarrow \eta_{234} \\ \bullet 1 \end{array} . \quad (4.7)$$

Multiplying chains corresponds to combining chain graphs. Whenever the same label appears in two different chains, the Fay identity (2.24) can be used to link the chains and produce tree graphs. In fact, repeated use of Fay identities implies various identities shown and proven in appendix A satisfied by products of chains φ^τ . Such identities among chains are not only useful for the translation to basis integrals, but also for expressing differential equations satisfied by these basis integrals in closed form in subsections 4.2 and 4.3 below. For each disconnected pair of tree graphs, the associated product of Kronecker–Eisenstein series can be represented as linear combination of the integrals in eq. (4.6), resulting in integrals of the form

$$\int_{\gamma_{12\dots n0}} dz_2 \cdots dz_n \text{KN}_{012\dots n}^\tau \Omega_{i_2 2}(\xi_2)\Omega_{i_3 3}(\xi_3) \cdots \Omega_{i_n n}(\xi_n) . \quad (4.8)$$

Since the indices $i_k \in \{0, \dots, n\}$, $i_k \neq k$ of the $\Omega_{i_k k}(\xi_k)$ in the integrand are related to the basis (4.3) via Fay identities with graphical form eq. (2.32), the associated edges between vertices i_k and k form tree graphs. The counting of vertices and edges only admits one or two connected components, and the vertices $0, 1$ cannot be in the same connected component. Moreover, each vertex $k \neq 0, 1$ has only one outgoing edge, while the vertices $k = 0, 1$ have none.

¹⁵The augmented integrals $\mathbf{Z}_{0,2}^\tau$ at two points are for instance obtained by starting from the integrands $\Omega_{12}(\eta_{20})\Omega_{20}(\eta_0)$ and $\Omega_{10}(\eta_{20})\Omega_{02}(\eta_2)$ of $\mathbf{Z}_3^\tau|_{z_3 \rightarrow z_0}^{\eta_3 \rightarrow \eta_0}$ and rewriting the former as $\Omega_{10}(\eta_0)\Omega_{12}(\eta_2) - \Omega_{10}(\eta_{20})\Omega_{02}(\eta_2)$. After peeling off the factors of $\Omega_{10}(\eta_0)$ and $\Omega_{10}(\eta_{20})$, one is left with the integrands $\Omega_{12}(\eta_2)$ and $\Omega_2(\eta_2)$ in the first and second component of eq. (4.3) at $n = 2$, respectively.

¹⁶For notational simplicity, in graphs we use the convention $\eta_{a_2 a_3 \dots a_p} = \eta_{a_2 3 \dots p}$ and similarly for other sums of η -variables associated to sequences of the form (a_2, a_3, \dots, a_p) .

The precise form of the variables ξ_k in eq. (4.8) can be deduced from the graph: for the edge pointing away from the vertex k , the associated ξ_k is a combination of $\eta_2, \eta_3, \dots, \eta_n$ obtained by accumulating (adding) all η_j -labels from edges higher in the tree pointing towards the vertex k . In other words, ξ_k for a given edge is the sum of all the η_j of those vertices j which become disconnected from 0 or 1 through deletion of the edge under consideration.

As detailed in appendix D the integrals eq. (4.8) with suitable restrictions on the i_k generate the Selberg integrals eq. (3.32) upon expansion in the ξ_k . From this observation as well as the aforementioned formal relation between the $n!$ bases $\mathbf{Z}_{0,n}^\tau$ and \mathbf{Z}_{n+1}^τ , one can already anticipate the potential of the augmented Z^τ -integrals eq. (4.3) to relate the two approaches of refs. [1, 2] to genus-one α' -expansions.

4.1.2 Five-point example

A typical example for (4.8) at $n = 5$ is the integral

$$\int_{\gamma_{123450}} dz_2 \cdots dz_5 \text{KN}_{01\dots 5}^\tau \Omega_{12}(\eta_{234}) \Omega_{23}(\eta_3) \Omega_{24}(\eta_4) \Omega_{05}(\eta_5), \quad (4.9)$$

which is represented by the following diagram:

$$\Omega_{12}(\eta_{234}) \Omega_{23}(\eta_3) \Omega_{24}(\eta_4) \Omega_{05}(\eta_5) = \begin{array}{c} \bullet 3 \quad \bullet 4 \\ \eta_3 \quad \eta_4 \\ \searrow \quad \swarrow \\ \bullet 2 \\ \eta_{234} \\ \downarrow \\ \bullet 1 \end{array} \quad \begin{array}{c} \bullet 5 \\ \eta_5 \\ \downarrow \\ \bullet 0 \end{array}, \quad (4.10)$$

where the η -variables with multiple indices have been defined in eq. (2.28). In parallel to the Fay identities for genus-one Z -integrals, one can apply Fay identities to rewrite eq. (4.9) as

$$\begin{aligned} & \int_{\gamma_{123450}} dz_2 \cdots dz_5 \text{KN}_{01\dots 5}^\tau \Omega_{12}(\eta_{234}) \Omega_{23}(\eta_3) \Omega_{24}(\eta_4) \Omega_{05}(\eta_5) \\ &= \int_{\gamma_{123450}} dz_2 \cdots dz_5 \text{KN}_{01\dots 5}^\tau \Omega_{12}(\eta_{234}) \Omega_{23}(\eta_{34}) \Omega_{34}(\eta_4) \Omega_{05}(\eta_5) \\ & \quad + \int_{\gamma_{123450}} dz_2 \cdots dz_5 \text{KN}_{01\dots 5}^\tau \Omega_{12}(\eta_{234}) \Omega_{24}(\eta_{34}) \Omega_{43}(\eta_3) \Omega_{05}(\eta_5) \\ &= Z_{0,5}^\tau((1, 2, 3, 4), (0, 5)) + Z_{0,5}^\tau((1, 2, 4, 3), (0, 5)), \end{aligned} \quad (4.11)$$

which is based on the following application of the graphical Fay identity (2.32):

$$\begin{array}{c} \bullet 3 \quad \bullet 4 \\ \eta_3 \quad \eta_4 \\ \searrow \quad \swarrow \\ \bullet 2 \\ \eta_{234} \\ \downarrow \\ \bullet 1 \end{array} \quad \begin{array}{c} \bullet 5 \\ \eta_5 \\ \downarrow \\ \bullet 0 \end{array} = \begin{array}{c} \bullet 4 \\ \eta_4 \\ \downarrow \\ \bullet 3 \\ \eta_{34} \\ \downarrow \\ \bullet 2 \\ \eta_{234} \\ \downarrow \\ \bullet 1 \end{array} \quad \begin{array}{c} \bullet 5 \\ \eta_5 \\ \downarrow \\ \bullet 0 \end{array} + \begin{array}{c} \bullet 3 \\ \eta_3 \\ \downarrow \\ \bullet 4 \\ \eta_{34} \\ \downarrow \\ \bullet 2 \\ \eta_{234} \\ \downarrow \\ \bullet 1 \end{array} \quad \begin{array}{c} \bullet 5 \\ \eta_5 \\ \downarrow \\ \bullet 0 \end{array}. \quad (4.12)$$

4.2 z_0 -derivative of $\mathbf{Z}_{0,n}^\tau$

Here, we will rewrite the differential equation of subsection 3.3 in the language of integrals $Z_{0,n}^\tau$, which will be the main players in section 5. The genus-one Selberg integrals (3.32) with an auxiliary point used in ref. [2] can be obtained by the methods described in appendix D.1.

Starting from the basis choice for the n -point integrals $Z_{0,n}^\tau$ in eq. (4.3), we will now demonstrate that the z_0 -derivatives $\partial_0 Z_{0,n}^\tau((1, A), (0, B))$, where we denote $\partial_0 = \partial_{z_0}$, are expressible in terms of the basis integrals $Z_{0,n}^\tau$. In the $n!$ -component vector notation of eq. (4.3), we will derive a differential equation of the form

$$\partial_0 \mathbf{Z}_{0,n}^\tau = X_{0,n}^\tau \mathbf{Z}_{0,n}^\tau, \quad (4.13)$$

where the entries of the $n! \times n!$ matrix $X_{0,n}^\tau$ are linear in s_{ij} , comprise first derivatives in the η_j and will be explicitly determined at any n . Moreover, the sole z_0 - and τ -dependence of $X_{0,n}^\tau$ occurs via $f_{01}^{(k)} = f^{(k)}(z_{01}|\tau)$, i.e. one can uniquely identify z_0 - and τ -independent $n! \times n!$ matrices $r_{0,n}(x_k)$ that cast (4.13) into the form

$$\partial_0 \mathbf{Z}_{0,n}^\tau = \sum_{k=0}^{\infty} f_{01}^{(k)} r_{0,n}(x_k) \mathbf{Z}_{0,n}^\tau. \quad (4.14)$$

Hence, the main result of this section to be derived below is that the $n!$ -component vector $\mathbf{Z}_{0,n}^\tau$ of augmented Z^τ -integrals satisfies an elliptic KZB equation in the auxiliary puncture z_0 .

4.2.1 Deriving the n -point formula

The first step in calculating $\partial_0 \mathbf{Z}_{0,n}^\tau$ is to use integration by parts such that all the partial derivatives only act on the Koba–Nielsen factor, followed by an application of eq. (3.16) with an extra point z_0

$$\partial_{z_i} \text{KN}_{012\dots n}^\tau = - \sum_{\substack{j=0 \\ j \neq i}}^n s_{ij} f_{ij}^{(1)} \text{KN}_{012\dots n}^\tau. \quad (4.15)$$

Using the notation $A = (a_1, a_2, \dots, a_p)$ and $B = (b_1, b_2, \dots, b_q)$ for the disjoint sequences with $A \cup B = \{2, 3, \dots, n\}$ and additionally denoting $a_0 = 1$, $b_0 = 0$, this amounts to

$$\begin{aligned} \partial_0 Z_{0,n}^\tau((1, A), (0, B)) &= \int_{\gamma_{12\dots n0}} \prod_{i=2}^n dz_i \left(\sum_{j=0}^q \partial_{b_j} \text{KN}_{01\dots n}^\tau \right) \varphi^\tau(1, A) \varphi^\tau(0, B) \\ &= \int_{\gamma_{12\dots n0}} \prod_{i=2}^n dz_i \text{KN}_{01\dots n}^\tau \sum_{k=0}^p \sum_{j=0}^q \left(s_{a_k, b_j} f_{a_k, b_j}^{(1)} \varphi^\tau(1, A) \varphi^\tau(0, B) \right). \end{aligned} \quad (4.16)$$

The second step of the calculation consists of rewriting the term in parenthesis using the Fay identity (2.24) and the chain identities (A.6) to (A.14). The rewriting process is cumbersome, but can be cast into an elegant form using a couple of additional notations and tools. The complete derivation can be found in appendix B and the result is the following: for a sequence $C = (c_1, c_2, \dots, c_m)$, a sum of η -variables is denoted by

$$\eta_C = \sum_{i=1}^m \eta_{c_i}, \quad (4.17)$$

then, the η -variables

$$\eta_0 = -\eta_B, \quad \eta_1 = -\eta_A \quad (4.18)$$

are assigned to the unintegrated punctures z_0 and $z_1 = 1$. Thus, defining the decomposition of a sequence C into subsequences C_{ij}

$$C = (c_1, \dots, c_{i-1}, \underbrace{c_i, c_{i+1}, \dots, c_{j-1}}_{C_{i,j}=C_{ij}}, c_j, c_{j+1}, \dots, c_m), \quad (4.19)$$

with

$$C_{ji} = \emptyset \text{ for } j \geq i, \quad C_{1,m+1} = C, \quad \tilde{C}_{ij} = (c_{j-1}, c_{j-2}, \dots, c_i), \quad (4.20)$$

where a tilde denotes the reversal of a sequence, the following closed formula can be derived as shown in appendix B.2:

$$\begin{aligned} & \partial_0 Z_{0,n}^\tau((1, A), (0, B)) \\ &= - \left(s_{(1,A),(0,B)} f_{01}^{(1)} + \sum_{k=1}^p s_{a_k,(0,B)} \partial_{\eta_{a_k}} - \sum_{j=1}^q s_{(1,A),b_j} \partial_{\eta_{b_j}} \right) Z_{0,n}^\tau((1, A), (0, B)) \\ &+ \sum_{k=1}^p \sum_{j=1}^q s_{a_k,b_j} \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \Omega_{01}(\eta_{B_{l,q+1}}) \\ & \quad Z_{0,n}^\tau \left((1, A_{1i} \sqcup (a_k, (\tilde{A}_{i,k} \sqcup A_{k+1,p+1})) \sqcup (b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1})) , (0, B_{1l}) \right) \\ &+ \sum_{k=1}^p \sum_{j=1}^q s_{a_k,b_j} \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \Omega_{01}(-\eta_{A_{i,p+1}}) \\ & \quad Z_{0,n}^\tau \left((1, A_{1i}), (0, B_{1l} \sqcup (b_j, (\tilde{B}_{l,j} \sqcup B_{j+1,q+1})) \sqcup (a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1})) \right) \\ &+ \sum_{j=1}^q s_{1,b_j} \sum_{l=1}^j (-1)^{j-l} \Omega_{01}(\eta_{B_{l,q+1}}) Z_{0,n}^\tau \left((1, A \sqcup (b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1})) , (0, B_{1l}) \right) \\ &+ \sum_{k=1}^p s_{a_k,0} \sum_{i=1}^k (-1)^{k-i} \Omega_{01}(-\eta_{A_{i,p+1}}) Z_{0,n}^\tau \left((1, A_{1i}), (0, B \sqcup (a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1})) \right). \quad (4.21) \end{aligned}$$

Moreover, $s_{(1,A),(0,B)}$, $s_{a_k,(0,B)}$ and $s_{(1,A),b_j}$ denote sums of Mandelstam invariants according to the following general definition for sequences $P = (p_1, p_2, \dots, p_l)$ and $Q = (q_1, q_2, \dots, q_m)$

$$s_{P,Q} = \sum_{i=1}^l \sum_{j=1}^m s_{p_i q_j}. \quad (4.22)$$

Upon writing the partial differential equation (4.21) for the vector of integrals $\mathbf{Z}_{0,n}^\tau$ in matrix form, we arrive at the central result (4.13) previewed above. The entries of the matrix $X_{0,n}^\tau$ are determined by the linear combinations in eq. (4.21), and expanding the Kronecker–Eisenstein series therein in terms of the functions $f_{01}^{(k)}$, we arrive at the elliptic KZB equation (4.14) satisfied by the $n!$ -component vector $\mathbf{Z}_{0,n}^\tau$ of augmented Z^τ -integrals. This generalizes the KZB-type eq. (3.35) for the genus-one Selberg integrals to their generating series $\mathbf{Z}_{0,n}^\tau$.

The matrices $r_{0,n}(x_k)$ in eq. (4.14) are independent of z_0 and τ , and one can see from eq. (4.21) that they are linear in the Mandelstam variables s_{ij} and of homogeneity degree $k-1$ in the variables η_j . The matrix $r_{0,n}(x_0)$ additionally involves first derivatives in η_j that are

counted as homogeneity degree -1 .

4.2.2 Alternative form in terms of the S -map

The z_0 -derivative in eq. (4.21) can be compactly rewritten using the so-called S -map defined by

$$\begin{aligned} \varphi^\tau(S[a_1 a_2 \dots a_p, b_1 b_2 \dots b_q]) &= \sum_{i=1}^p \sum_{j=1}^q (-1)^{i-j+p-1} s_{a_i b_j} \\ &\times \varphi^\tau((a_1 a_2 \dots a_{i-1} \sqcup a_p a_{p-1} \dots a_{i+1}), a_i, b_j, (b_{j-1} b_{j-2} \dots b_1 \sqcup b_{j+1} b_{j+2} \dots b_q)). \end{aligned} \quad (4.23)$$

The S -map (4.23) has been firstly studied in ref. [81] to rewrite BCJ relations [37] and can therefore be used to bring integration-by-parts relations among disk integrals (2.7) into the form

$$Z_n^{\text{tree}}(a_1, \dots, a_n | S[P, Q], n) = 0 \quad (4.24)$$

with arbitrary disjoint sequences P, Q such that $P \cup Q = \{1, 2, \dots, n-1\}$. In a genus-one context, the S -map featured in the n -point proposal for the τ -derivatives of Z^τ -integrals (2.26) in ref. [1],

$$\begin{aligned} 2\pi i \partial_\tau Z_n^\tau(\mathbb{I}_n | 1, 2, \dots, n) &= \left(\frac{1}{2} \sum_{i=2}^n s_{1i} \partial_{\eta_i}^2 + \frac{1}{2} \sum_{2 \leq i < j}^n s_{ij} (\partial_{\eta_i} - \partial_{\eta_j})^2 - 2\zeta_2 s_{12\dots n} \right) Z_n^\tau(\mathbb{I}_n | 1, 2, \dots, n) \\ &\quad - \sum_{i=2}^n \wp(\eta_i + \eta_{i+1} + \dots + \eta_n | \tau) Z_n^\tau(\mathbb{I}_n | S[12\dots i-1, i(i+1)\dots n]) \end{aligned} \quad (4.25)$$

which was rigorously derived in ref. [79].

As will be derived in appendix B.3, an alternative form of eq. (4.21) is given by the following formula,

$$\begin{aligned} &\partial_0 Z_{0,n}^\tau((1, A), (0, B)) \\ &= - \left(s_{(1,A),(0,B)} f_{01}^{(1)} + \sum_{k=1}^p s_{a_k, (0,B)} \partial_{\eta_{a_k}} - \sum_{j=1}^q s_{(1,A), b_j} \partial_{\eta_{b_j}} \right) Z_{0,n}^\tau((1, A), (0, B)) \\ &\quad + \sum_{l=1}^q \Omega_{01}(\eta_{B_{l,q+1}}) Z_{0,n}^\tau((0, B_{1l}), (S[(1, A), B_{l,q+1}])) \\ &\quad + \sum_{l=1}^p \Omega_{01}(-\eta_{A_{l,p+1}}) Z_{0,n}^\tau((1, A_{1l}), (S[(0, B), A_{l,p+1}]]), \end{aligned} \quad (4.26)$$

where e.g. (recall that $b_0 = 0$)

$$\varphi^\tau(S[(0, B), A_{l,p+1}]) = \sum_{k=l}^p \sum_{j=0}^q (-1)^{q-j+k-l} s_{a_k, b_j} \varphi^\tau(B_{0j} \sqcup \tilde{B}_{j+1, q+1}, b_j, a_k, \tilde{A}_{lk} \sqcup A_{k+1, p+1}). \quad (4.27)$$

The individual terms in the shuffle $\varphi^\tau(B_{0j} \sqcup \dots)$ do not necessarily have the label 0 in the first entry of the chain and thereby involve integrands outside the basis of $Z_{0,n}^\tau((1, A), (0, B))$ in eq. (4.6). Hence, it remains to apply combinations of Fay identities in the Kleiss–Kuijff form [82, 83]

$$Z_{0,n}^\tau((P, 1, Q), (0, B)) = (-1)^{|P|} Z_{0,n}^\tau((1, \tilde{P} \sqcup Q), (0, B)),$$

$$Z_{0,n}^\tau((1, A), (P, 0, Q)) = (-1)^{|P|} Z_{0,n}^\tau((1, A), (0, \tilde{P} \sqcup Q)) \quad (4.28)$$

in order to manifest the $n!$ entries of $\mathbf{Z}_{0,n}^\tau$ on the right-hand side of eq. (4.26), where $|P|$ denotes the number of labels in P . The combination of eqs. (4.28) and (4.26) encodes all-multiplicity expressions for the matrix $X_{0,n}^\tau$ in eq. (4.13).

4.2.3 Two-point example

The simplest example can be found at two points. The basis vector eq. (4.3) of augmented Z^τ -integrals at $n = 2$ points is given by

$$\mathbf{Z}_{0,2}^\tau = \int_0^{z_0} dz_2 \text{KN}_{012}^\tau \begin{pmatrix} \Omega_{12}(\eta) \\ \Omega_{02}(\eta) \end{pmatrix} = \begin{pmatrix} Z_{0,2}^\tau(1, 2) \\ Z_{0,2}^\tau(0, 2) \end{pmatrix}. \quad (4.29)$$

The partial differential equation (4.13) follows from the closed formula (4.21) or its reformulation in section 4.2.2. Both approaches yield

$$\partial_0 \mathbf{Z}_{0,2}^\tau = \begin{pmatrix} -(s_{01} + s_{02})f_{01}^{(1)} - s_{02}\partial_\eta & s_{02}\Omega_{01}(-\eta) \\ s_{12}\Omega_{01}(\eta) & -(s_{01} + s_{12})f_{01}^{(1)} - s_{12}\partial_\eta \end{pmatrix} \mathbf{Z}_{0,2}^\tau \quad (4.30)$$

and expose the matrix $X_{0,2}^\tau$ in the notation of eq. (4.13). The expansion $X_{0,2}^\tau = \sum_{k=0}^{\infty} f_{01}^{(k)} r_{0,2}(x_k)$ leads to the elliptic KZB equation (4.14), where the matrices $r_{0,2}(x_k)$ are given by

$$\begin{aligned} r_{0,2}(x_0) &= \begin{pmatrix} -s_{02}\partial_\eta & -s_{02}/\eta \\ s_{12}/\eta & s_{12}\partial_\eta \end{pmatrix}, \\ r_{0,2}(x_1) &= \begin{pmatrix} -(s_{01} + s_{02}) & s_{02} \\ s_{12} & -(s_{01} + s_{12}) \end{pmatrix}, \\ r_{0,2}(x_k) &= \eta^{k-1} \begin{pmatrix} 0 & (-1)^{k-1}s_{02} \\ s_{12} & 0 \end{pmatrix}, \quad k \geq 2. \end{aligned} \quad (4.31)$$

4.2.4 Three-point example

The three-point basis vector (4.3)

$$\mathbf{Z}_{0,3}^\tau = \int_0^{z_0} dz_3 \int_0^{z_3} dz_2 \text{KN}_{0123}^\tau \begin{pmatrix} \Omega_{12}(\eta_{23})\Omega_{23}(\eta_3) \\ \Omega_{13}(\eta_{23})\Omega_{32}(\eta_2) \\ \Omega_{12}(\eta_2)\Omega_{03}(\eta_3) \\ \Omega_{13}(\eta_3)\Omega_{02}(\eta_2) \\ \Omega_{03}(\eta_{23})\Omega_{32}(\eta_2) \\ \Omega_{02}(\eta_{23})\Omega_{23}(\eta_3) \end{pmatrix} = \begin{pmatrix} Z_{0,3}^\tau(1, 2, 3) \\ Z_{0,3}^\tau(1, 3, 2) \\ Z_{0,3}^\tau((1, 2), (0, 3)) \\ Z_{0,3}^\tau((1, 3), (0, 2)) \\ Z_{0,3}^\tau(0, 3, 2) \\ Z_{0,3}^\tau(0, 2, 3) \end{pmatrix} \quad (4.32)$$

obeys the following differential equation according to eqs. (4.21) and (4.26),

$$\partial_0 \mathbf{Z}_{0,3}^\tau = \text{diag} \begin{pmatrix} -s_{02}\partial_{\eta_2} - s_{03}\partial_{\eta_3} - s_{0,123}f_{01}^{(1)} \\ -s_{02}\partial_{\eta_2} - s_{03}\partial_{\eta_3} - s_{0,123}f_{01}^{(1)} \\ -(s_{02} + s_{23})\partial_{\eta_2} + (s_{13} + s_{23})\partial_{\eta_3} - s_{03,12}f_{01}^{(1)} \\ -(s_{03} + s_{23})\partial_{\eta_3} + (s_{12} + s_{23})\partial_{\eta_2} - s_{02,13}f_{01}^{(1)} \\ s_{12}\partial_{\eta_2} + s_{13}\partial_{\eta_3} - s_{1,023}f_{01}^{(1)} \\ s_{12}\partial_{\eta_2} + s_{13}\partial_{\eta_3} - s_{1,023}f_{01}^{(1)} \end{pmatrix} \quad (4.33)$$

$$+ \begin{pmatrix} 0 & 0 & -s_{03}\Omega_{10}(\eta_3) & 0 & s_{03}\Omega_{10}(\eta_{23}) & -s_{02}\Omega_{10}(\eta_{23}) \\ 0 & 0 & 0 & -s_{02}\Omega_{10}(\eta_2) & -s_{03}\Omega_{10}(\eta_{23}) & s_{02}\Omega_{10}(\eta_{23}) \\ (s_{13}+s_{23})\Omega_{01}(\eta_3) & s_{31}\Omega_{01}(\eta_3) & 0 & 0 & -(s_{02}+s_{23})\Omega_{10}(\eta_2) & -s_{02}\Omega_{10}(\eta_2) \\ s_{21}\Omega_{01}(\eta_2) & (s_{12}+s_{23})\Omega_{01}(\eta_2) & 0 & 0 & -s_{03}\Omega_{10}(\eta_3) & -(s_{03}+s_{23})\Omega_{10}(\eta_3) \\ -s_{12}\Omega_{01}(\eta_{23}) & s_{13}\Omega_{01}(\eta_{23}) & s_{12}\Omega_{01}(\eta_2) & 0 & 0 & 0 \\ s_{12}\Omega_{01}(\eta_{23}) & -s_{13}\Omega_{01}(\eta_{23}) & 0 & s_{13}\Omega_{01}(\eta_3) & 0 & 0 \end{pmatrix} \mathbf{Z}_{0,3}^\tau$$

see eq. (4.22) for the $s_{P,Q}$ notation in the first line. By matching with the general form (4.14) of the elliptic KZB equation, one can read off the following 6×6 matrices $r_{0,3}(x_k)$:

$$r_{0,3}(x_0) = \text{diag} \begin{pmatrix} -s_{02}\partial_{\eta_2} - s_{03}\partial_{\eta_3} \\ -s_{02}\partial_{\eta_2} - s_{03}\partial_{\eta_3} \\ -(s_{02}+s_{23})\partial_{\eta_2} + (s_{13}+s_{23})\partial_{\eta_3} \\ -(s_{03}+s_{23})\partial_{\eta_3} + (s_{12}+s_{23})\partial_{\eta_2} \\ s_{12}\partial_{\eta_2} + s_{13}\partial_{\eta_3} \\ s_{12}\partial_{\eta_2} + s_{13}\partial_{\eta_3} \end{pmatrix} + \begin{pmatrix} 0 & 0 & -\frac{s_{03}}{\eta_3} & 0 & \frac{s_{03}}{\eta_{23}} & -\frac{s_{02}}{\eta_{23}} \\ 0 & 0 & 0 & -\frac{s_{02}}{\eta_2} & -\frac{s_{03}}{\eta_{23}} & \frac{s_{02}}{\eta_{23}} \\ \frac{s_{13}+s_{23}}{\eta_3} & \frac{s_{13}}{\eta_3} & 0 & 0 & -\frac{s_{02}+s_{23}}{\eta_2} & -\frac{s_{02}}{\eta_2} \\ \frac{s_{12}}{\eta_2} & \frac{s_{12}+s_{23}}{\eta_2} & 0 & 0 & -\frac{s_{03}}{\eta_3} & -\frac{s_{03}+s_{23}}{\eta_3} \\ -\frac{s_{12}}{\eta_{23}} & \frac{s_{13}}{\eta_{23}} & \frac{s_{12}}{\eta_2} & 0 & 0 & 0 \\ \frac{s_{12}}{\eta_{23}} & -\frac{s_{13}}{\eta_{23}} & 0 & \frac{s_{13}}{\eta_3} & 0 & 0 \end{pmatrix}, \quad (4.34)$$

$$r_{0,3}(x_1) = \begin{pmatrix} -s_{0,123} & 0 & s_{03} & 0 & -s_{03} & s_{02} \\ 0 & -s_{0,123} & 0 & s_{02} & s_{03} & -s_{02} \\ s_{13}+s_{23} & s_{13} & -s_{03,12} & 0 & s_{02}+s_{23} & s_{02} \\ s_{12} & s_{12}+s_{23} & 0 & -s_{02,13} & s_{03} & s_{03}+s_{23} \\ -s_{12} & s_{13} & s_{12} & 0 & -s_{023,1} & 0 \\ s_{12} & -s_{13} & 0 & s_{13} & 0 & -s_{023,1} \end{pmatrix}, \quad (4.35)$$

$$r_{0,3}(x_k) = \begin{pmatrix} 0 & 0 & s_{03}(-\eta_3)^{k-1} & 0 & -s_{03}(-\eta_{23})^{k-1} & s_{02}(-\eta_{23})^{k-1} \\ 0 & 0 & 0 & s_{02}(-\eta_2)^{k-1} & s_{03}(-\eta_{23})^{k-1} & -s_{02}(-\eta_{23})^{k-1} \\ (s_{13}+s_{23})\eta_3^{k-1} & s_{13}\eta_3^{k-1} & 0 & 0 & (s_{02}+s_{23})(-\eta_2)^{k-1} & s_{02}(-\eta_2)^{k-1} \\ s_{12}\eta_2^{k-1} & (s_{12}+s_{23})\eta_2^{k-1} & 0 & 0 & s_{03}(-\eta_3)^{k-1} & (s_{03}+s_{23})(-\eta_3)^{k-1} \\ -s_{12}\eta_{23}^{k-1} & s_{13}\eta_{23}^{k-1} & s_{12}\eta_2^{k-1} & 0 & 0 & 0 \\ s_{12}\eta_{23}^{k-1} & -s_{13}\eta_{23}^{k-1} & 0 & s_{13}\eta_3^{k-1} & 0 & 0 \end{pmatrix}, \quad (4.36)$$

where $k \geq 2$.

4.3 τ -derivative of $\mathbf{Z}_{0,n}^\tau$

As we will show in this section, the $n!$ basis $\mathbf{Z}_{0,n}^\tau$ in eq. (4.3) also closes under τ -derivatives. Similar to the homogeneous first-order equation (4.13) in z_0 , the τ -derivative of $\mathbf{Z}_{0,n}^\tau$ will be cast into the form

$$2\pi i \partial_\tau \mathbf{Z}_{0,n}^\tau = (D_{0,n}^\tau + B_{0,n}^\tau) \mathbf{Z}_{0,n}^\tau, \quad (4.37)$$

where the explicit form of the $n! \times n!$ matrices $D_{0,n}^\tau, B_{0,n}^\tau$ will be determined below. We have grouped the matrices according to the τ - and z_0 -dependence which is solely carried by $f_{01}^{(k)}$ and Eisenstein series G_k ,

$$D_{0,n}^\tau = -r_{0,n}(\epsilon_0) + \sum_{k=4}^{\infty} (1-k) G_k r_{0,n}(\epsilon_k),$$

$$B_{0,n}^\tau = \sum_{k=2}^{\infty} (k-1) f_{01}^{(k)} r_{0,n}(b_k), \quad (4.38)$$

where the entries of $D_{0,n}^\tau, B_{0,n}^\tau$ and therefore all the $r_{0,n}(b_k), r_{0,n}(\epsilon_k)$ are again linear in s_{ij} . By construction, the $n! \times n!$ matrices $r_{0,n}(b_k), r_{0,n}(\epsilon_k)$ no longer depend on z_0 and τ . The appearance of $f_{01}^{(k)}$ in the differential equation in τ is shared by the operator eq. (4.14) in the z_0 derivative, and we will see from two perspectives that the accompanying $n! \times n!$ matrices are related by

$$r_{0,n}(b_k) = r_{0,n}(x_{k-1}), \quad k \geq 2. \quad (4.39)$$

Note that the additional zero in the subscript distinguishes the $n! \times n!$ matrices $r_{0,n}(\epsilon_k)$ in eq. (4.38) from the $(n-1)! \times (n-1)!$ matrices $r_n(\epsilon_k)$ in the differential equation (3.19) of the Z^τ -integrals without augmentation.

4.3.1 Deriving the n -point formula

The evaluation of the τ -derivative $2\pi i \partial_\tau Z_{0,n}^\tau((1, A), (0, B))$ with $A = (a_1, a_2, \dots, a_p)$ and $B = (b_1, b_2, \dots, b_q)$ follows the same steps as the z_0 -derivative in section 4.2. While the details are shown in appendix C, we give an overview in the following paragraphs.

First, the mixed heat equation (2.25) and integration by parts can be used to find an expression where all the derivatives only act on the Koba–Nielsen factor. Then, for the z_j -derivatives eq. (4.15) and for the τ -derivative the equation

$$2\pi i \partial_\tau \text{KN}_{012\dots n}^\tau = - \sum_{0 \leq i < j \leq n} s_{ij} (f_{ij}^{(2)} + 2\zeta_2) \text{KN}_{012\dots n}^\tau \quad (4.40)$$

can be applied, which leads to the expression

$$\begin{aligned} & 2\pi i \partial_\tau Z_{0,n}^\tau((1, A), (0, B)) \\ &= - \int_{\gamma_{12\dots n0}} dz_2 \dots dz_n \text{KN}_{01\dots n}^\tau \left(2\zeta_2 s_{01\dots n} \varphi^\tau(1, A) \varphi^\tau(0, B) \right. \\ &+ \sum_{k=1}^p \sum_{j=0}^{k-1} s_{a_k, a_j} \left(f_{a_k, a_j}^{(1)} \left(\partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{a_j}} \right) + f_{a_k, a_j}^{(2)} \right) \varphi^\tau(0, B) \varphi^\tau(1, A) \\ &+ \sum_{k=1}^q \sum_{j=0}^{k-1} s_{b_k, b_j} \left(f_{b_k, b_j}^{(1)} \left(\partial_{\eta_{b_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} \right) + f_{b_k, b_j}^{(2)} \right) \varphi^\tau(0, B) \varphi^\tau(1, A) \\ &\left. + \sum_{k=0}^p \sum_{j=0}^q s_{a_k, b_j} \left(f_{a_k, b_j}^{(1)} \left(\theta_{k \geq 1} \partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} \right) - f_{b_j, a_k}^{(2)} \right) \varphi^\tau(1, A) \varphi^\tau(0, B) \right), \quad (4.41) \end{aligned}$$

where the step function $\theta_{j \geq 1}$ is taken to be 1 for $j \geq 1$ and zero for $j = 0$. From this equation similar identities as for the z_0 -derivative, mainly based on the Fay identity of Kronecker–Eisenstein series, lead to the following expression involving the S -map in eqs. (4.27) and (4.28)

$$\begin{aligned} & 2\pi i \partial_\tau Z_{0,n}^\tau((1, A), (0, B)) \\ &= \left(\frac{1}{2} \sum_{j=2}^n (s_{0j} + s_{1j}) \partial_{\eta_j}^2 + \frac{1}{2} \sum_{2 \leq i < j \leq n} s_{ij} (\partial_{\eta_i} - \partial_{\eta_j})^2 - 2\zeta_2 s_{01\dots n} - s_{(1,A),(0,B)} f_{01}^{(2)} \right) Z_{0,n}^\tau((1, A), (0, B)) \\ &+ \sum_{l=1}^q \left(\Omega_{01}^+(\eta_{B_{l,q+1}}) Z_{0,n}^\tau((0, B_{1l}), (S[(1, A), B_{l,q+1}])) \right. \\ &\quad \left. - \wp(\eta_{B_{l,p+1}}) Z_{0,n}^\tau((1, A), (S[(0, B_{1,l}), B_{l,q+1}])) \right) \end{aligned}$$

$$\begin{aligned}
& + \sum_{l=1}^p \left(\Omega_{01}^-(-\eta_{A_{l,p+1}}) Z_{0,n}^\tau((1, A_{1l}), (S[(0, B), A_{l,p+1}])) \right. \\
& \quad \left. - \wp(\eta_{A_{l,p+1}}) Z_{0,n}^\tau((0, B), (S[(1, A_{1,l}), A_{l,p+1}])) \right), \tag{4.42}
\end{aligned}$$

where

$$\Omega_{01}^\pm(\pm\xi) = \pm\partial_\xi\Omega_{01}(\pm\xi). \tag{4.43}$$

When all the S -maps in eq. (4.42) are expanded in terms of $Z_{0,n}^\tau((1, P), (0, Q))$, the result takes the closed form

$$\begin{aligned}
& 2\pi i \partial_\tau Z_{0,n}^\tau((1, A), (0, B)) \\
& = \left(\frac{1}{2} \sum_{j=2}^n (s_{0j} + s_{1j}) \partial_{\eta_j}^2 + \frac{1}{2} \sum_{2 \leq i < j \leq n} s_{ij} (\partial_{\eta_i} - \partial_{\eta_j})^2 - 2\zeta_2 s_{01\dots n} - s_{(1,A),(0,B)} f_{01}^{(2)} \right) Z_{0,n}^\tau((1, A), (0, B)) \\
& \quad - \sum_{k=1}^q \sum_{j=0}^{k-1} s_{b_k, b_j} \sum_{l=j+1}^k \wp(\eta_{B_{l,q+1}}) (-1)^{k-l} Z_{0,n}^\tau \left((1, A), \left(0, B_{1,j}, b_j, B_{j,l} \sqcup (b_k, \tilde{B}_{l,k} \sqcup B_{k+1,q+1}) \right) \right) \\
& \quad - \sum_{k=1}^p \sum_{j=0}^{k-1} s_{a_k, a_j} \sum_{l=j+1}^k \wp(\eta_{A_{l,p+1}}) (-1)^{k-l} Z_{0,n}^\tau \left((1, A_{1,j}, a_j, A_{j,l} \sqcup (a_k, \tilde{A}_{l,k} \sqcup A_{k+1,p+1}) \right), (0, B) \right) \\
& \quad + \sum_{k=1}^p \sum_{j=1}^q s_{a_k, b_j} \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \Omega_{01}^+(\eta_{B_{l,q+1}}) \\
& \quad \quad Z_{0,n}^\tau \left((1, A_{1i} \sqcup (a_k, (\tilde{A}_{i,k} \sqcup A_{k+1,p+1}) \sqcup (b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1})) \right), (0, B_{1l}) \right) \\
& \quad + \sum_{k=1}^p \sum_{j=1}^q s_{a_k, b_j} \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \Omega_{01}^-(-\eta_{A_{i,p+1}}) \\
& \quad \quad Z_{0,n}^\tau \left((1, A_{1i}), \left(0, B_{1l} \sqcup (b_j, (\tilde{B}_{l,j} \sqcup B_{j+1,q+1}) \sqcup (a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1}) \right) \right) \\
& \quad + \sum_{j=1}^q s_{1, b_j} \sum_{l=1}^j (-1)^{j-l} \Omega_{01}^+(\eta_{B_{l,q+1}}) Z_{0,n}^\tau \left((1, A \sqcup (b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1}) \right), (0, B_{1l}) \right) \\
& \quad + \sum_{k=1}^p s_{a_k, 0} \sum_{i=1}^k (-1)^{k-i} \Omega_{01}^-(-\eta_{A_{i,p+1}}) Z_{0,n}^\tau \left((1, A_{1i}), \left(0, B \sqcup (a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1}) \right) \right). \tag{4.44}
\end{aligned}$$

Note that the all-multiplicity formulæ (4.42) and (4.44) for τ -derivatives strongly resemble eqs. (4.26) and (4.21) for z_0 -derivatives, respectively. The only differences concern the diagonal term (the coefficients of $Z_{0,n}^\tau((1, A), (0, B))$ on the right-hand sides), the η_j -derivatives $\Omega_{01}^+(\eta_{B_{l,q+1}})$, $\Omega_{01}^-(-\eta_{A_{l,p+1}})$ instead of $\Omega_{01}(\eta_{B_{l,q+1}})$, $\Omega_{01}(-\eta_{A_{l,p+1}})$, respectively, and the additional appearance of Weierstraß \wp -functions in the τ -derivatives.

The closed formula (4.44) or (4.42) along with eq. (4.28) lead to the matrix equation (4.37) for the basis vector eq. (4.3), i.e. determine the entries of the $n! \times n!$ matrices $D_{0,n}^\tau, B_{0,n}^\tau$. With the expansion of the Kronecker–Eisenstein series and \wp -functions in the τ -derivatives in terms of $f_{01}^{(k)}$ and G_k , we can read off the explicit form of the matrices $r_{0,n}(b_k)$ and $r_{0,n}(\epsilon_k)$ defined by

eq. (4.38),

$$2\pi i \partial_\tau \mathbf{Z}_{0,n}^\tau = \left(-r_{0,n}(\epsilon_0) + \sum_{k=4}^{\infty} (1-k) G_k r_{0,n}(\epsilon_k) + \sum_{k=2}^{\infty} (k-1) f_{01}^{(k)} r_{0,n}(b_k) \right) \mathbf{Z}_{0,n}^\tau. \quad (4.45)$$

The $r_{0,n}(b_k)$ and $r_{0,n}(\epsilon_k)$ are all linear in s_{ij} and independent of z_0 and τ . Moreover, their instances at $k \geq 2$ are both homogeneous polynomials of degree $k-2$ in the η_j , whereas $r_{0,n}(\epsilon_0)$ is a combination of $2\zeta_2 s_{012\dots n}$, η_j^{-2} and $\partial_{\eta_j}^2$. As previewed in eq. (4.39), one can confirm from eq. (4.44) or eq. (4.42) that all the $r_{0,n}(b_k)$ with $k \geq 2$ agree with the operators $r_{0,n}(x_{k-1})$ in the z_0 -derivative eq. (4.14). An alternative derivation of eq. (4.39) will be given in section 4.4.

4.3.2 Two-point example

According to eqs. (4.42) and (4.44), the τ -derivative of the $n = 2$ example eq. (4.29) is given by

$$2\pi i \partial_\tau \mathbf{Z}_{0,2}^\tau = \left(\frac{1}{2}(s_{02} + s_{12}) \partial_\eta^2 - 2\zeta_2 s_{012} \right) \mathbf{Z}_{0,2}^\tau + \begin{pmatrix} -s_{12} \wp(\eta) - (s_{01} + s_{02}) f_{01}^{(2)} & -s_{02} \partial_\eta \Omega_{01}(-\eta) \\ s_{12} \partial_\eta \Omega_{01}(\eta) & -s_{02} \wp(\eta) - (s_{01} + s_{12}) f_{01}^{(2)} \end{pmatrix} \mathbf{Z}_{0,2}^\tau. \quad (4.46)$$

Upon comparison with (4.45), one can read off the $r_{0,2}(\epsilon_k)$ matrices

$$r_{0,2}(\epsilon_0) = \frac{1}{\eta^2} \begin{pmatrix} s_{12} & s_{02} \\ s_{12} & s_{02} \end{pmatrix} + \left(2\zeta_2 s_{012} - \frac{1}{2}(s_{02} + s_{12}) \partial_\eta^2 \right) \mathbb{1}_{2 \times 2},$$

$$r_{0,2}(\epsilon_k) = \eta^{k-2} \begin{pmatrix} s_{12} & 0 \\ 0 & s_{02} \end{pmatrix}, \quad k \geq 4, \quad (4.47)$$

and $r_{0,2}(b_k)$ matrices

$$r_{0,2}(b_2) = \begin{pmatrix} -(s_{01} + s_{02}) & s_{02} \\ s_{12} & -(s_{01} + s_{12}) \end{pmatrix} = r_{0,2}(x_1),$$

$$r_{0,2}(b_k) = \eta^{k-2} \begin{pmatrix} 0 & (-1)^{k-2} s_{02} \\ s_{12} & 0 \end{pmatrix} = r_{0,2}(x_{k-1}), \quad k \geq 3, \quad (4.48)$$

in agreement with the $r_{0,2}(x_{k-1})$ in eq. (4.31).

4.3.3 Three-point example

For the six-component vector $\mathbf{Z}_{0,3}^\tau$ in eq. (4.32), the τ -derivative resulting from eqs. (4.42) and (4.44) is spelt out in appendix C.3. The $r_{0,3}(\cdot)$ matrices obtained by matching eq. (C.22) with eq. (4.45) are given by

$$r_{0,3}(\epsilon_0) = \left(2\zeta_2 s_{0123} - \frac{1}{2}(s_{02} + s_{12}) \partial_{\eta_2}^2 - \frac{1}{2}(s_{03} + s_{13}) \partial_{\eta_3}^2 - \frac{1}{2} s_{23} (\partial_{\eta_2} - \partial_{\eta_3})^2 \right) \mathbb{1}_{6 \times 6}$$

$$+ \begin{pmatrix} \frac{s_{12}}{\eta_{23}} + \frac{s_{13+s_{23}}}{\eta_3} & \frac{s_{13}}{\eta_3} - \frac{s_{12}}{\eta_{23}} & \frac{s_{03}}{\eta_3} & 0 & -\frac{s_{03}}{\eta_{23}} & \frac{s_{02}}{\eta_{23}} \\ \frac{s_{12}}{\eta_2} - \frac{s_{12}}{\eta_{23}} & \frac{s_{13}}{\eta_{23}} + \frac{s_{12+s_{23}}}{\eta_2} & 0 & \frac{s_{02}}{\eta_2} & \frac{s_{03}}{\eta_{23}} & -\frac{s_{02}}{\eta_{23}} \\ \frac{(s_{13+s_{23}})}{\eta_3} & \frac{s_{13}}{\eta_3} & \frac{s_{12}}{\eta_2} + \frac{s_{03}}{\eta_3} & 0 & \frac{(s_{02+s_{23}})}{\eta_2} & \frac{s_{02}}{\eta_2} \\ \frac{s_{12}}{\eta_2} & \frac{(s_{12+s_{23}})}{\eta_2} & 0 & \frac{s_{13}}{\eta_3} + \frac{s_{02}}{\eta_2} & \frac{s_{03}}{\eta_3} & \frac{(s_{03+s_{23}})}{\eta_3} \\ -\frac{s_{12}}{\eta_{23}} & \frac{s_{13}}{\eta_{23}} & \frac{s_{12}}{\eta_2} & 0 & \frac{s_{03}}{\eta_{23}} + \frac{(s_{02+s_{23}})}{\eta_2} & \frac{s_{02}}{\eta_2} - \frac{s_{02}}{\eta_{23}} \\ \frac{s_{12}}{\eta_{23}} & -\frac{s_{13}}{\eta_{23}} & 0 & \frac{s_{13}}{\eta_3} & \frac{s_{03}}{\eta_3} - \frac{s_{03}}{\eta_{23}} & \frac{s_{02}}{\eta_{23}} + \frac{(s_{03+s_{23}})}{\eta_3} \end{pmatrix}, \quad (4.49)$$

$$r_{0,3}(\epsilon_k) = \text{diag} \left\{ \begin{pmatrix} s_{12}\eta_{23}^{k-2} + (s_{13+s_{23}})\eta_3^{k-2} & s_{13}\eta_3^{k-2} - s_{13}\eta_{23}^{k-2} \\ s_{12}\eta_2^{k-2} - s_{12}\eta_{23}^{k-2} & s_{13}\eta_{23}^{k-2} + (s_{12+s_{23}})\eta_2^{k-2} \end{pmatrix}, \right. \\ \left. \begin{pmatrix} s_{12}\eta_2^{k-2} + s_{03}\eta_3^{k-2} & 0 \\ 0 & s_{13}\eta_3^{k-2} + s_{02}\eta_2^{k-2} \end{pmatrix}, \right. \\ \left. \begin{pmatrix} s_{03}\eta_{23}^{k-2} + (s_{02+s_{23}})\eta_2^{k-2} & s_{02}\eta_2^{k-2} - s_{02}\eta_{23}^{k-2} \\ s_{03}\eta_3^{k-2} - s_{03}\eta_{23}^{k-2} & s_{02}\eta_{23}^{k-2} + (s_{03+s_{23}})\eta_3^{k-2} \end{pmatrix} \right\}, \quad k \geq 4, \quad (4.50)$$

as well as the $r_{0,3}(x_{k-1})$ in eqs. (4.35) and (4.36),

$$r_{0,3}(b_k) = r_{0,3}(x_{k-1}), \quad k \geq 2. \quad (4.51)$$

4.4 Elliptic KZB system on the twice-punctured torus

In the previous subsections, the two partial differential equations (4.14) and (4.45) satisfied by the vector $\mathbf{Z}_{0,n}^\tau$ defined in eq. (4.3) have been identified. Together, they form the system of differential equations

$$\partial_{z_0} \mathbf{Z}_{0,n}^\tau = \sum_{k=0}^{\infty} f_{01}^{(k)} r_{0,n}(x_k) \mathbf{Z}_{0,n}^\tau, \\ 2\pi i \partial_\tau \mathbf{Z}_{0,n}^\tau = \left(-r_{0,n}(\epsilon_0) + \sum_{k=4}^{\infty} (1-k) G_k r_{0,n}(\epsilon_k) + \sum_{k=2}^{\infty} (k-1) f_{01}^{(k)} r_{0,n}(b_k) \right) \mathbf{Z}_{0,n}^\tau, \quad (4.52)$$

which is an elliptic KZB system on the moduli space of the twice-punctured torus, with (fixed) puncture $z_1 = 0$ and (variable) puncture z_0 [67]. While we have considered the two differential equations separately so far, in this section properties of the corresponding matrices $r_{0,n}(x_k)$, $r_{0,n}(b_k)$ and $r_{0,n}(\epsilon_k)$ are determined employing the interplay of both differential equations. In order to investigate these commutation relations, an unspecified system is considered, which has the same structure

$$\partial_{z_0} \mathcal{I}_0^\tau = \sum_{k=0}^{\infty} f_{01}^{(k)} x_k \mathcal{I}_0^\tau, \\ 2\pi i \partial_\tau \mathcal{I}_0^\tau = \left\{ -\epsilon_0 + \sum_{k=4}^{\infty} (1-k) G_k \epsilon_k + \sum_{k=2}^{\infty} (k-1) f_{01}^{(k)} b_k \right\} \mathcal{I}_0^\tau, \quad (4.53)$$

where unspecified representations of braid matrices x_k , derivations ϵ_k and further generators b_k act on an abstract solution \mathcal{I}_0^τ . The commutativity of the mixed second derivatives (Schwarz

integrability condition)

$$\begin{aligned}
\partial_{z_0}(2\pi i \partial_\tau \mathcal{I}_0^\tau) &= \sum_{k=2}^{\infty} \partial_{z_0} f_{01}^{(k)} (k-1) b_k \mathcal{I}_0^\tau \\
&\quad + \left\{ -\epsilon_0 + \sum_{k=4}^{\infty} (1-k) G_k \epsilon_k + \sum_{k=2}^{\infty} f_{01}^{(k)} (k-1) b_k \right\} \sum_{\ell=0}^{\infty} f_{01}^{(\ell)} x_\ell \mathcal{I}_0^\tau, \\
2\pi i \partial_\tau (\partial_{z_0} \mathcal{I}_0^\tau) &= \sum_{k=0}^{\infty} 2\pi i \partial_\tau f_{01}^{(k)} x_k \mathcal{I}_0^\tau \\
&\quad + \sum_{\ell=0}^{\infty} f_{01}^{(\ell)} x_\ell \left\{ -\epsilon_0 + \sum_{k=4}^{\infty} (1-k) G_k \epsilon_k + \sum_{k=2}^{\infty} f_{01}^{(k)} (k-1) b_k \right\} \mathcal{I}_0^\tau
\end{aligned} \tag{4.54}$$

imposes various constraints on the x_k, ϵ_k, b_k which will serve as cross-checks for the $n! \times n!$ representations $r_{0,n}(\cdot)$ encoded in eqs. (4.26) and (4.42). By the components $2\pi i \partial_\tau f_{01}^{(k)} = k \partial_{z_0} f_{01}^{(k+1)}$ of the mixed heat equation (2.25) for real z_{01} , the commutator

$$\begin{aligned}
[2\pi i \partial_\tau, \partial_{z_0}] \mathcal{I}_0^\tau &= \sum_{k=2}^{\infty} (k-1) \partial_{z_0} f_{01}^{(k)} (x_{k-1} - b_k) \mathcal{I}_0^\tau \\
&\quad + \sum_{\ell=0}^{\infty} f_{01}^{(\ell)} \left\{ -[x_\ell, \epsilon_0] + \sum_{k=4}^{\infty} (1-k) G_k [x_\ell, \epsilon_k] + \sum_{k=2}^{\infty} (k-1) f_{01}^{(k)} [x_\ell, b_k] \right\} \mathcal{I}_0^\tau
\end{aligned} \tag{4.55}$$

has to vanish. In particular, the first line of eq. (4.55) has to vanish separately,

$$b_k = x_{k-1}, \quad k \geq 2, \tag{4.56}$$

since the derivatives $\partial_{z_0} f_{01}^{(k+1)}$ can be rewritten as [79]¹⁷

$$\partial_{z_0} f_{01}^{(n)} = -f_{01}^{(1)} f_{01}^{(n)} + (n+1) f_{01}^{(n+1)} - \widehat{G}_2 f_{01}^{(n-1)} - \sum_{k=4}^{n+1} G_k f_{01}^{(n+1-k)}, \quad n \geq 1 \tag{4.57}$$

and generate terms $\sim \widehat{G}_2 = G_2 - \frac{\pi}{\text{Im} \tau}$ that do not occur in the second line of eq. (4.55). By repeating these arguments for the KZB system (4.52) obeyed by the $n!$ -component vector $\mathbf{Z}_{0,n}^\tau$ in eq. (4.3), we arrive at eq. (4.39) independent of the explicit form of $r_{0,n}(b_k)$ and $r_{0,n}(x_k)$ obtained in sections 4.2 and 4.3.

Hence, the leftover integrability constraints after imposing eq. (4.56) are

$$\begin{aligned}
0 &= \sum_{k=2}^{\infty} (k-1) f_{01}^{(k)} [x_0, x_{k-1}] - \sum_{\ell=0}^{\infty} f_{01}^{(\ell)} [x_\ell, \epsilon_0] + \sum_{\ell=0}^{\infty} f_{01}^{(\ell)} \sum_{k=4}^{\infty} (1-k) G_k [x_\ell, \epsilon_k] \\
&\quad + \sum_{1 \leq a < b}^{\infty} (b f_{01}^{(a)} f_{01}^{(b+1)} - a f_{01}^{(a+1)} f_{01}^{(b)}) [x_a, x_b].
\end{aligned} \tag{4.58}$$

¹⁷The simplest examples of eq. (4.57) are

$$\partial_{z_0} f_{01}^{(1)} = -f_{01}^{(1)} f_{01}^{(1)} + 2f_{01}^{(2)} - \widehat{G}_2, \quad \partial_{z_0} f_{01}^{(2)} = -f_{01}^{(1)} f_{01}^{(2)} + 3f_{01}^{(3)} - \widehat{G}_2 f_{01}^{(1)},$$

while the simplest examples of eq. (4.59) below are

$$2f_{01}^{(1)} f_{01}^{(3)} - f_{01}^{(2)} f_{01}^{(2)} = 2f_{01}^{(4)} - 3G_4, \quad 3f_{01}^{(1)} f_{01}^{(4)} - f_{01}^{(2)} f_{01}^{(3)} = 5f_{01}^{(5)} - 3f_{01}^{(1)} G_4.$$

In order to infer relations among the commutators, the products $f_{01}^{(a)} f_{01}^{(b+1)}$ and $f_{01}^{(a+1)} f_{01}^{(b)}$ in the second line have to be rewritten in terms of the combinations $G_k f_{01}^{(\ell)}$ or $f_{01}^{(k+\ell)}$ in the first line. The required identities valid for $a+b \geq 2$ are generated by the ξ - and η -expansion of eq. (3.17),

$$\begin{aligned} & b f_{01}^{(a)} f_{01}^{(b+1)} - a f_{01}^{(a+1)} f_{01}^{(b)} \\ &= \frac{(b-a)(a+b+1)!}{(a+1)!(b+1)!} f_{01}^{(a+b+1)} - (-1)^{b(a+b)} G_{a+b+1} + a G_{a+1} \theta_{a \geq 3} f_{01}^{(b)} - b G_{b+1} \theta_{b \geq 3} f_{01}^{(a)} \\ &+ \sum_{k=4}^a \binom{a+b-k}{b-1} (k-1) G_k f_{01}^{(a+b+1-k)} - \sum_{k=4}^b \binom{a+b-k}{a-1} (k-1) G_k f_{01}^{(a+b+1-k)}. \end{aligned} \quad (4.59)$$

Since the step functions $\theta_{c \geq 3}$ in the second line are taken to be 1 for $c \geq 3$ and zero for $c \leq 2$, the aforementioned \widehat{G}_2 does not occur in eq. (4.58) or eq. (4.59). After rewriting the second line of eq. (4.58) via eq. (4.59), the coefficients of $G_k f_{01}^{(\ell)}$ and $f_{01}^{(k+\ell)}$ have to vanish separately, and one can read off identities like

$$\begin{aligned} [x_0, \epsilon_0] &= 0, & [x_0, \epsilon_4] &= -[x_1, x_2], \\ [x_1, \epsilon_0] &= 0, & [x_1, \epsilon_4] &= -[x_1, x_3], \\ [x_2, \epsilon_0] &= [x_0, x_1], & [x_2, \epsilon_4] &= -[x_1, x_4] - [x_2, x_3], \\ [x_3, \epsilon_0] &= 2[x_0, x_2], & [x_0, \epsilon_6] &= -[x_1, x_4] + [x_2, x_3], \\ [x_4, \epsilon_0] &= 3[x_0, x_3] + 2[x_1, x_2], & [x_1, \epsilon_6] &= -[x_1, x_5], \\ [x_5, \epsilon_0] &= 4[x_0, x_4] + 5[x_1, x_3], & [x_2, \epsilon_6] &= -[x_1, x_6] - [x_2, x_5], \\ [x_6, \epsilon_0] &= 5[x_0, x_5] + 9[x_1, x_4] + 5[x_2, x_3], & [x_0, \epsilon_8] &= -[x_1, x_6] + [x_2, x_5] - [x_3, x_4], \end{aligned} \quad (4.60)$$

and more generally (with $\ell \geq 1$ and $k \geq 4$)

$$\begin{aligned} [x_\ell, \epsilon_0] &= \sum_{j=0}^{\lfloor \ell/2 \rfloor - 1} \binom{\ell}{j} \frac{(\ell-1-2j)}{(j+1)} [x_j, x_{\ell-1-j}] \\ [x_0, \epsilon_k] &= \sum_{j=1}^{k/2-1} (-1)^j [x_j, x_{k-1-j}] \\ [x_\ell, \epsilon_k] &= - \sum_{j=0}^{\ell-1} \binom{\ell-1}{j} [x_{j+1}, x_{k+\ell-j-2}]. \end{aligned} \quad (4.61)$$

By iterating the first relation, the adjoint action $\text{ad}_{\epsilon_0}(\cdot) = [\epsilon_0, \cdot]$ turns out to be nilpotent when acting on x_ℓ ,

$$\text{ad}_{\epsilon_0}^\ell(x_\ell) = 0, \quad \ell \geq 1, \quad (4.62)$$

for instance $[\epsilon_0, [\epsilon_0, x_2]] = 0$. This follows from the fact that eq. (4.61) relates $[x_\ell, \epsilon_0]$ to $[x_a, x_b]$ with $a+b = \ell-1$, so the k^{th} adjoint action $\text{ad}_{\epsilon_0}^k(x_\ell)$ yields nested commutators of $x_{a_1}, x_{a_2}, \dots, x_{a_{k+1}}$ with $\sum_{j=1}^{k+1} a_j = \ell-k$. After $k = \ell-1$ steps, only x_0 and x_1 are left in the nested commutators which are both annihilated by the ℓ^{th} application of ad_{ϵ_0} , see eq. (4.60).

By repeating the above arguments for the KZB system (4.52) obeyed by the $n!$ -component vector $\mathbf{Z}_{0,n}^T$ in eq. (4.3), the commutator relations (4.61) are found to be preserved under $x_k \rightarrow$

$r_{0,n}(x_k)$ and $\epsilon_k \rightarrow r_{0,n}(\epsilon_k)$, for instance $[r_{0,n}(x_0), r_{0,n}(\epsilon_0)] = 0$ and ($\ell \geq 1, k \geq 4$)

$$[r_{0,n}(x_\ell), r_{0,n}(\epsilon_k)] = - \sum_{j=0}^{\ell-1} \binom{\ell-1}{j} [r_{0,n}(x_{j+1}), r_{0,n}(x_{k+\ell-j-2})]. \quad (4.63)$$

As a consistency check of the results for $\partial_{z_0} \mathbf{Z}_{0,n}^\tau$ and $\partial_\tau \mathbf{Z}_{0,n}^\tau$, we have confirmed validity of the above relations $[r_{0,n}(x_\ell), r_{0,n}(\epsilon_k)]$ for numerous configurations (n, k) .

The nilpotency property (4.62) is known to also hold for Tsunogai's derivations [76],

$$\text{ad}_{\epsilon_0}^{k-1}(\epsilon_k) = 0. \quad (4.64)$$

The Z^τ -integrals (3.13) without augmentation introduce conjectural $(n-1)! \times (n-1)!$ matrix representations $r_n(\epsilon_k)$ through their differential equations (3.19) which have been tested to preserve eq. (4.64) for a wide range of k and n [1]. For the analogous $n! \times n!$ matrices $r_{0,n}(\epsilon_k)$ seen in the KZB system (4.52) of the augmented $\mathbf{Z}_{0,n}^\tau$, we conjecture that they furnish another representation of the derivation algebra. This conjecture not only applies to eq. (4.64),

$$\text{conjecture :} \quad \text{ad}_{r_{0,n}(\epsilon_0)}^{k-1}(r_{0,n}(\epsilon_k)) = 0, \quad (4.65)$$

but also to the additional depth-two relations in the derivation algebra besides eq. (4.64) [77, 78, 19] such as

$$\begin{aligned} 0 &= [\epsilon_{10}, \epsilon_4] - 3[\epsilon_8, \epsilon_6], \\ 0 &= 2[\epsilon_{14}, \epsilon_4] - 7[\epsilon_{12}, \epsilon_6] + 11[\epsilon_{10}, \epsilon_8]. \end{aligned} \quad (4.66)$$

Given that the Schwarz integrability condition (4.55) does not allow to derive constraints for commutators $[\epsilon_k, \epsilon_\ell]$, we have supported our conjecture through numerous successful case-by-case tests using the representations $r_{0,n}(\epsilon_k)$ only. However, the depth-three relations in the derivation algebra starting from

$$\begin{aligned} 0 &= 80[\epsilon_{12}, [\epsilon_4, \epsilon_0]] + 16[\epsilon_4, [\epsilon_{12}, \epsilon_0]] - 250[\epsilon_{10}, [\epsilon_6, \epsilon_0]] \\ &\quad - 125[\epsilon_6, [\epsilon_{10}, \epsilon_0]] + 280[\epsilon_8, [\epsilon_8, \epsilon_0]] - 462[\epsilon_4, [\epsilon_4, \epsilon_8]] - 1725[\epsilon_6, [\epsilon_6, \epsilon_4]] \end{aligned} \quad (4.67)$$

do not seem to carry over to the $r_{0,n}(\epsilon_k)$, e.g. eq. (4.67) with $\epsilon_k \rightarrow r_{0,n}(\epsilon_k)$ is already violated at $n = 2$. Instead, eq. (4.67) and some of its higher-weight analogues [78, 19] have been checked to hold upon assigning

$$\epsilon_k \rightarrow \begin{cases} r_{0,n}(\epsilon_0) & : k = 0, \\ r_{0,n}(\epsilon_k) + r_{0,n}(x_{k-1}) & : k \geq 4. \end{cases} \quad (4.68)$$

The deformation in the second line resonates with the additional appearance of $b_k = x_{k-1}$ in the augmented differential eq. (4.52) with respect to τ compared to the non-augmented one in eq. (3.18). As we will see in eq. (5.69), the combination $r_{0,n}(\epsilon_k) + r_{0,n}(x_{k-1})$ in eq. (4.68) appears naturally when relating the representations $r_{0,n}(\epsilon_k)$ and $r_n(\epsilon_k)$ of the derivations. Note that depth-two relations such as eq. (4.66) were tested to hold for both assignments eq. (4.68) and $\epsilon_k \rightarrow r_{0,n}(\epsilon_k)$.

4.5 Total differential of $Z_{0,n}^\tau$ integrals

In summary of the differential equations in sections 4.2, 4.3 and as a way of manifesting the Schwarz integrability conditions, we will now spell out the total differential of the $Z_{0,n}^\tau$ -integrals (4.6), to bring the differential of $Z_{0,n}^\tau$ into the form (3.3). After eliminating the $r_{0,n}(b_k)$, the total differential $d = dz_0 \partial_{z_0} + d\tau \partial_\tau$ following from the KZB system (4.52) takes the form

$$dZ_{0,n}^\tau = \left\{ dz_0 r_{0,n}(x_0) - \frac{d\tau}{2\pi i} r_{0,n}(\epsilon_0) - \frac{d\tau}{2\pi i} \sum_{k=4}^{\infty} (k-1) G_k r_{0,n}(\epsilon_k) + \sum_{k=1}^{\infty} \psi_{01}^{(k)} r_{0,n}(x_k) \right\} Z_{0,n}^\tau, \quad (4.69)$$

where the characteristic combinations

$$\psi_{01}^{(k)} = dz_0 f_{01}^{(k)} + \frac{k d\tau}{2\pi i} f_{01}^{(k+1)} \quad (4.70)$$

in the last term of eq. (4.69) agree with the closed one-forms $\omega_{ij}^{(k)}$ in eqn. (3.15) of [84] since $z_0, z_1 \in \mathbb{R}$. The same one-forms $\psi_{01}^{(k)}$ in eq. (4.70) appear when the z_0 - and τ -derivatives (4.26) and (4.42) are combined to the following explicit form of the total differential:

$$\begin{aligned} dZ_{0,n}^\tau((1, 2, 3, \dots, p), (0, n, n-1, \dots, p+1)) &= \left\{ dz_0 \left[\sum_{j=p+1}^n s_{j,123\dots p} \partial_{\eta_j} - \sum_{j=2}^p s_{j,0n(n-1)\dots p+1} \partial_{\eta_j} \right] \right. \\ &+ \frac{d\tau}{2\pi i} \left[\frac{1}{2} \sum_{j=2}^n (s_{0j} + s_{1j}) \partial_{\eta_j}^2 + \frac{1}{2} \sum_{2 \leq i < j} s_{ij} (\partial_{\eta_i} - \partial_{\eta_j})^2 - 2\zeta_2 s_{012\dots n} \right] \\ &- s_{12\dots p, 0n(n-1)\dots(p+1)} \psi_{01}^{(1)} \left. \right\} Z_{0,n}^\tau((1, 2, 3, \dots, p), (0, n, n-1, \dots, p+1)) \\ &+ \sum_{j=2}^p \left\{ \left(-\frac{dz_0}{\eta_{j(j+1)\dots p}} - \frac{d\tau}{2\pi i \eta_{j(j+1)\dots p}^2} + \sum_{k=1}^{\infty} (-\eta_{j(j+1)\dots p})^{k-1} \psi_{01}^{(k)} \right) \right. \\ &\quad \times Z_{0,n}^\tau((1, 2, \dots, j-1), (S[0n(n-1)\dots(p+1), j(j+1)\dots p])) \\ &\quad \left. - \frac{d\tau}{2\pi i} \wp(\eta_{j(j+1)\dots p}) Z_{0,n}^\tau((0, n, n-1, \dots, p+1), (S[12\dots(j-1), j(j+1)\dots p])) \right\} \\ &+ \sum_{j=p+1}^n \left\{ \left(\frac{dz_0}{\eta_{j(j-1)\dots p+1}} - \frac{d\tau}{2\pi i \eta_{j(j-1)\dots p+1}^2} + \sum_{k=1}^{\infty} (\eta_{j(j-1)\dots p+1})^{k-1} \psi_{01}^{(k)} \right) \right. \\ &\quad \times Z_{0,n}^\tau((0, n, \dots, j+1), (S[12\dots p, j(j-1)\dots p+1])) \\ &\quad \left. - \frac{d\tau}{2\pi i} \wp(\eta_{j(j-1)\dots p+1}) Z_{0,n}^\tau((1, 2, \dots, p), (S[0n\dots j+1, j(j-1)\dots p+1])) \right\}. \quad (4.71) \end{aligned}$$

In the third and sixth line from below, we have used that

$$\Omega_{01}^\pm(\eta) \frac{d\tau}{2\pi i} + \Omega_{01}(\pm\eta) dz_0 = \pm \frac{dz_0}{\eta} - \frac{d\tau}{2\pi i \eta^2} + \sum_{k=1}^{\infty} (\pm\eta)^{k-1} \psi_{01}^{(k)}. \quad (4.72)$$

The fact that the $f_{01}^{(k \neq 0)}$ on the right-hand side of eq. (4.71) combine to $\psi_{01}^{(k)}$ manifests the equality of the operators $r_{0,n}(b_k)$ and $r_{0,n}(x_{k-1})$ in the KZB system (4.52). Based on the total differential eq. (4.69), the formalism of [84] can be used to obtain the coaction of the augmented Z^τ -integrals, also see section 7.2 of [1] for the coaction of plain Z^τ -integrals (2.26).

5 Identification and translation

While z_0 - and τ -derivatives of the integrals $Z_{0,n}^\tau$ have been discussed in full generality in the previous section, let us now compare the two resulting approaches by investigating their boundary conditions, limits and solutions, respectively. As a guiding principle, we will explore how the representations r_n and $r_{0,n}^E$ of the algebra generators¹⁸ ϵ_k and x_k in eqs. (3.19) and (3.35), respectively, are related to each other and to the representations $r_{0,n}(\epsilon_k)$ in eqs. (4.14) and (4.37) above.

5.1 Overview

Boundary values $\mathbf{C}_{0,n}^\tau$ and $\mathbf{C}_{1,n}^\tau$ of $\mathbf{Z}_{0,n}^\tau$ for the limits $z_0 \rightarrow 0$ and $z_0 \rightarrow 1$, respectively, are particularly important since they allow for an explicit expansion of the integrals \mathbf{Z}_n^τ in α' using the elliptic KZB associator. Simultaneously, it is those boundary values, which finally allow to find the link between the matrices $r_n(\epsilon_k)$, $r_{0,n}^E(x_k)$, $r_{0,n}(\epsilon_k)$ and $r_{0,n}(x_k)$. Due to the poles at $z_0 = 0$ and $z_0 = 1$ of $f_{01}^{(1)}$ in the differential equation (4.14), these limits are singular. The regularization leading to the corresponding non-vanishing finite values will be derived and related to the genus-zero and genus-one Z -integrals Z_n^{tree} and Z_n^τ , respectively, in this section.

The boundary values $\mathbf{C}_{0,n}^\tau$ and $\mathbf{C}_{1,n}^\tau$ to be considered here are the finite-length cousins of the infinitely long boundary vectors $\mathbf{C}_{0,n}^E$ and $\mathbf{C}_{1,n}^E$ in eq. (3.36) for the genus-one Selberg integrals. The main results to be derived below are the expressions

$$\begin{aligned} \mathbf{C}_{0,n}^\tau &= -e^{s_{012\dots n}\omega(1,0|\tau)} U_n^{\text{BCJ}} \mathbf{Z}_{n+2}^{\text{tree}}, \\ P_n^\omega \mathbf{C}_{1,n}^\tau &= e^{s_{01}\omega(1,0|\tau)} \mathbf{Z}_n^\tau \end{aligned} \quad (5.1)$$

in terms of bases of genus-zero integrals $\mathbf{Z}_{n+2}^{\text{tree}}$ in eq. (2.9) and genus-one integrals \mathbf{Z}_n^τ in eq. (2.26). The entries of the $n! \times (n-1)!$ matrices U_n^{BCJ} and $(n-1)! \times n!$ matrices P_n^ω are rational functions of the s_{ij} with $0 \leq i < j \leq n$ and will be defined in the discussions around eqs. (5.15) and (5.42), respectively.

Based on the associator relation

$$\mathbf{C}_{1,n}^\tau = r_{0,n}(\Phi^\tau(x_k)) \mathbf{C}_{0,n}^\tau \quad (5.3)$$

adapted to the $n! \times n!$ matrices $r_{0,n}(x_k)$ constructed in section 4.2, eqs. (5.1) and (5.2) connect the genus-one integrals \mathbf{Z}_n^τ with their genus-zero counterparts $\mathbf{Z}_{n+2}^{\text{tree}}$,

$$\mathbf{Z}_n^\tau = -e^{(s_{012\dots n} - s_{01})\omega(1,0|\tau)} P_n^\omega r_{0,n}(\Phi^\tau(x_k)) U_n^{\text{BCJ}} \mathbf{Z}_{n+2}^{\text{tree}}. \quad (5.4)$$

Using the expansion of the elliptic KZB associator [80],

$$r_{0,n}(\Phi^\tau(x_k)) = \sum_{w \geq 0} \sum_{k_1, \dots, k_w \geq 0} r_{0,n}(x_{k_1} \dots x_{k_w}) \omega(k_w, \dots, k_1 | \tau), \quad (5.5)$$

each term in the expansion of the genus-one integrals in α' and η_j can be obtained via elementary operations. Eq. (5.4) is the generating-function reformulation of the method in [2], where the matrices $r_{0,n}(x_k)$ are now finite dimensional.

The application of the formalism to integrals Z_n^τ with kinematic poles (i.e. factors of $f_{ij}^{(1)}$ in the integrand) have not been investigated in ref. [2]. However, when doing so using the method

¹⁸Sometimes these generators are referred to as *letters* and their respective entirety as *alphabets*.

of ref. [2], the matrices P_n^{u} allow to project on the desired configuration-space integrals in the same way as they do in the language using generating functions in the current paper.

5.2 Lower boundary value $\mathbf{C}_{0,n}^\tau$ in the z_0 -language

In this subsection, we will derive the expression (5.1) for the lower boundary value $\mathbf{C}_{0,n}^\tau$ which is defined as the regularized limit

$$\mathbf{C}_{0,n}^\tau = \lim_{z_0 \rightarrow 0} (-2\pi i z_0)^{-r_{0,n}(x_1)} \mathbf{Z}_{0,n}^\tau. \quad (5.6)$$

The vector $\mathbf{Z}_{0,n}^\tau$ has been introduced in eq. (4.3), and $r_{0,n}(x_1)$ is the representation of the letter x_1 appearing in the KZB equation (4.14) along with the singular $f_{01}^{(1)}$. Here we are going to derive the main mechanism necessary for evaluating eq. (5.6).

5.2.1 Recovering Parke–Taylor integrals

Let us start by examining the limiting behaviour of the Koba–Nielsen factor: following the reasoning of ref. [2] and using eq. (2.22), we find by the change of variables $z_i = z_0 x_i$ and recalling that $0 < z_i < z_0$ for $1 \leq i \leq n$, that the Koba–Nielsen factor degenerates as follows in the limit $z_0 \rightarrow 0$:

$$\begin{aligned} \text{KN}_{012\dots n}^\tau &= (-2\pi i z_0)^{-s_{012\dots n}} e^{s_{012\dots n} \omega(1,0|\tau)} \prod_{1 \leq i < j \leq n} x_{ji}^{-s_{ij}} \prod_{k=2}^n (1-x_k)^{-s_{0k}} + \mathcal{O}(z_0^{-s_{012\dots n}+1}) \\ &= (-2\pi i z_0)^{-s_{012\dots n}} e^{s_{012\dots n} \omega(1,0|\tau)} \text{KN}_{12\dots n+2}^{\text{tree}} + \mathcal{O}(z_0^{-s_{012\dots n}+1}). \end{aligned} \quad (5.7)$$

We have identified

$$x_{n+1} = x_0 = 1, \quad s_{j,n+1} = s_{0j} \quad (5.8)$$

and $\text{KN}_{12\dots n+2}^{\text{tree}}$ is the $(n+2)$ -point tree-level Koba–Nielsen factor (2.6) with the fixed variables

$$(x_1, x_{n+1}, x_{n+2}) = (0, 1, \infty). \quad (5.9)$$

The asymptotics of the functions $f^{(k)}(z|\tau)$ with z approaching zero from the positive real line

$$f^{(k)}(z|\tau) = \begin{cases} \frac{1}{z} + \mathcal{O}(z) & \text{if } k = 1, \\ \mathcal{O}(1) & \text{otherwise,} \end{cases} \quad (5.10)$$

determine the asymptotic behaviour of the Kronecker–Eisenstein series for $z \rightarrow 0$

$$\Omega(z, \eta|\tau) = \frac{1}{z} + \mathcal{O}(1). \quad (5.11)$$

Using this equation, the integrand in the augmented genus-one Z -integrals in eq. (4.6) without the Koba–Nielsen factor degenerates to the tree-level integrand

$$\lim_{z_0 \rightarrow 0} \prod_{k=2}^n dz_k \varphi^\tau(1, A) \varphi^\tau(0, B) = \prod_{k=2}^n dx_k \left[\frac{1}{(-x_{a_1})} \prod_{t=2}^p \frac{1}{x_{a_{t-1}, a_t}} \right] \left[\frac{1}{1-x_{b_1}} \prod_{r=2}^q \frac{1}{x_{b_{r-1}, b_r}} \right], \quad (5.12)$$

where the limit is performed at fixed x_i in $z_i = z_0 x_i$, and $A = (a_1, a_2, \dots, a_p)$, $B = (b_1, b_2, \dots, b_q)$ are again disjoint sequences without repetitions such that $A \cup B = \{2, 3, \dots, n\}$. Note that only the contribution from the simple poles of the Kronecker–Eisenstein series in eq. (5.11) survives the change of variables $dz_i = z_0 dx_i$ followed by the limit $z_0 \rightarrow 0$ in the product eq. (5.12).

Combining eqs. (5.7) and (5.12), we find that the asymptotic behaviour of the augmented Z^τ -integrals eq. (4.6) yields genus-zero integrals (2.7) of Parke–Taylor type,

$$\lim_{z_0 \rightarrow 0} (-2\pi i z_0)^{s_{012\dots n}} Z_{0,n}^\tau((1, A), (0, B)) = -(-1)^{|B|} e^{s_{012\dots n} \omega(1,0|\tau)} Z_{n+2}^{\text{tree}}(\mathbb{I}_{n+2}|1, A, n+2, \tilde{B}, n+1), \quad (5.13)$$

with the identification eq. (5.8) of Mandelstam invariants and $|B| = q$ denoting the number of labels in B . The integrals Z_{n+2}^{tree} have been identified by matching eq. (5.12) with their expression (2.9) in the SL_2 -frame eq. (5.9). In particular, eq. (5.13) at $B = \emptyset$ specializes to

$$\lim_{z_0 \rightarrow 0} (-2\pi i z_0)^{s_{012\dots n}} Z_{0,n}^\tau(1, A) = -e^{s_{012\dots n} \omega(1,0|\tau)} Z_{n+2}^{\text{tree}}(\mathbb{I}_{n+2}|1, A, n+2, n+1), \quad (5.14)$$

for $A = (a_2, a_3, \dots, a_n)$ a permutation of $(2, 3, \dots, n)$. Therefore, the first $(n-1)!$ entries of the vector $\mathbf{Z}_{0,n}^\tau$ degenerate to the BCJ basis $\mathbf{Z}_{n+2}^{\text{tree}} = Z_{n+2}^{\text{tree}}(\mathbb{I}_{n+2}|1, \sigma, n+2, n+1)$, $\sigma \in \mathcal{P}(2, 3, \dots, n)$ of $(n+2)$ -point genus-zero integrals at fixed integration domain \mathbb{I}_{n+2} , cf. eq. (2.8). The remaining Parke–Taylor orderings in eq. (5.13) descending from $Z_{0,n}^\tau((1, A), (0, B))$ at $B \neq \emptyset$ can be reduced to the $(n-1)!$ basis integrals $Z_{n+2}^{\text{tree}}(\mathbb{I}_{n+2}|1, A, n+2, n+1)$ in eq. (5.14) via BCJ relations [37]. Their unique decomposition into an $(n-1)!$ BCJ basis define the entries of the following $n! \times (n-1)!$ matrix U_n^{BCJ} indexed by permutations $\rho \in S_{n-1}$:

$$\begin{pmatrix} Z_{n+2}^{\text{tree}}(\mathbb{I}_{n+2}|1, \rho(2, 3, \dots, n), n+2, n+1) \\ -Z_{n+2}^{\text{tree}}(\mathbb{I}_{n+2}|1, \rho(2, 3, \dots, n-1), n+2, \rho(n), n+1) \\ Z_{n+2}^{\text{tree}}(\mathbb{I}_{n+2}|1, \rho(2, 3, \dots, n-2), n+2, \rho(n-1, n), n+1) \\ \dots \\ (-1)^n Z_{n+2}^{\text{tree}}(\mathbb{I}_{n+2}|1, \rho(2), n+2, \rho(3, \dots, n), n+1) \\ -(-1)^n Z_{n+2}^{\text{tree}}(\mathbb{I}_{n+2}|1, n+2, \rho(2, 3, \dots, n), n+1) \end{pmatrix} = U_n^{\text{BCJ}} \mathbf{Z}_{n+2}^{\text{tree}}. \quad (5.15)$$

Given the order of the $Z_{0,n}^\tau((1, A), (0, B))$ integrals in the $\mathbf{Z}_{0,n}^\tau$ -vector eq. (4.3), the degeneration (5.13) and the BCJ basis decomposition (5.15) yield

$$\lim_{z_0 \rightarrow 0} (-2\pi i z_0)^{s_{012\dots n}} \mathbf{Z}_{0,n}^\tau = -e^{s_{012\dots n} \omega(1,0|\tau)} \begin{pmatrix} \mathbf{Z}_{n+2}^{\text{tree}} \\ * \end{pmatrix} = -e^{s_{012\dots n} \omega(1,0|\tau)} U_n^{\text{BCJ}} \mathbf{Z}_{n+2}^{\text{tree}}. \quad (5.16)$$

In the second step, we have used that the upper block of size $(n-1)! \times (n-1)!$ in U_n^{BCJ} is the identity matrix.

5.2.2 The maximal $r_{0,n}(x_1)$ eigenvalue

In order to derive our earlier claim eq. (5.1) for the lower boundary value, we will show how the finite value $\lim_{z_0 \rightarrow 0} (-2\pi i z_0)^{s_{01\dots n}} \mathbf{Z}_{0,n}^\tau$ in eq. (5.16) emerges from the regularized boundary value $\mathbf{C}_{0,n}^\tau$ in eq. (5.6). The key observation to be demonstrated below is that the matrix $r_{0,n}(x_1)$ in the exponent of eq. (5.6) can be set to its eigenvalue $-s_{012\dots n}$ when acting on the $z_0 \rightarrow 0$ asymptotics of $\mathbf{Z}_{0,n}^\tau$. With the asymptotic result (5.16), the task is therefore to show that

$$(-2\pi i z_0)^{-r_{0,n}(x_1)} U_n^{\text{BCJ}} = (-2\pi i z_0)^{s_{012\dots n}} U_n^{\text{BCJ}}, \quad (5.17)$$

which will turn out to be independent on the BCJ basis vector $\mathbf{Z}_{n+2}^{\text{tree}}$ that U_n^{BCJ} acts on.

Our proof of eq. (5.17) is based on the continuity of $(2\pi iz_0)^{s_{012\dots n}} 2\pi i \partial_\tau \mathbf{Z}_{0,n}^\tau$ at $z_0 = 0$ due to the absence of singular terms in eq. (4.45). We can therefore equate the two orders of performing the limit $z_0 \rightarrow 0$ and the τ -derivative.

- On the one hand, eq. (5.16) can be differentiated with respect to τ *after* taking the $z_0 \rightarrow 0$ limit, which only acts via $2\pi i \partial_\tau \omega(1, 0|\tau) = G_2 - 2\zeta_2$ and yields

$$2\pi i \partial_\tau \lim_{z_0 \rightarrow 0} (-2\pi iz_0)^{s_{012\dots n}} \mathbf{Z}_{0,n}^\tau = s_{012\dots n} (G_2 - 2\zeta_2) e^{s_{012\dots n} \omega(1,0|\tau)} U_n^{\text{BCJ}} \mathbf{Z}_{n+2}^{\text{tree}}. \quad (5.18)$$

- On the other hand, exchanging the limit and the partial derivative in eq. (5.18) leads – according to eq. (4.45) – to the identity

$$\begin{aligned} & \lim_{z_0 \rightarrow 0} (-2\pi iz_0)^{s_{012\dots n}} 2\pi i \partial_\tau \mathbf{Z}_{0,n}^\tau \\ &= \left(-r_{0,n}(\epsilon_0) - G_2 r_{0,n}(x_1) + \sum_{k=4}^{\infty} (1-k) G_k (r_{0,n}(\epsilon_k) + r_{0,n}(x_{k-1})) \right) \\ & \quad \times e^{s_{012\dots n} \omega(1,0|\tau)} U_n^{\text{BCJ}} \mathbf{Z}_{n+2}^{\text{tree}}, \end{aligned} \quad (5.19)$$

where we have used that $r_{0,n}(b_k) = r_{0,n}(x_{k-1})$ (cf. eq. (4.56)) and that for $k \geq 2$ (and $z_0 \in \mathbb{R}$ in case of $k = 2$)

$$\lim_{z_0 \rightarrow 0} f_{01}^{(k)} = -G_k. \quad (5.20)$$

Since the derivative $(2\pi iz_0)^{s_{012\dots n}} 2\pi i \partial_\tau \mathbf{Z}_{0,n}^\tau$ is continuous at $z_0 = 0$, eqs. (5.18) and (5.19) have to agree. Comparing the coefficients of G_k in the two equations leads to the eigenvalue equations:

$$\begin{aligned} r_{0,n}(x_1) U_n^{\text{BCJ}} &= -s_{01\dots n} U_n^{\text{BCJ}}, \\ r_{0,n}(\epsilon_0) U_n^{\text{BCJ}} &= 2\zeta_2 s_{01\dots n} U_n^{\text{BCJ}}, \\ (r_{0,n}(\epsilon_k) + r_{0,n}(x_{k-1})) U_n^{\text{BCJ}} &= 0, \quad k \geq 4. \end{aligned} \quad (5.21)$$

These equations imply that the columns of U_n^{BCJ} are eigenvectors of $r_{0,n}(x_1)$ and $r_{0,n}(\epsilon_0)$ for the eigenvalues $-s_{012\dots n}$ and $2\zeta_2 s_{012\dots n}$, respectively. This proves the lemma (5.17) and ultimately the main claim (5.1) of this subsection. Moreover, we see that the representations $r_{0,n}(\epsilon_0)$ and $r_{0,n}(x_1)$ as well as $r_{0,n}(\epsilon_k)$ and $r_{0,n}(x_{k-1})$ for $k = 4, 6, \dots$ acting on U_n^{BCJ} and thus, on the lower boundary value, are equivalent up to constant factors.

5.2.3 Two-point example

Let us approve the above findings on the two-point example $\mathbf{Z}_{0,2}^\tau$ from eq. (4.29). The finite part at $z_0 = 0$ according to eq. (5.13) and $s_{23} = s_{02}$ is given by

$$\begin{aligned} \lim_{z_0 \rightarrow 0} (-2\pi iz_0)^{s_{012}} \mathbf{Z}_{0,2}^\tau &= e^{s_{012} \omega(1,0|\tau)} \begin{pmatrix} -Z_4^{\text{tree}}(\mathbb{I}_4|1, 2, 4, 3) \\ Z_4^{\text{tree}}(\mathbb{I}_4|1, 4, 2, 3) \end{pmatrix} \\ &= e^{s_{012} \omega(1,0|\tau)} \begin{pmatrix} \frac{1}{s_{12}} \\ -\frac{1}{s_{02}} \end{pmatrix} \frac{\Gamma(1-s_{12})\Gamma(1-s_{02})}{\Gamma(1-s_{12}-s_{02})} \end{aligned} \quad (5.22)$$

which can be rewritten using the following BCJ matrix in eq. (5.16)

$$\lim_{z_0 \rightarrow 0} (-2\pi i z_0)^{s_{012}} \mathbf{Z}_{0,2}^\tau = -e^{s_{012}\omega(1,0|\tau)} U_2^{\text{BCJ}} Z_4^{\text{tree}}(\mathbb{I}_4|1, 2, 4, 3), \quad U_2^{\text{BCJ}} = \begin{pmatrix} 1 \\ -\frac{s_{12}}{s_{02}} \end{pmatrix}. \quad (5.23)$$

The eigenvalue equations (5.21) can immediately be checked using the explicit form of the $r_{0,2}(\cdot)$ in eqs. (4.31) and (4.47). In particular,

$$r_{0,2}(x_1) U_2^{\text{BCJ}} = -s_{012} U_2^{\text{BCJ}} \quad (5.24)$$

together with eq. (5.23) lead to

$$\begin{aligned} \mathbf{C}_{0,2}^\tau &= \lim_{z_0 \rightarrow 0} (-2\pi i z_0)^{-r_{0,2}(x_1)} \mathbf{Z}_{0,2}^\tau \\ &= -e^{s_{012}\omega(1,0|\tau)} U_2^{\text{BCJ}} Z_4^{\text{tree}}(\mathbb{I}_4|1, 2, 4, 3) \\ &= e^{s_{012}\omega(1,0|\tau)} \begin{pmatrix} \frac{1}{s_{12}} \\ -\frac{1}{s_{02}} \end{pmatrix} \frac{\Gamma(1-s_{12})\Gamma(1-s_{02})}{\Gamma(1-s_{12}-s_{02})}. \end{aligned} \quad (5.25)$$

Note that the other two eigenvalue equations of (5.21) are also straightforwardly checked via eqs. (4.31) and (4.47).

5.2.4 Three-point example

At three points, the explicit form of $\mathbf{Z}_{0,3}^\tau$ can be found in eq. (4.32), and its finite part at $z_0 = 0$ is determined as follows by eq. (5.13):

$$\lim_{z_0 \rightarrow 0} (-2\pi i z_0)^{s_{0123}} \mathbf{Z}_{0,3}^\tau = e^{s_{0123}\omega(1,0|\tau)} \begin{pmatrix} -Z_5^{\text{tree}}(\mathbb{I}_5|1, 2, 3, 5, 4) \\ -Z_5^{\text{tree}}(\mathbb{I}_5|1, 3, 2, 5, 4) \\ Z_5^{\text{tree}}(\mathbb{I}_5|1, 2, 5, 3, 4) \\ Z_5^{\text{tree}}(\mathbb{I}_5|1, 3, 5, 2, 4) \\ -Z_5^{\text{tree}}(\mathbb{I}_5|1, 5, 2, 3, 4) \\ -Z_5^{\text{tree}}(\mathbb{I}_5|1, 5, 3, 2, 4) \end{pmatrix}. \quad (5.26)$$

BCJ relations among five-point disk integrals give rise to the following matrix U_3^{BCJ} in eq. (5.15),

$$U_3^{\text{BCJ}} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ -\frac{(s_{13}+s_{23})}{s_{03}} & -\frac{s_{13}}{s_{03}} \\ -\frac{s_{12}}{s_{02}} & -\frac{(s_{12}+s_{23})}{s_{02}} \\ \frac{s_{12}(s_{03}+s_{13}+s_{23})}{s_{03}s_{023}} & \frac{(s_{12}-s_{03})s_{13}}{s_{03}s_{023}} \\ \frac{s_{12}(s_{13}-s_{02})}{s_{02}s_{023}} & \frac{s_{13}(s_{02}+s_{12}+s_{23})}{s_{02}s_{023}} \end{pmatrix}, \quad (5.27)$$

which can be checked to obey the eigenvalue equations (5.21) using the expressions for $r_{0,3}(\cdot)$ from sections 4.2.4 and 4.3.3. By eqs. (5.15) and (5.26), we arrive at

$$\begin{aligned} \mathbf{C}_{0,3}^\tau &= \lim_{z_0 \rightarrow 0} (-2\pi i z_0)^{-r_{0,3}(x_1)} \mathbf{Z}_{0,3}^\tau \\ &= -e^{s_{0123}\omega(1,0|\tau)} U_3^{\text{BCJ}} \begin{pmatrix} Z_5^{\text{tree}}(\mathbb{I}_5|1, 2, 3, 5, 4) \\ Z_5^{\text{tree}}(\mathbb{I}_5|1, 3, 2, 5, 4) \end{pmatrix}. \end{aligned} \quad (5.28)$$

5.3 Upper boundary value $\mathbf{C}_{1,n}^\tau$ in the z_0 -language

In order to derive the claim (5.2) for the upper boundary value $\mathbf{C}_{1,n}^\tau$, one will have to evaluate

$$\mathbf{C}_{1,n}^\tau = \lim_{z_0 \rightarrow 1} (-2\pi i(1-z_0))^{-r_{0,n}(x_1)} \mathbf{Z}_{0,n}^\tau. \quad (5.29)$$

Similar to the procedure in the last subsection, we will evaluate the limit $z_0 \rightarrow 1$ separately for the Koba-Nielsen part and the remainder of the integrand, before commenting on the action of the matrix representation $r_{0,n}$ in the exponent of the regulating factor.

5.3.1 Recovering genus-one integrands

Following the same steps as in ref. [2], the Koba-Nielsen factor degenerates for $z_0 \rightarrow 1$ along the unit interval as follows:

$$\text{KN}_{012\dots n} = (-2\pi i(1-z_0))^{-s_{01}} e^{s_{01}\omega(1,0|\tau)} \text{KN}_{12\dots n}^\tau|_{\tilde{s}_{ij}} + \mathcal{O}((1-z_0)^{-s_{01}+1}), \quad (5.30)$$

where

$$\text{KN}_{12\dots n}^\tau|_{\tilde{s}_{ij}} = \prod_{1 \leq i < j \leq n} e^{-\tilde{s}_{ij} G_{ij}^\tau} \quad (5.31)$$

is the n -point Koba-Nielsen factor with shifted Mandelstam invariants \tilde{s}_{ij} with $i < j$ given by

$$\tilde{s}_{ij} = \begin{cases} s_{1j} + s_{0j} & \text{if } i = 1, \\ s_{ij} & \text{otherwise.} \end{cases} \quad (5.32)$$

The Kronecker-Eisenstein chains in the integrand of $Z_{0,n}^\tau((1,A),(0,B))$ are regular for $z_0 \rightarrow 1$ since $0 \notin A$ and $1 \notin B$, and, using the periodicity (2.19) of the Kronecker-Eisenstein series and the shuffle identity (A.8), given by

$$\lim_{z_0 \rightarrow 1} \varphi^\tau(1,A)\varphi^\tau(0,B) = \varphi^\tau(1,A \sqcup B). \quad (5.33)$$

In addition to the higher-order terms in eq. (5.30), there is another subtlety in taking the limit $\lim_{z_0 \rightarrow 1} Z_{0,n}^\tau((1,A),(0,B))$: as discussed in appendix E, further subleading terms will appear at certain orders in $(1-z_0)^{-s_{01}+\Delta}$ for some Δ composed of further s_{ij} with $\text{Re}(\Delta) > 0$. They originate from the difference between the integration domain $\int_0^{z_0}$ entering the definition of $Z_{0,n}^\tau((1,A),(0,B))$ and the larger integration domain \int_0^1 of the integrals Z_n^τ . On the one hand, the interval $(z_0, 1)$ distinguishing the integration domains of $Z_{0,n}^\tau((1,A),(0,B))$ and Z_n^τ becomes arbitrarily small as $z_0 \rightarrow 1$. On the other hand, the poles of $\varphi^\tau(1,A)\varphi^\tau(0,B)$ lead to $n-1$ subleading contributions to the integral over $(z_0, 1)$ due to the merging of $k+2$ punctures $z_0 < z_{n-k+1} < \dots < z_n < 1 \cong z_1$ for $0 < k < n$ as $z_0 \rightarrow 1$. Still, these subleading contributions scale as $(-2\pi i(1-z_0))^{-s_{01}n-k+1\dots n}$, where according to eq. (2.3) the exponent has a real part larger than $-s_{01}$. For the boundary value $\mathbf{C}_{1,n}^\tau$ in (5.29), these finite terms only pose a problem in an eigenspace of $-r_{0,n}(x_1)$ where the associated eigenvalue is larger than $-s_{01}$. By multiplication with $(-2\pi i(1-z_0))^{s_{01}}$ and taking the limit $z_0 \rightarrow 1$, the lowest order contribution can be isolated. The corresponding non-vanishing value is determined by combining eqs. (5.30)

and (5.33):

$$\lim_{z_0 \rightarrow 1} (-2\pi i(1-z_0))^{s_{01}} Z_{0,n}^\tau((1, A), (0, B)) = e^{s_{01}\omega(1,0|\tau)} Z_n^\tau(\mathbb{I}_n|1, (A \sqcup B))|_{\tilde{s}_{ij}}. \quad (5.34)$$

The right-hand side involves the genus-one integrals (2.26) with the shifted Mandelstam variables \tilde{s}_{ij} from eq. (5.32) in the Koba–Nielsen factor. The special cases of eq. (5.34) with $B = \emptyset$ yield a particularly simple form for the first $(n-1)!$ components of,

$$\lim_{z_0 \rightarrow 1} (-2\pi i(1-z_0))^{s_{01}} \mathbf{Z}_{0,n}^\tau = e^{s_{01}\omega(1,0|\tau)} \begin{pmatrix} \mathbf{Z}_n^\tau |_{\tilde{s}_{ij}} \\ * \end{pmatrix}, \quad (5.35)$$

where \mathbf{Z}_n^τ defined in eq. (3.13) comprises $(n-1)!$ basis integrals $Z_n^\tau(\mathbb{I}_n|1, A)$. Also the remaining components of eq. (5.34) fall into this basis: evaluating the shuffles on the right-hand side of eq. (5.34) defines a $n! \times (n-1)!$ matrix U_n^\sqcup with entries in $\{0, 1\}$

$$\begin{pmatrix} Z_n^\tau(\mathbb{I}_n|1, \rho(2, 3, \dots, n)) \\ Z_n^\tau(\mathbb{I}_n|1, [\rho(2, 3, \dots, n-1) \sqcup \rho(n)]) \\ Z_n^\tau(\mathbb{I}_n|1, [\rho(2, 3, \dots, n-2) \sqcup \rho(n-1, n)]) \\ \dots \\ Z_n^\tau(\mathbb{I}_n|1, [\rho(2) \sqcup \rho(n, \dots, 3)]) \\ Z_n^\tau(\mathbb{I}_n|1, \rho(n, \dots, 3, 2)) \end{pmatrix} = U_n^\sqcup \mathbf{Z}_n^\tau \quad (5.36)$$

such that

$$\lim_{z_0 \rightarrow 1} (-2\pi i(1-z_0))^{s_{01}} \mathbf{Z}_{0,n}^\tau = e^{s_{01}\omega(1,0|\tau)} U_n^\sqcup \mathbf{Z}_n^\tau |_{\tilde{s}_{ij}}. \quad (5.37)$$

Note that the shuffle decomposition (5.36) of genus-one integrals in the context of the boundary value $\mathbf{C}_{1,n}^\tau$ is the analogue of the BCJ decomposition (5.15) relevant for the genus-zero integrals in $\mathbf{C}_{0,n}^\tau$. In particular, both $n! \times (n-1)!$ matrices U_n^{BCJ} and U_n^\sqcup feature a unit matrix within their upper $(n-1)! \times (n-1)!$ block.

5.3.2 The minimal $r_{0,n}(x_1)$ eigenvalue

What remains to be discussed here is the regulating factor: similar to the previous subsection, it turns out that the finite value in eq. (5.37) emerges from the regularized boundary value $\mathbf{C}_{1,n}^\tau$. However, recovering the genus-one Z^τ -integrals is more subtle than the tree-level integrals from $\mathbf{C}_{0,n}^\tau$, since the validity of eq. (5.34), i.e. the absence of rest terms, relies on the exponent s_{01} of the regulating factor $(-2\pi i(1-z_0))^{s_{01}}$ and would generally fail if there were further contributions s_{ij} . Therefore, one has to make sure that the dominating eigenvalue of $r_{0,n}(x_1)$ in $\mathbf{C}_{1,n}^\tau$, c.f. eq. (5.29), is $-s_{01}$, i.e. the eigenvalue with the minimal real part as opposed to the eigenvalue $-s_{012\dots n}$ with maximal real part in the calculation (5.17). This can be achieved by employing a projection to the eigenspace of $-s_{01}$ as follows: interchanging limit and τ -derivative of $(-2\pi i(1-z_0))^{s_{01}} \mathbf{Z}_{0,n}^\tau$ using the continuity of the latter leads again on the one hand according to eqs. (3.18) and (5.35) to

$$\begin{aligned} & 2\pi i \partial_\tau \lim_{z_0 \rightarrow 1} (-2\pi i(1-z_0))^{s_{01}} \mathbf{Z}_{0,n}^\tau \\ &= 2\pi i \partial_\tau e^{s_{01}\omega(1,0|\tau)} U_n^\sqcup \mathbf{Z}_n^\tau |_{\tilde{s}_{ij}} \end{aligned} \quad (5.38)$$

$$= e^{s_{01}\omega(1,0|\tau)} U_n^\omega \left(- \left(r_n(\epsilon_0)|_{\bar{s}_{ij}} + 2\zeta_2 s_{01} \right) + s_{01} G_2 + \sum_{k=4}^{\infty} (1-k) G_k r_n(\epsilon_k)|_{\bar{s}_{ij}} \right) \mathbf{Z}_n^\tau|_{\bar{s}_{ij}}.$$

On the other hand, we find similar to the calculation in eq. (5.19)

$$\begin{aligned} & \lim_{z_0 \rightarrow 1} (-2\pi i(1-z_0))^{s_{01}} 2\pi i \partial_\tau \mathbf{Z}_{0,n}^\tau \\ &= e^{s_{01}\omega(1,0|\tau)} \left(-r_{0,n}(\epsilon_0) - G_2 r_{0,n}(x_1) + \sum_{k=4}^{\infty} (1-k) G_k (r_{0,n}(\epsilon_k) + r_{0,n}(x_{k-1})) \right) U_n^\omega \mathbf{Z}_n^\tau|_{\bar{s}_{ij}}, \end{aligned} \quad (5.39)$$

such that comparing the coefficients of G_k leads to the matrix equations

$$\begin{aligned} r_{0,n}(x_1) U_n^\omega &= -s_{01} U_n^\omega, \\ r_{0,n}(\epsilon_0) U_n^\omega &= U_n^\omega \left(r_n(\epsilon_0)|_{\bar{s}_{ij}} + 2\zeta_2 s_{01} \right), \\ (r_{0,n}(\epsilon_k) + r_{0,n}(x_{k-1})) U_n^\omega &= U_n^\omega r_n(\epsilon_k)|_{\bar{s}_{ij}}, \quad k \geq 4. \end{aligned} \quad (5.40)$$

While the second and third equations show the action of the representations $r_{0,n}(\epsilon_k)$, $r_{0,n}(x_k)$ and $r_n(\epsilon_k)$ on the vector space spanned by the columns of U_n^ω , which will be discussed in more detail in subsection 5.4.3, we shall next elaborate on the first one.

5.3.3 Projecting to the $r_{0,n}(x_1)$ eigenspace of the minimal eigenvalue

The first eigenvalue equation (5.40) determines the first $(n-1)!$ column vectors of the basis transformation U_n diagonalizing the matrix $r_{0,n}(x_1)$:

$$r_{0,n}(x_1) = U_n \text{diag} \left(\underbrace{-s_{01}, \dots, -s_{01}}_{(n-1)!}, \dots, \underbrace{-s_{01\dots n}, \dots, -s_{01\dots n}}_{(n-1)!} \right) U_n^{-1}, \quad (5.41)$$

with

$$U_n = \left(U_n^\omega \quad \dots \quad U_n^{\text{BCJ}} \right), \quad U_n^{-1} = \begin{pmatrix} P_n^\omega \\ \vdots \end{pmatrix}, \quad (5.42)$$

where the last $(n-1)!$ column vectors of U_n are determined by the first eigenvalue equation in eq. (5.21). The $(n-1)! \times n!$ matrix P_n^ω defined by eq. (5.42) is composed of the dual vectors of U_n^ω , such that

$$P_n^\omega U_n^\omega = \mathbb{1}_{(n-1)!}. \quad (5.43)$$

This equation and the eigenvalue decomposition (5.41) imply that the matrix P_n^ω acts on the regularizing factor $(-2\pi i(1-z_0))^{-r_{0,n}(x_1)}$ in $\mathbf{C}_{1,n}^\tau$ by projecting to the eigenspace associated with the eigenvalue $-s_{01}$,

$$P_n^\omega (-2\pi i(1-z_0))^{-r_{0,n}(x_1)} = (-2\pi i(1-z_0))^{s_{01}} P_n^\omega. \quad (5.44)$$

Combining this with eq. (5.35) shows that the boundary value $\mathbf{C}_{1,n}^\tau$ can be projected to the $(n-1)!$ -vector \mathbf{Z}_n^τ of genus-one Z -integrals by left-multiplication with P_n^ω :

$$P_n^\omega \mathbf{C}_{1,n}^\tau = \lim_{z_0 \rightarrow 1} (-2\pi i(1-z_0))^{s_{01}} P_n^\omega \mathbf{Z}_{0,n}^\tau$$

$$= e^{s_{01}\omega(1,0|\tau)} \mathbf{Z}_n^T |_{\tilde{s}_{ij}}, \quad (5.45)$$

which finishes the proof of eq. (5.2).

5.3.4 Two-point example

Let us explicitly determine the upper boundary value $\mathbf{C}_{1,2}^T$ and the associated matrices $U_2^\mathbb{W}, P_2^\mathbb{W}$ for the two-point example. The finite part in eq. (5.35) for $\mathbf{Z}_{0,2}^T$ is given by

$$\begin{aligned} \lim_{z_0 \rightarrow 1} (-2\pi i(1-z_0))^{s_{01}} \mathbf{Z}_{0,2}^T &= \lim_{z_0 \rightarrow 1} e^{s_{01}\omega(1,0|\tau)} \int_0^{z_0} dz_2 e^{-s_{02}\mathcal{G}_{02}^T - s_{12}\mathcal{G}_{12}^T} \begin{pmatrix} \Omega_{12}(\eta) \\ \Omega_{02}(\eta) \end{pmatrix} (1 + \mathcal{O}(1-z_0)) \\ &= e^{s_{01}\omega(1,0|\tau)} \int_0^1 dz_2 e^{-(s_{02}+s_{12})\mathcal{G}_{12}^T} \begin{pmatrix} \Omega_{12}(\eta) \\ \Omega_{12}(\eta) \end{pmatrix} \\ &= e^{s_{01}\omega(1,0|\tau)} U_2^\mathbb{W} \mathbf{Z}_2^T |_{\tilde{s}_{ij}} \end{aligned} \quad (5.46)$$

where $\tilde{s}_{12} = s_{02} + s_{12}$, and the symmetry $\Omega(1-z_2, \eta|\tau) = \Omega(-z_2, \eta|\tau)$ determines

$$U_2^\mathbb{W} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}. \quad (5.47)$$

The integral $\mathbf{Z}_2^T = Z_2^T(\mathbb{I}_2|1, 2)$ is given by the two-point, genus-one integral

$$\mathbf{Z}_2^T = \int_0^1 dz_2 e^{-s_{12}\mathcal{G}_{12}^T} \Omega_{12}(\eta). \quad (5.48)$$

The three eigenvalue equations (5.40) can be easily verified using the expressions (3.28) for the scalar derivations $r_2(\epsilon_k)|_{\tilde{s}_{ij}}$ as well as eqs. (4.31) and (4.47) for $r_{0,2}(x_k)$ and $r_{0,2}(\epsilon_k)$, respectively. In particular, we have

$$r_{0,2}(x_1)U_2^\mathbb{W} = -s_{01}U_2^\mathbb{W} \quad (5.49)$$

and can diagonalize $r_{0,2}(x_1)$ via

$$\begin{aligned} r_{0,2}(x_1) &= \begin{pmatrix} -(s_{01} + s_{02}) & s_{02} \\ s_{12} & -(s_{01} + s_{12}) \end{pmatrix} \\ &= \underbrace{\begin{pmatrix} 1 & 1 \\ 1 & -\frac{s_{12}}{s_{02}} \end{pmatrix}}_{U_2} \begin{pmatrix} -s_{01} & 0 \\ 0 & -s_{012} \end{pmatrix} \underbrace{\frac{1}{s_{02} + s_{12}} \begin{pmatrix} s_{12} & s_{02} \\ s_{02} & -s_{02} \end{pmatrix}}_{U_2^{-1}}, \end{aligned} \quad (5.50)$$

By isolating the first row of U_2^{-1} as prescribed by eq. (5.42), one can read off

$$P_2^\mathbb{W} = \frac{1}{s_{02} + s_{12}} \begin{pmatrix} s_{12} & s_{02} \end{pmatrix} \quad (5.51)$$

and, hence,

$$\begin{aligned} P_2^\mathbb{W} \mathbf{C}_{1,2}^T &= \lim_{z_0 \rightarrow 1} (-2\pi i(1-z_0))^{s_{01}} P_2^\mathbb{W} \mathbf{Z}_{0,2}^T \\ &= e^{s_{01}\omega(1,0|\tau)} P_2^\mathbb{W} U_2^\mathbb{W} \mathbf{Z}_2^T |_{\tilde{s}_{ij}} \\ &= e^{s_{01}\omega(1,0|\tau)} \mathbf{Z}_2^T |_{\tilde{s}_{ij}}. \end{aligned} \quad (5.52)$$

5.3.5 Three-point example

In the three-point case $n = 3$, the eigenvalue decomposition (5.41) leads to the matrix

$$U_3 = \begin{pmatrix} 1 & 0 & -\frac{s_{02}}{s_{12}} & 0 & 1 & 0 \\ 0 & 1 & 0 & -\frac{s_{03}}{s_{13}} & 0 & 1 \\ 1 & 1 & -\frac{s_{02}}{s_{12}} & 1 & -\frac{(s_{13}+s_{23})}{s_{03}} & -\frac{s_{13}}{s_{03}} \\ 1 & 1 & 1 & -\frac{s_{03}}{s_{13}} & -\frac{s_{12}}{s_{02}} & -\frac{(s_{12}+s_{23})}{s_{02}} \\ 0 & 1 & 0 & 1 & \frac{s_{12}(s_{03}+s_{13}+s_{23})}{s_{03}s_{023}} & \frac{(s_{12}-s_{03})s_{13}}{s_{02}} \\ 1 & 0 & 1 & 0 & \frac{s_{12}(s_{13}-s_{02})}{s_{02}s_{023}} & \frac{s_{13}(s_{02}+s_{12}+s_{23})}{s_{02}s_{023}} \end{pmatrix} \quad (5.53)$$

of eigenvectors of $r_{0,3}(x_1)$, written out in eq. (4.35). The first two columns of U_3 correspond to the eigenvalue $-s_{01}$ and furnish the matrix U_3^{u} such that

$$\lim_{z_0 \rightarrow 1} (-2\pi i(1-z_0))^{s_{01}} \mathbf{Z}_{0,3}^\tau = e^{s_{01}\omega(1,0|\tau)} U_3^{\text{u}} \mathbf{Z}_3^\tau |_{\tilde{s}_{ij}}, \quad (5.54)$$

while the last two columns reproduce the matrix U_3^{BCJ} in eq. (5.27) and are the eigenvectors to $-s_{0123}$. The projection P_3^{u} given by the first two rows of U_3^{-1} takes the form

$$P_3^{\text{u}} = \frac{1}{(s_{02}+s_{03}+s_{12}+s_{13}+s_{23})} \begin{pmatrix} \frac{s_{12}(s_{02}+s_{12}+s_{13}+s_{23})}{(s_{02}+s_{12})} & -\frac{s_{02}s_{13}}{(s_{02}+s_{12})} & \cdots \\ -\frac{s_{03}s_{12}}{(s_{03}+s_{13})} & \frac{s_{13}(s_{03}+s_{12}+s_{13}+s_{23})}{(s_{03}+s_{13})} & \cdots \\ \cdots & \frac{s_{03}s_{12}}{(s_{02}+s_{12})} & \frac{s_{02}s_{13}}{(s_{02}+s_{12})} & -\frac{s_{03}s_{12}}{(s_{02}+s_{12})} & \frac{s_{02}(s_{02}+s_{03}+s_{12}+s_{23})}{(s_{02}+s_{12})} \\ \cdots & \frac{s_{03}s_{12}}{(s_{03}+s_{13})} & \frac{s_{02}s_{13}}{(s_{03}+s_{13})} & \frac{s_{03}(s_{02}+s_{03}+s_{13}+s_{23})}{(s_{03}+s_{13})} & -\frac{s_{02}s_{13}}{(s_{03}+s_{13})} \end{pmatrix}. \quad (5.55)$$

5.4 Applying the languages: two solution strategies for $\mathbf{C}_{1,n}^\tau$

The system of differential equations (4.52) for $Z_{0,n}^\tau$ contains the fundamental equation (3.18) for Z_n^τ as well as the elliptic KZB equation (3.35) for $\mathbf{S}_n^{\text{E}}(z_0|\tau)$. As a consequence, both corresponding solution strategies can be applied to calculate the integrals Z_n^τ appearing in the regularized boundary value $\mathbf{C}_{1,n}^\tau$ given in eq. (5.45). The corresponding calculations presented in the following two subsections are applications of the methods developed in refs. [1, 2] and reviewed in subsection 3.2 and subsection 3.3 which builds upon the analysis of $\mathbf{C}_{0,n}^\tau, \mathbf{C}_{1,n}^\tau$ in the previous subsections.

5.4.1 The elliptic KZB associator

Having the elliptic KZB equation (4.14) at hand, analogously to the discussion in subsection 3.3 the regularized boundary values identified in eqs. (5.17) and (5.45) are related according to the associator equation (5.3) by the elliptic KZB associator Φ^τ defined in eq. (3.38). Applying the projection P_n^{u} from eq. (5.42) and rearranging factors leads to the associator equation for the genus-one Z -integrals

$$\mathbf{Z}_n^\tau |_{\tilde{s}_{ij}} = -e^{(s_{012}\dots n - s_{01})\omega(1,0|\tau)} P_n^{\text{u}} r_{0,n}(\Phi^\tau(x_k)) U_n^{\text{BCJ}} \mathbf{Z}_{n+2}^{\text{tree}}. \quad (5.56)$$

The associator equation (5.56) is the backbone in calculating the α' -expansions of \mathbf{Z}_n^τ from differential equations in z_0 . It relates the n -point, genus-one integrals \mathbf{Z}_n^τ containing the planar, one-loop configuration-space integrals with (arbitrary) Mandelstam variables \tilde{s}_{ij} for $1 \leq i < j \leq n$ to the $(n+2)$ -point, tree-level Z -integrals $\mathbf{Z}_{n+2}^{\text{tree}}$: the elliptic KZB associator can be represented

by the generating series of eMZVs with the letters being the matrices $r_{0,n}^\tau(x_k)$ appearing in the elliptic KZB equation of $\mathbf{Z}_{0,n}^\tau$ [80]

$$r_{0,n}(\Phi^\tau(x_k)) = \sum_{w \geq 0} \sum_{k_1, \dots, k_w \geq 0} r_{0,n}(x_{k_1} \dots x_{k_w}) \omega(k_w, \dots, k_1 | \tau). \quad (5.57)$$

The matrices $r_{0,n}^\tau(x_k)$ are proportional to s_{ij} and therefore to α' (cf. eq. (2.1)), such that eq. (5.57) is simply the α' -expansion of Φ^τ . When plugged into the associator equation (5.56), it yields the α' -expansion of the genus-one integrals \mathbf{Z}_n^τ from the α' -expansion of the genus-zero integrals $\mathbf{Z}_{n+2}^{\text{tree}}$. To obtain the α' -expansion of \mathbf{Z}_n^τ up to the order $o_{\alpha, \text{max}}^\tau$, words $r_{0,n}^\tau(x_{k_1} \dots x_{k_w})$ up to the maximal word length $0 \leq w \leq w_{\text{max}}$ with

$$w_{\text{max}} = o_{\alpha, \text{max}}^\tau - o_{\alpha, \text{min}}^{\text{tree}} \quad (5.58)$$

have to be included, where

$$o_{\alpha, \text{min}}^{\text{tree}} = 1 - n \quad (5.59)$$

is the minimal order in α' of $\mathbf{Z}_{n+2}^{\text{tree}}$. However, the actual genus-one configuration-space integrals appearing in one-loop open-string amplitudes are the coefficients of the η -variables from the integrals \mathbf{Z}_n^τ . Since the matrices $r_{0,n}^\tau(x_{k_i})$ are homogeneous in these variables of degree $k_i - 1 \geq -1$, a configuration-space integral which is given by an η -degree $k \geq 1 - n$ coefficient of \mathbf{Z}_n^τ receives at most non-trivial contributions from words $r_{0,n}^\tau(x_{k_1} \dots x_{k_w})$ with word length $0 \leq w \leq w_{\text{max}}$ satisfying

$$w = (k_1 + \dots + k_w) - k. \quad (5.60)$$

To summarize, in order to calculate the α' -expansion of an n -point, genus-one configuration-space integral appearing as an η -coefficient¹⁹ of degree k of \mathbf{Z}_n^τ up to the order $o_{\alpha, \text{max}}^\tau$, only the finitely many words $r_{0,n}^\tau(x_{k_1} \dots x_{k_w})$ with

$$0 \leq w \leq o_{\alpha, \text{max}}^\tau + n - 1, \quad w = (k_1 + \dots + k_w) - k \quad (5.61)$$

contribute to the corresponding η -coefficients of the elliptic KZB associator (5.57) and, thus, have to be included in the associator eq. (5.56). Upon rewriting the eMZVs in eq. (5.57) in terms of iterated Eisenstein integrals [19], we have checked eq. (5.56) to reproduce the α' -expansion generated by eq. (3.23) for a wide range of orders in α' and η_j .

Note that the results of eq. (5.56) for the integrals $\mathbf{Z}_n^\tau |_{\bar{s}_{ij}}$ relevant to one-loop open-string amplitudes no longer depend on s_{01} , which is why the conditions eq. (2.3) on its real part do not pose any restrictions on the physical applications.

5.4.2 Two-point example

Let us investigate the two-point working example. From eqs. (3.25) and (5.23), the tree-level integrals are known to be given by

$$U_2^{\text{BCJ}} \mathbf{Z}_4^{\text{tree}} = \left(\frac{-\frac{1}{s_{12}}}{\frac{1}{s_{02}}} \right) \frac{\Gamma(1-s_{12})\Gamma(1-s_{02})}{\Gamma(1-s_{12}-s_{02})}, \quad (5.62)$$

¹⁹See ref. [1] for details on the extraction of the appropriate η -coefficient from a Z -integral Z_n^τ .

while the matrices $r_{0,2}(x_k)$ are spelled out in eq. (4.31). The projection $P_2^{\mathbb{W}}$ is given in eq. (5.51), such that upon combining these quantities the associator eq. (5.56) for the two-point integral \mathbf{Z}_2^τ in eq. (5.48) takes the form

$$\mathbf{Z}_2^\tau \Big|_{\bar{s}_{12}} = e^{(s_{02}+s_{12})\omega(1,0|\tau)} \frac{1}{s_{02}+s_{12}} \begin{pmatrix} s_{12} & s_{02} \end{pmatrix} r_{0,2}(\Phi^\tau(x_k)) \begin{pmatrix} \frac{1}{s_{12}} \\ -\frac{1}{s_{02}} \end{pmatrix} \frac{\Gamma(1-s_{12})\Gamma(1-s_{02})}{\Gamma(1-s_{12}-s_{02})}. \quad (5.63)$$

Let us extract the configuration-space integral for the two-point, one-loop integral

$$I_2^\tau = \int_0^1 dz_2 e^{-(s_{02}+s_{12})\mathcal{G}_{12}^\tau} = \mathbf{Z}_2^\tau \Big|_{\bar{s}_{12}} \Big|_{\eta^{-1}} \quad (5.64)$$

on the left-hand side of eq. (5.63) and calculate its α' -expansion up to order $o_{\alpha,\max}^\tau = 2$. Since according to eq. (5.62) the minimal order of the tree-level integral is $o_{\alpha,\min}^\tau = -1$, words $r_{0,n}^\tau(x_{k_1} \dots x_{k_w})$ with word length $0 \leq w \leq 3$ have to be considered. However, the condition (5.61) only selects the words which are explicitly written down in the following to contribute non-trivially:

$$\begin{aligned} r_{0,2}(\Phi^\tau(x_k)) &= r_{0,2}(x_0)\omega(0|\tau) + r_{0,2}([x_1, x_0])\omega(0, 1|\tau) \\ &\quad + r_{0,2}(x_2x_0x_0 + x_0x_0x_2)\omega(0, 0, 2|\tau) + r_{0,2}(x_0x_2x_0)\omega(0, 2, 0|\tau) \\ &\quad + r_{0,2}(x_1x_1x_0 + x_0x_1x_1)\omega(0, 1, 1|\tau) + r_{0,2}(x_1x_0x_1)\omega(1, 0, 1|\tau) + \mathcal{O}(\eta^0, s_{ij}^4) \\ &= r_{0,2}(x_0) + r_{0,2}([x_1, x_0])\omega(0, 1|\tau) \\ &\quad + r_{0,2}([x_0, [x_0, x_2]])\omega(0, 0, 2|\tau) - r_{0,2}(x_0x_2x_0)\zeta_2 \\ &\quad + r_{0,2}([x_1, [x_1, x_0]])\left(\frac{5}{12}\zeta_2 + \frac{1}{2}\omega(0, 1|\tau)^2 + \frac{1}{2}\omega(0, 0, 2|\tau)\right) \\ &\quad + \mathcal{O}(\eta^0, s_{ij}^4). \end{aligned} \quad (5.65)$$

Therefore, denoting the words written down above and the corresponding higher-order terms $\mathcal{O}(s_{ij}^4)$ which give the order η^{-1} of the elliptic KZB associator by $r_{0,2}(\Phi^\tau(x_k)) \Big|_{\eta^{-1}}$, we obtain the equation for the configuration-space integral

$$\begin{aligned} I_2^\tau &= e^{(s_{02}+s_{12})\omega(1,0|\tau)} \frac{1}{s_{02}+s_{12}} \begin{pmatrix} s_{12} & s_{02} \end{pmatrix} r_{0,2}(\Phi^\tau(x_k)) \Big|_{\eta^{-1}} \begin{pmatrix} \frac{1}{s_{12}} \\ -\frac{1}{s_{02}} \end{pmatrix} \frac{\Gamma(1-s_{12})\Gamma(1-s_{02})}{\Gamma(1-s_{12}-s_{02})} \\ &= 1 + \frac{1}{4}(s_{02}+s_{12})^2(\zeta_2 - 12\gamma(4, 0|q)) + \mathcal{O}(s_{ij}^3) \end{aligned} \quad (5.66)$$

in agreement with eq. (2.39) and [1].

5.4.3 Two organization schemes for α' -expansions

The other expansion method for the genus-one Z -integrals \mathbf{Z}_n^τ put forward in ref. [1] is reviewed in subsection 3.2 and consists of solving the differential eq. (3.18) in τ by Picard iteration. The resulting α' -expansion eq. (3.23) is organized in terms of iterated Eisenstein integrals and $(n-1)! \times (n-1)!$ matrix representations $r_n(\epsilon_k)$ and furnishes an alternative to the expanded form of eq. (5.56) in terms of eMZVs and $n! \times n!$ matrix representations $r_{0,n}(x_k)$. The equivalence of eqs. (3.23) and (5.56), i.e.

$$\sum_{\ell=0}^{\infty} \sum_{\substack{k_1, k_2, \dots, k_\ell \\ =0, 4, 6, 8, \dots}} \left(\prod_{j=1}^{\ell} (k_j - 1) \right) \gamma(k_1, k_2, \dots, k_\ell | q) r_n(\epsilon_{k_\ell} \dots \epsilon_{k_2} \epsilon_{k_1}) \mathbf{Z}_n^{i\infty} \Big|_{\bar{s}_{ij}}$$

$$\begin{aligned}
&= -e^{(s_{012\dots n} - s_{01})\omega(1,0|\tau)} \sum_{w=0}^{\infty} \sum_{k_1, \dots, k_w \geq 0} \omega(k_1, k_2, \dots, k_w | \tau) \\
&\quad \times P_n^{\omega} r_{0,n}(x_{k_w} \dots x_{k_2} x_{k_1}) U_n^{\text{BCJ}} \mathbf{Z}_{n+2}^{\text{tree}},
\end{aligned} \tag{5.67}$$

is not obvious from the first glance at these types of series but guaranteed by the arguments in refs. [1, 2] and the previous sections. The initial value $\mathbf{Z}_n^{i\infty}$ on the left-hand side is related to $\mathbf{Z}_{n+2}^{\text{tree}}$ on the right-hand side by an s_{ij} - and η_j dependent $(n-1)! \times (n-1)!$ matrix described in ref. [1], see eq. (3.24) for the two-point example.

The discussion of the previous subsections yields a streamlined way of showing *directly* that both sides of eq. (5.67) obey the same differential equation in τ . The differential eq. (3.18) (with \tilde{s}_{ij} in the place of s_{ij}) holds for the left-hand side by construction, and the analogous equation for $P_n^{\omega} \mathbf{C}_{1,n}^{\tau} = e^{s_{01}\omega(1,0|\tau)} \mathbf{Z}_n^{\tau} |_{\tilde{s}_{ij}}$ on the right-hand side can be inferred from properties of the augmented Z -integrals: according to the calculation (5.39), this differential equation for $P_n^{\omega} \mathbf{C}_{1,n}^{\tau}$ can be written as

$$\begin{aligned}
2\pi i \partial_{\tau} P_n^{\omega} \mathbf{C}_{1,n}^{\tau} &= \lim_{z_0 \rightarrow 1} (-2\pi i (1-z_0))^{s_{01}} P_n^{\omega} 2\pi i \partial_{\tau} \mathbf{Z}_{0,n}^{\tau} \\
&= P_n^{\omega} \left(-r_{0,n}(\epsilon_0) - G_2 r_{0,n}(x_1) + \sum_{k=4}^{\infty} (1-k) G_k (r_{0,n}(\epsilon_k) + r_{0,n}(x_{k-1})) \right) U_n^{\omega} \\
&\quad \times e^{-s_{01}\omega(1,0|\tau)} \mathbf{Z}_n^{\tau} |_{\tilde{s}_{ij}},
\end{aligned} \tag{5.68}$$

where the identities (5.40) together with eq. (5.43) can be used to relate the matrix representations of different sizes

$$\begin{aligned}
P_n^{\omega} r_{0,n}(x_1) U_n^{\omega} &= -s_{01} \mathbb{1}_{(n-1)! \times (n-1)!}, \\
P_n^{\omega} r_{0,n}(\epsilon_0) U_n^{\omega} &= \left(r_n(\epsilon_0) |_{\tilde{s}_{ij}} + 2\zeta_2 s_{01} \right), \\
P_n^{\omega} (r_{0,n}(\epsilon_k) + r_{0,n}(x_{k-1})) U_n^{\omega} &= r_n(\epsilon_k) |_{\tilde{s}_{ij}}, \quad k \geq 4.
\end{aligned} \tag{5.69}$$

As a consequence, eq. (5.45) can be simplified to

$$\begin{aligned}
2\pi i \partial_{\tau} (e^{s_{01}\omega(1,0|\tau)} \mathbf{Z}_n^{\tau} |_{\tilde{s}_{ij}}) &= 2\pi i \partial_{\tau} P_n^{\omega} \mathbf{C}_{1,n}^{\tau} \\
&= \left(- \left(r_n(\epsilon_0) |_{\tilde{s}_{ij}} + 2\zeta_2 s_{01} \right) + s_{01} G_2 + \sum_{k=4}^{\infty} (1-k) G_k r_n(\epsilon_k) |_{\tilde{s}_{ij}} \right) e^{s_{01}\omega(1,0|\tau)} \mathbf{Z}_n^{\tau} |_{\tilde{s}_{ij}},
\end{aligned} \tag{5.70}$$

which is equivalent to eq. (3.18) for the Mandelstam variables \tilde{s}_{ij} defined in eq. (5.32) after employing

$$2\pi i \partial_{\tau} \omega(1,0|\tau) = G_2 - 2\zeta_2. \tag{5.71}$$

This concludes the direct proof that both sides of eq. (5.67) obey the same differential equation in τ . A direct comparison of the respective initial values as $\tau \rightarrow i\infty$ may be challenging, but the consistency in this limit is guaranteed since both sides have been derived in refs. [1, 2] and the previous sections. Note that the combination $r_{0,n}(\epsilon_k) + r_{0,n}(x_{k-1})$ in the third line of eq. (5.69) also arises when adapting depth-three relations eq. (4.67) in the derivation algebra to the twice punctured torus.

6 Conclusion

In refs. [1, 2] two different constructions for the α' -expansion of configuration-space integrals in one-loop open-string amplitudes have been put forward. In both references the (elliptic) multiple zeta values in the α' -expansions are derived from different types of differential equations. Here we have connected these two approaches within a more general framework and, in particular, shown that

- both approaches and the definitions therein can be traced back to one class of iterated integrals, called augmented (genus-one) Z -integrals, a vector of n -point basis integrals $\mathbf{Z}_{0,n}^\tau$ is defined in eq. (4.3). Besides the usual fixed puncture $z_1 = 0$ on the torus $\mathbb{C}/(\mathbb{Z} + \tau\mathbb{Z})$ appearing in the definition of the genus-one Z -integrals of ref. [1], the integrals $\mathbf{Z}_{0,n}^\tau$ are augmented by a second unintegrated puncture z_0 with $z_1 = 0 < z_0 < 1$ as in ref. [2]. Thus – apart from Mandelstam invariants s_{ij} – the augmented integrals depend on two parameters: the modular parameter τ of the torus and the additional puncture z_0 .
- differentiation of $\mathbf{Z}_{0,n}^\tau$ with respect to the two parameters τ and z_0 leads to a homogeneous linear system of two partial differential equations – an elliptic KZB system (4.52) on the twice-punctured torus
- the genus-one Selberg integrals from ref. [2] are linear combinations of the components of the augmented Z -integrals $\mathbf{Z}_{0,n}^\tau$; they can be recovered according to the discussion in appendix D.
- the genus-one Z -integrals from ref. [1] – and hence the configuration-space integrals in n -point, planar, one-loop open-string amplitudes – are recovered as regularized boundary values of the augmented integrals in $\mathbf{Z}_{0,n}^\tau$ as $z_0 \rightarrow 1$. Correspondingly, the two differential equations in the system (4.52) can be solved independently for the string integrals in the limit of $z_0 \rightarrow 1$ via integration w.r.t. τ or z_0 . The respective initial values at $\tau \rightarrow i\infty$ and $z_0 \rightarrow 0$ are reduced to $(n+2)$ -point genus-zero integrals whose α' -expansion in terms of multiple zeta values is known from several all-multiplicity methods, see e.g. [35, 11, 14, 44]. As summarized in subsection 5.4, this yields the two approaches in refs. [1, 2] to calculate the α' -expansion of one-loop open-string amplitudes in terms of (elliptic) multiple zeta values and iterated Eisenstein integrals.
- calculating the α' -expansion using the integrals $\mathbf{Z}_{0,n}^\tau$ involves elementary operations only: differentiation in formal expansion variables η_j and matrix algebra, with the matrices being determined by the elliptic KZB system (4.52). The entries of the corresponding $n! \times n!$ matrix representation determine the coefficients in the α' -expansion and are explicitly given for an arbitrary number of points n in eqs. (4.21) and (4.44).
- the $(n-1)! \times (n-1)!$ matrix representation in the differential equation in ref. [1] is reproduced from the matrices appearing in the elliptic KZB system (4.52) according to eq. (5.69).
- the operators appearing in an elliptic KZB system of the form (4.52) satisfy the commutation relations (4.61) which serve as consistency checks for our explicit matrix representations.

Our construction of particular integral representations $\mathbf{Z}_{0,n}^\tau$ for the solution of an elliptic KZB system on the twice-punctured curve leads to the question as how it may be embedded into the existing Mathematics literature about similar systems. In particular, its connection to ref. [67]

and the representation of the algebra generators therein appearing in the differential equations as nested commutators, should be clarified.

Acknowledgments

We are grateful to Federico Zerbini for discussions and to Carlos Mafra, Nils Matthes, Carlos Rodriguez and Federico Zerbini for comments on the manuscript. AK is supported by the International Max Planck Research School for Mathematical and Physical Aspects of Gravitation, Cosmology and Quantum Field Theory. OS is supported by the European Research Council under ERC-STG-804286 UNISCAMP.

A Kronecker–Eisenstein chain identities

In this appendix, we prove various identities used for chains (4.1) of Kronecker–Eisenstein series in the proofs of the n -point formulæ of the z_0 - and τ -derivative of the augmented Z -integrals in appendix B and appendix C, respectively. Some of these identities involve chains with shifts or replacements in certain η -variables. For a replacement of η_{a_k} by ξ (or a shift by $\xi - \eta_{a_k}$, respectively), this will be denoted as follows,

$$\varphi^\tau(a_1, a_2, \dots, a_p)|_{\eta_{a_k} \rightarrow \xi} = \prod_{i=2}^k \Omega_{a_{i-1}, a_i}(\eta_{a_i a_{i+1} \dots a_p} + \xi - \eta_{a_k}) \prod_{i=k+1}^p \Omega_{a_{i-1}, a_i}(\eta_{a_i a_{i+1} \dots a_p}), \quad (\text{A.1})$$

where we recall the shorthand $\Omega_{ij}(\eta) = \Omega(z_{ij}, \eta|\tau)$. Moreover, we generally assign an η -variable to the first index of a chain $\varphi^\tau(a_1, a_2, \dots, a_p)$ such that the overall sum vanishes, i.e.

$$\eta_{a_1} = -\eta_{a_2} - \dots - \eta_{a_p}, \quad (\text{A.2})$$

which is in agreement with eq. (4.18) for the chains $\varphi^\tau(1, A)$ and $\varphi^\tau(0, B)$.

Throughout this and the following section, we accompany the crucial identities by the graphical notation for chains of Kronecker–Eisenstein series in order to facilitate the readability of the proofs for the n -point z_0 - and τ -derivatives. Let us briefly recall the corresponding definitions and conventions from subsection 2.2.2:

- A Kronecker–Eisenstein series $\Omega_{ij}(\eta)$ is represented by a directed edge with weight η from vertex j to vertex i

$$\Omega_{ij}(\eta) = i \bullet \xleftarrow{\eta} \bullet j. \quad (\text{A.3})$$

- A chain of Kronecker–Eisenstein series $\varphi^\tau(A)$ labeled by the sequence $A = (a_1, a_2, \dots, a_p)$ is represented by a chain of directed edges connecting the corresponding vertices a_i and a_{i+1} . If the η -variable $\eta_{a_i \dots a_p}$ of the factor $\Omega_{a_{i-1}, a_i}(\eta_{a_i \dots a_p})$ is not explicitly depicted as a weight of the edge and unless stated otherwise, it is determined by the vertices pointing to the vertex i through a chain of arrows: each vertex j which has an edge pointing in the direction of i (possibly via further directed edges pointing towards i) contributes a term η_j , such that

the edge pointing away from i is given by the corresponding sum

$$\varphi^\tau(A) = \begin{array}{c} a_p \\ \vdots \\ a_2 \\ \downarrow \\ a_1 \end{array} = \prod_{i=2}^p \begin{array}{c} a_i \\ \downarrow \eta_{a_i \dots p} \\ a_{i-1} \end{array} = \prod_{i=2}^p \Omega_{a_{i-1}, a_i}(\eta_{a_i a_{i+1} \dots a_p}), \quad (\text{A.4})$$

where we use the convention $\eta_{a_i a_{i+1} \dots a_p} = \eta_{a_i, i+1 \dots p}$ for sums of η -variables associated to a sequence $(a_i, a_{i+1}, \dots, a_p)$ in graphs. It should always be clear from the context that whether edges without weights refer to the genus-zero notation or the genus-one notation where the weights are only implicit. In particular, in this and the next section, we exclusively discuss the genus-one case.

- The same accumulation of the η -variables is used for directed tree graphs, if it is not denoted explicitly: the weight of the edge pointing away from the vertex i is the sum of all the η -variables associated to the edges pointing towards i via a chain of Kronecker–Eisenstein series. For example

$$\Omega_{12}(\eta_{234})\Omega_{23}(\eta_3)\Omega_{24}(\eta_4) = \begin{array}{c} 3 \quad 4 \\ \swarrow \eta_3 \quad \searrow \eta_4 \\ \bullet 2 \\ \downarrow \eta_{234} \\ \bullet 1 \end{array} = \begin{array}{c} 3 \quad 4 \\ \swarrow \quad \searrow \\ \bullet 2 \\ \downarrow \\ \bullet 1 \end{array}. \quad (\text{A.5})$$

The following identities, which are proven in appendix A.1, are particularly useful: for finite, disjoint sequences $A = (a_1, \dots, a_p)$, $B = (b_1, \dots, b_q)$, $C = (c_1, \dots, c_m)$ and $D = (d_1, \dots, d_l)$ as well as distinct labels r, r_0, r_1 not contained in any of the sequences A, B, C, D , we find

- the concatenation of two chains with shifted η -variables of the first chain

$$\varphi^\tau(A, r)|_{\eta_r \rightarrow \eta_r + \eta_B} \varphi^\tau(r, B) = \varphi^\tau(A, r, B), \quad (\text{A.6})$$

i.e.

$$\begin{array}{c} r \\ \downarrow \eta_r + \eta_B \\ a_p \\ \vdots \\ a_i \\ \downarrow \eta_{a_i \dots p} + \eta_r + \eta_B \\ a_{i-1} \\ \vdots \\ a_2 \\ \downarrow \eta_{a_2 \dots p} + \eta_r + \eta_B \\ a_1 \end{array} \quad \begin{array}{c} b_q \\ \vdots \\ b_2 \\ \downarrow \\ b_1 \\ \downarrow \\ r \\ \downarrow \\ a_p \\ \vdots \\ a_2 \\ \downarrow \\ r \end{array} = \begin{array}{c} b_q \\ \vdots \\ b_2 \\ \downarrow \\ b_1 \\ \downarrow \\ r \\ \downarrow \\ a_p \\ \vdots \\ a_2 \\ \downarrow \\ a_1 \end{array} \quad (\text{A.7})$$

- the shuffle product of two chains ending at the same point r

$$\varphi^\tau(r, A)\varphi^\tau(r, B) = \varphi^\tau(r, A \sqcup B), \quad (\text{A.8})$$

i.e.

$$(A.9)$$

- the shuffle product of two chains beginning at the same point r

$$\varphi^\tau(C, r)|_{\eta_r \rightarrow \eta_A} \varphi^\tau(D, r)|_{\eta_r \rightarrow \eta_r + \eta_B} = \varphi^\tau(C \sqcup D, r)|_{\eta_r \rightarrow \eta_r + \eta_A + \eta_B}, \quad (A.10)$$

where according to eq. (A.2) $\eta_{c_1} = -\eta_A - \eta_{c_2, \dots, c_m}$ and $\eta_{d_1} = -\eta_r - \eta_B - \eta_{d_2, \dots, d_l}$, i.e.

$$(A.11)$$

- the reflection property

$$\varphi^\tau(r, a_1, \dots, a_p) = (-1)^p \varphi^\tau(a_p, \dots, a_1, r), \quad (A.12)$$

i.e.

$$(A.13)$$

where again by our convention $\eta_r = -\eta_A = -\eta_{a_1 \dots a_p}$.

- and the shifting of two labels r_0 and r_1 next to each other

$$\begin{aligned} & \varphi^\tau(r_0, A, r_1, B) \\ &= \sum_{i=1}^{p+1} (-1)^{p+1-i} \varphi^\tau(r_0, a_1, a_2, \dots, a_{i-1}) \varphi^\tau(r_0, r_1, (a_p, a_{p-1}, \dots, a_i) \sqcup B), \end{aligned} \quad (A.14)$$

i.e.

$$\begin{array}{c}
b_q \\
\vdots \\
b_1 \\
r_1 \\
a_p \\
\vdots \\
a_1 \\
r_0
\end{array}
= \sum_{i=1}^{p+1} (-1)^{p+1-i}
\begin{array}{c}
a_i \quad b_q \\
\vdots \quad \vdots \\
a_{i-1} \quad a_p \quad b_1 \\
\vdots \quad \vdots \quad \vdots \\
a_1 \quad r_1 \\
\vdots \quad \vdots \\
r_0
\end{array}
. \quad (\text{A.15})$$

A.1 Shuffle and concatenation identities

The first identity is the concatenation (A.6) of two chains, where one has a shifted η -variable

$$\varphi^\tau(A, r)|_{\eta_r \rightarrow \eta_r + \eta_B} \varphi^\tau(r, B) = \varphi^\tau(A, r, B). \quad (\text{A.16})$$

For $A = \emptyset$ or $B = \emptyset$, this relation is trivial due to eq. (4.2), while for $A = (a_1, \dots, a_p)$, $B = (b_1, \dots, b_q) \neq \emptyset$, it follows from the definitions (4.1) and (A.6)

$$\begin{aligned}
& \varphi^\tau(A, r)|_{\eta_r \rightarrow \eta_r + \eta_B} \varphi^\tau(r, B) \\
&= \Omega_{a_1, a_2}(\eta_A + \eta_r + \eta_B, \tau) \dots \Omega_{a_{p-1}, a_p}(\eta_{a_p} + \eta_r + \eta_B, \tau) \Omega_{a_p, r}(\eta_r + \eta_B, \tau) \\
&\quad \times \Omega_{r, b_1}(\eta_B, \tau) \Omega_{b_1, b_2}(\eta_{b_2, \dots, b_q}, \tau) \dots \Omega_{b_{q-1}, b_q}(\eta_{b_q}, \tau) \\
&= \varphi^\tau(A, r, B). \quad (\text{A.17})
\end{aligned}$$

The second identity is the shuffle relation (A.8), which can be proven by induction in the length of the sequence A (and by the symmetry in A and B). Thus, let us assume that $A = \emptyset$ or $B = \emptyset$, then it is trivially satisfied according to the definition (4.2), i.e. $\varphi^\tau(r) = 1$. For $A = (a_1)$ and $B = (b_1)$, we simply find the Fay identity (2.24) for the Kronecker–Eisenstein series

$$\begin{aligned}
\varphi^\tau(r, a_1) \varphi^\tau(r, b_1) &= \Omega_{r, a_1}(\eta_{a_1}) \Omega_{r, b_1}(\eta_{b_1}) \\
&= \Omega_{r, a_1}(\eta_{a_1, b_1}) \Omega_{a_1, b_1}(\eta_{b_1}) + \Omega_{r, b_1}(\eta_{a_1, b_1}) \Omega_{b_1, a_1}(\eta_{a_1}) \\
&= \varphi^\tau(r, a_1, b_1) + \varphi^\tau(r, b_1, a_1) \\
&= \varphi^\tau(r, a_1 \sqcup b_1). \quad (\text{A.18})
\end{aligned}$$

Now, let us assume that it holds for (a_2, \dots, a_p) and $B = (b_1, \dots, b_q)$, as well as for $A = (a_1, \dots, a_p)$ and (b_2, \dots, b_q) and use the Fay identity for the induction step to show the identity for A and B

$$\begin{aligned}
\varphi^\tau(r, A) \varphi^\tau(r, B) &= \varphi^\tau(A) \varphi^\tau(B) \varphi^\tau(r, a_1)|_{\eta_{a_1} \rightarrow \eta_A} \varphi^\tau(r, b_1)|_{\eta_{b_1} \rightarrow \eta_B} \\
&= \varphi^\tau(A) \varphi^\tau(B) (\varphi^\tau(r, a_1, b_1) + \varphi^\tau(r, b_1, a_1))|_{\eta_{a_1}, \eta_{b_1} \rightarrow \eta_A, \eta_B} \\
&= \varphi^\tau(a_1, a_2, \dots, a_p) \varphi^\tau(r, a_1, B)|_{\eta_{a_1} \rightarrow \eta_A} + \varphi^\tau(r, b_1, A)|_{\eta_{b_1} \rightarrow \eta_B} \varphi^\tau(b_1, b_2, \dots, b_q) \\
&= \varphi^\tau(r, a_1)|_{\eta_{a_1} \rightarrow \eta_A + \eta_B} \varphi^\tau(a_1, a_2, \dots, a_p) \varphi^\tau(a_1, B) \\
&\quad + \varphi^\tau(r, b_1)|_{\eta_{b_1} \rightarrow \eta_B + \eta_A} \varphi^\tau(b_1, b_2, \dots, b_q) \varphi^\tau(b_1, A) \\
&= \varphi^\tau(r, a_1, (a_2, \dots, a_p) \sqcup B) + \varphi^\tau(r, b_1, A \sqcup (b_2, \dots, b_q)) \\
&= \varphi^\tau(r, A \sqcup B), \quad (\text{A.19})
\end{aligned}$$

where we have used the concatenation property in the intermediate step.

The next identity (A.10),

$$\begin{aligned} & \varphi^\tau(C, r)|_{\eta_r \rightarrow \eta_A} \varphi^\tau(D, r)|_{\eta_r \rightarrow \eta_r + \eta_B} \\ &= \varphi^\tau(C \sqcup D, r)|_{\eta_r \rightarrow \eta_r + \eta_A + \eta_B, \eta_{c_1} \rightarrow -\eta_A - \eta_{c_2, \dots, c_m}, \eta_{d_1} \rightarrow -\eta_r - \eta_B - \eta_{d_2, \dots, d_l}}, \end{aligned} \quad (\text{A.20})$$

is similar to the one before, but we have to be more careful with the shifts in the η -variables. For $C = \emptyset$ or $D = \emptyset$, it is trivial. Thus, let $C = (c_1, \dots, c_m)$ and $D = (d_1, \dots, d_l)$ with $m, l \neq 0$. For $m = l = 1$, it is simply the Fay identity. For $m, l \geq 2$, we can iteratively apply the Fay identity:

$$\begin{aligned} & \varphi^\tau(C, r)|_{\eta_r \rightarrow \eta_A} \varphi^\tau(D, r)|_{\eta_r \rightarrow \eta_r + \eta_B} \\ &= \varphi^\tau(c_1, \dots, c_{m-1}, c_m, r)|_{\eta_r \rightarrow \eta_A} \varphi^\tau(d_1, \dots, d_{l-1}, d_l, r)|_{\eta_r \rightarrow \eta_r + \eta_B} \\ &= \varphi^\tau(c_1, \dots, c_{m-1}, c_m)|_{\eta_{c_m} \rightarrow \eta_{c_m} + \eta_A} \varphi^\tau(d_1, \dots, d_l, c_m)|_{\eta_{c_m} \rightarrow \eta_r + \eta_B} \varphi^\tau(c_m, r)|_{\eta_r \rightarrow \eta_r + \eta_A + \eta_B} \\ &\quad + \varphi^\tau(c_1, \dots, c_m, d_l)|_{\eta_{d_l} \rightarrow \eta_A} \varphi^\tau(d_1, \dots, d_{l-1}, d_l)|_{\eta_{d_l} \rightarrow \eta_{d_l} + \eta_r + \eta_B} \varphi^\tau(d_l, r)|_{\eta_r \rightarrow \eta_r + \eta_A + \eta_B} \\ &= \varphi^\tau((c_1, \dots, c_{m-1}) \sqcup D, c_m, r)|_{\eta_r \rightarrow \eta_r + \eta_A + \eta_B} \\ &\quad + \varphi^\tau(C \sqcup (d_1, \dots, d_{l-1}), d_l, r)|_{\eta_r \rightarrow \eta_r + \eta_A + \eta_B} \\ &= \varphi^\tau(C \sqcup D, r)|_{\eta_r \rightarrow \eta_r + \eta_A + \eta_B}, \end{aligned} \quad (\text{A.21})$$

where according to eq. (A.2), $\eta_{c_1} = -\eta_A - \eta_{c_2, \dots, c_m}$ and $\eta_{d_1} = -\eta_r - \eta_B - \eta_{d_2, \dots, d_l}$

In a similar inductive proof of the reflection property (A.12),

$$\varphi^\tau(r, a_1, \dots, a_p) = (-1)^p \varphi^\tau(a_p, \dots, a_1, r), \quad (\text{A.22})$$

with $\eta_r = -\eta_A$, the $p = 1$ case simply reduces to the antisymmetry property of the Kronecker–Eisenstein series,

$$\varphi^\tau(r, a_1) = \Omega_{r, a_1}(\eta_{a_1}, \tau) = -\Omega_{a_1, r}(-\eta_{a_1}, \tau) = -\varphi^\tau(a_1, r). \quad (\text{A.23})$$

The inductive step is done by concatenation

$$\begin{aligned} \varphi^\tau(r, a_1, \dots, a_{p-1}, a_p) &= \varphi^\tau(r, a_1, \dots, a_{p-1})|_{\eta_{a_{p-1}} \rightarrow \eta_{a_{p-1}, a_p}} \varphi^\tau(a_{p-1}, a_p) \\ &= (-1)^{p-1} \varphi^\tau(a_{p-1}, \dots, a_1, r)|_{\eta_r = -\eta_{a_1, \dots, a_p}} \varphi^\tau(a_{p-1}, a_p) \\ &= (-1)^p \varphi^\tau(a_p, a_{p-1})|_{\eta_{a_{p-1}} \rightarrow -\eta_{a_p}} \varphi^\tau(a_{p-1}, \dots, a_1, r)|_{\eta_r = -\eta_{a_1, \dots, a_p}} \\ &= (-1)^p \varphi^\tau(a_p, a_{p-1}, \dots, a_1, r)|_{\eta_r = -\eta_{a_1, \dots, a_p}}. \end{aligned} \quad (\text{A.24})$$

To finish, let us prove the identity (A.14),

$$\varphi^\tau(r_0, A, r_1, B) = \sum_{i=1}^{p+1} (-1)^{p+1-i} \varphi^\tau(r_0, A_{1i}) \varphi^\tau(r_0, r_1, \tilde{A}_{i, p+1} \sqcup B), \quad (\text{A.25})$$

for $A = (a_1, a_2, \dots, a_p)$ and $B = (b_1, b_2, \dots, b_q)$, where we already make use of the notation in eq. (4.19) for subsequences. It is trivially satisfied for $A = \emptyset$, thus, let us assume that it holds for $A = (a_1, \dots, a_p)$ and show it for $A^0 = (a_0, A) = (a_0, a_1, \dots, a_p)$. We do this in two steps. First, the following combinatorial identity is proven

$$\sum_{i=1}^{p+1} (-1)^i (a_0, A_{1, i}) \sqcup \tilde{A}_{i, p+1} = -(\tilde{A}, a_0). \quad (\text{A.26})$$

It is trivially satisfied for $A = \emptyset$ and for $A = (a_1)$, it takes the form

$$(-1)(a_0) \sqcup (a_1) + (a_0, a_1) = -(a_1, a_0). \quad (\text{A.27})$$

The induction step can be obtained using the recursive definition of the shuffle product

$$\begin{aligned} \sum_{i=1}^{p+1} (-1)^i (a_0, A_{1,i}) \sqcup \tilde{A}_{i,p+1} &= \sum_{i=1}^{p+1} (-1)^i (a_0, (A_{1,i} \sqcup \tilde{A}_{i,p+1})) + \sum_{i=1}^p (-1)^i (a_p, (a_0, A_{1,i} \sqcup \tilde{A}_{i,p})) \\ &= -(a_0, \tilde{A}) + \sum_{i=2}^{p+1} (-1)^i (a_0, (A_{1,i} \sqcup \tilde{A}_{i,p+1})) - (\tilde{A}, a_0) \\ &= -(a_0, \tilde{A}) - \sum_{i=2}^{p+1} (-1)^{i-1} (a_0, (a_1, A_{2,i} \sqcup \tilde{A}_{i,p+1})) - (\tilde{A}, a_0) \\ &= -(a_0, \tilde{A}) + (a_0, \tilde{A}) - (\tilde{A}, a_0) \\ &= -(\tilde{A}, a_0). \end{aligned} \quad (\text{A.28})$$

Second, we use concatenation and the induction step to write

$$\begin{aligned} &\varphi^\tau(r_0, a_0, A, r_1, B) \\ &= \Omega_{r_0, a_0}(\eta_{a_0} + \eta_A + \eta_{r_1} + \eta_B) \varphi^\tau(a_0, A, r_1, B) \\ &= \Omega_{r_0, a_0}(\eta_{a_0} + \eta_A + \eta_{r_1} + \eta_B) \sum_{i=1}^{p+1} (-1)^{p+1-i} \varphi^\tau(a_0, A_{1i}) \varphi^\tau(a_0, r_1, \tilde{A}_{i,p+1} \sqcup B) \end{aligned} \quad (\text{A.29})$$

and apply the Fay identity

$$\begin{aligned} &\Omega_{r_0, a_0}(\eta_{a_0} + \eta_A + \eta_{r_1} + \eta_B) \Omega_{a_0, r_1}(\eta_{a_i, \dots, a_p} + \eta_{r_1} + \eta_B) \\ &= \Omega_{r_0, a_0}(\eta_{a_0, \dots, a_{i-1}}) \Omega_{r_0, r_1}(\eta_{a_i, \dots, a_p} + \eta_{r_1} + \eta_B) \\ &\quad - \Omega_{r_0, r_1}(\eta_{a_0} + \eta_A + \eta_{r_1} + \eta_B) \Omega_{r_1, a_0}(\eta_{a_i, \dots, a_p} + \eta_{r_1} + \eta_B) \end{aligned} \quad (\text{A.30})$$

to obtain

$$\begin{aligned} &\varphi^\tau(r_0, a_0, A, r_1, B) \\ &= \Omega_{r_0, a_0}(\eta_{a_0} + \eta_A + \eta_{r_1} + \eta_B) \sum_{i=1}^{p+1} (-1)^{p+1-i} \varphi^\tau(a_0, A_{1i}) \varphi^\tau(a_0, r_1, \tilde{A}_{i,p+1} \sqcup B) \\ &= \sum_{i=1}^{p+1} (-1)^{p+1-i} \varphi^\tau(r_0, a_0, A_{1i}) \varphi^\tau(r_0, r_1, \tilde{A}_{i,p+1} \sqcup B) \\ &\quad - \Omega_{r_0, r_1}(\eta_{a_0} + \eta_A + \eta_{r_1} + \eta_B) \sum_{i=1}^{p+1} (-1)^{p+1-i} \varphi^\tau(r_1, a_0, A_{1i}) \varphi^\tau(r_1, \tilde{A}_{i,p+1} \sqcup B) \\ &= \sum_{i=1}^{p+1} (-1)^{p+1-i} \varphi^\tau(r_0, a_0, A_{1i}) \varphi^\tau(r_0, r_1, \tilde{A}_{i,p+1} \sqcup B) \\ &\quad - \Omega_{r_0, r_1}(\eta_{a_0} + \eta_A + \eta_{r_1} + \eta_B) \sum_{i=1}^{p+1} (-1)^{p+1-i} \varphi^\tau(r_1, (a_0, A_{1i}) \sqcup \tilde{A}_{i,p+1} \sqcup B) \\ &= \sum_{i=2}^{p+2} (-1)^{p+2-i} \varphi^\tau(r_0, A_{1i}^0) \varphi^\tau(r_0, r_1, \tilde{A}_{i,p+1}^0 \sqcup B) \end{aligned}$$

$$\begin{aligned}
& -\Omega_{b_j, a_k}(\eta_a - \xi) \left(\Omega_{1,0}(\eta_a) \Omega_{0, b_j}(\eta_a + \eta_b) + \Omega_{1, b_j}(\eta_a + \eta_b) \Omega_{01}(\eta_b) \right) \\
&= \left(\Omega_{1, a_k}(\eta_a - \xi) \Omega_{1, b_j}(\eta_b + \xi) - \Omega_{b_j, a_k}(\eta_a - \xi) \Omega_{1, b_j}(\eta_a + \eta_b) \right) \Omega_{01}(\eta_b) \\
&\quad + \Omega_{1, a_k}(\eta_a - \xi) \Omega_{1,0}(\xi) \Omega_{0, b_j}(\eta_b + \xi) - \Omega_{b_j, a_k}(\eta_a - \xi) \Omega_{1,0}(\eta_a) \Omega_{0, b_j}(\eta_a + \eta_b) \\
&= \Omega_{1, a_k}(\eta_a + \eta_b) \Omega_{a_k, b_j}(\eta_b + \xi) \Omega_{01}(\eta_b) \\
&\quad + \Omega_{1, a_k}(\eta_a - \xi) \Omega_{1,0}(\xi) \Omega_{0, b_j}(\eta_b + \xi) - \Omega_{b_j, a_k}(\eta_a - \xi) \Omega_{1,0}(\eta_a) \Omega_{0, b_j}(\eta_a + \eta_b) \\
&\quad + \Omega_{1, a_k}(\eta_a - \xi) \Omega_{1,0}(\xi) \Omega_{0, b_j}(\eta_b + \xi) - \Omega_{b_j, a_k}(\eta_a - \xi) \Omega_{1,0}(\eta_a) \Omega_{0, b_j}(\eta_a + \eta_b) \\
&= \Omega_{01}(\eta_b) \Omega_{1, a_k}(\eta_a + \eta_b) \Omega_{a_k, b_j}(\eta_b + \xi) + \Omega_{01}(-\eta_a) \Omega_{0, b_j}(\eta_a + \eta_b) \Omega_{b_j, a_k}(\eta_a - \xi) \\
&\quad + \Omega_{1,0}(\xi) \Omega_{1, a_k}(\eta_a - \xi) \Omega_{0, b_j}(\eta_b + \xi), \tag{B.4}
\end{aligned}$$

which can be depicted as

$$\begin{array}{c} a_k \bullet \\ \downarrow \eta_a \\ 1 \bullet \end{array} \begin{array}{c} \xleftarrow{\xi} \\ \bullet \\ b_j \end{array} \begin{array}{c} \downarrow \eta_b \\ \bullet \\ 0 \end{array} = \begin{array}{c} a_k \bullet \\ \downarrow \eta_{ab} \\ 1 \bullet \end{array} \begin{array}{c} \xleftarrow{\xi} \\ \bullet \\ b_j \end{array} \begin{array}{c} \xrightarrow{\eta_b} \\ \bullet \\ 0 \end{array} + \begin{array}{c} a_k \bullet \\ \xrightarrow{-\eta_a} \\ 1 \bullet \end{array} \begin{array}{c} \xleftarrow{\xi} \\ \bullet \\ b_j \end{array} \begin{array}{c} \downarrow \eta_{ab} \\ \bullet \\ 0 \end{array} + \begin{array}{c} a_k \bullet \\ \downarrow \eta_a \\ 1 \bullet \end{array} \begin{array}{c} \xrightarrow{\xi} \\ \bullet \\ b_j \end{array} \begin{array}{c} \downarrow \eta_b \\ \bullet \\ 0 \end{array}, \tag{B.5}$$

while for $k \neq 0$ and $j = 0$

$$\Omega_{1, a_k}(\eta_a) \Omega_{a_k, 0}(\xi) = \Omega_{01}(-\eta_a) \Omega_{0, a_k}(\eta_a - \xi) + \Omega_{1,0}(\xi) \Omega_{1, a_k}(\eta_a - \xi), \tag{B.6}$$

depicted by

$$\begin{array}{c} \bullet \\ a_k \\ \downarrow \eta_a \\ 1 \bullet \end{array} \begin{array}{c} \xrightarrow{\xi} \\ \bullet \\ 0 \end{array} = \begin{array}{c} \bullet \\ a_k \\ \downarrow \eta_a - \xi \\ 1 \bullet \end{array} \begin{array}{c} \xrightarrow{-\eta_a} \\ \bullet \\ 0 \end{array} + \begin{array}{c} \bullet \\ a_k \\ \downarrow \eta_a - \xi \\ 1 \bullet \end{array} \begin{array}{c} \xrightarrow{\xi} \\ \bullet \\ 0 \end{array}, \tag{B.7}$$

and for $k = 0$ and $j \neq 0$

$$\Omega_{1, b_j}(\xi) \Omega_{0, b_j}(\eta_b) = \Omega_{01}(\eta_b) \Omega_{1, b_j}(\eta_b + \xi) + \Omega_{1,0}(\xi) \Omega_{0, b_j}(\eta_b + \xi), \tag{B.8}$$

i.e.

$$\begin{array}{c} \bullet \\ b_j \\ \downarrow \eta_b \\ 1 \bullet \end{array} \begin{array}{c} \xrightarrow{\xi} \\ \bullet \\ 0 \end{array} = \begin{array}{c} \bullet \\ b_j \\ \downarrow \eta_b + \xi \\ 1 \bullet \end{array} \begin{array}{c} \xrightarrow{\eta_b} \\ \bullet \\ 0 \end{array} + \begin{array}{c} \bullet \\ b_j \\ \downarrow \eta_b + \xi \\ 1 \bullet \end{array} \begin{array}{c} \xrightarrow{\xi} \\ \bullet \\ 0 \end{array}. \tag{B.9}$$

The procedure to rewrite the Ω_{a_k, b_j} in eq. (B.2) is the following: first, we move the indices a_k and b_j in $\varphi^\tau(1, A) \varphi^\tau(0, B)$ next to 1 and 0, respectively, by means of eq. (A.14), which yields for $k \neq 0$

$$\begin{aligned}
\varphi^\tau(1, A) &= \varphi^\tau(1, A_{1, k}, a_k, A_{k+1, p+1}) \\
&= \sum_{i=1}^k (-1)^{k-i} \varphi^\tau(1, A_{1i}) \varphi^\tau(1, a_k, \tilde{A}_{i, k} \sqcup A_{k+1, p+1}) \\
&= \sum_{i=1}^k (-1)^{k-i} \varphi^\tau(1, A_{1i}) \varphi^\tau(a_k, \tilde{A}_{i, k} \sqcup A_{k+1, p+1}) \Omega_{1, a_k}(\eta_{A_i, p+1}), \tag{B.10}
\end{aligned}$$

i.e.

$$\begin{array}{c} a_p \\ \vdots \\ a_k \\ \vdots \\ a_2 \\ \downarrow \\ a_1 \\ \downarrow \\ 1 \end{array} = \sum_{i=1}^k (-1)^{k-i} \begin{array}{c} \bullet \quad \bullet \\ \vdots \quad \vdots \\ a_{i-1} \quad a_{k-1} \quad a_{k+1} \\ \vdots \quad \vdots \\ a_1 \quad a_k \\ \downarrow \quad \downarrow \\ 1 \end{array}, \quad (\text{B.11})$$

and for $j \neq 0$

$$\begin{aligned} \varphi^\tau(0, B) &= \varphi^\tau(0, B_{1,j}, b_j, B_{j+1,q+1}) \\ &= \sum_{l=1}^j (-1)^{j-l} \varphi^\tau(0, B_{1l}) \varphi^\tau(0, b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1}) \\ &= \sum_{l=1}^j (-1)^{j-l} \varphi^\tau(0, B_{1l}) \varphi^\tau(b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1}) \Omega_{0,b_j}(\eta_{B_{l,q+1}}), \end{aligned} \quad (\text{B.12})$$

i.e.

$$\begin{array}{c} b_q \\ \vdots \\ b_j \\ \vdots \\ b_2 \\ \downarrow \\ b_1 \\ \downarrow \\ 0 \end{array} = \sum_{l=1}^j (-1)^{j-l} \begin{array}{c} \bullet \quad \bullet \\ \vdots \quad \vdots \\ b_{j+1} \quad b_{j-1} \quad b_{l-1} \\ \vdots \quad \vdots \\ b_j \quad b_1 \\ \downarrow \quad \downarrow \\ 0 \end{array}. \quad (\text{B.13})$$

As a consequence, for $k, j \neq 0$

$$\begin{aligned} &\Omega_{a_k, b_j}(\xi) \varphi^\tau(1, A) \varphi^\tau(0, B) \\ &= \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \varphi^\tau(1, A_{1i}) \varphi^\tau(a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1}) \varphi^\tau(0, B_{1l}) \varphi^\tau(b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1}) \\ &\quad \Omega_{1,a_k}(\eta_{A_{i,p+1}}) \Omega_{a_k, b_j}(\xi) \Omega_{0,b_j}(\eta_{B_{l,q+1}}), \end{aligned} \quad (\text{B.14})$$

i.e.

$$\begin{array}{c} a_p \\ \vdots \\ a_k \\ \vdots \\ a_2 \\ \downarrow \eta_{a_{23\dots p}} \\ a_1 \\ \downarrow \eta_A \\ 1 \end{array} \quad \begin{array}{c} \bullet \\ \vdots \\ b_j \\ \vdots \\ b_2 \\ \downarrow \eta_{b_{23\dots q}} \\ b_1 \\ \downarrow \eta_B \\ 0 \end{array} \xrightarrow{\xi} \begin{array}{c} \bullet \quad \bullet \\ \vdots \quad \vdots \\ a_{i-1} \quad a_{k-1} \quad a_{k+1} \quad b_{j+1} \quad b_{j-1} \quad b_{l-1} \\ \vdots \quad \vdots \\ a_1 \quad a_k \quad b_j \quad b_1 \\ \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \\ 1 \quad 0 \end{array}, \quad (\text{B.15})$$

for $k \neq 0, j = 0$

$$\begin{aligned} & \Omega_{a_k,0}(\xi)\varphi^\tau(1,A)\varphi^\tau(0,B) \\ &= \sum_{i=1}^k (-1)^{k-i}\varphi^\tau(1,A_{1i})\varphi^\tau(a_k,\tilde{A}_{i,k} \sqcup A_{k+1,p+1})\varphi^\tau(0,B)\Omega_{1,a_k}(\eta_{A_i,p+1})\Omega_{a_k,0}(\xi) \end{aligned} \quad (\text{B.16})$$

i.e.

$$= \sum_{i=1}^k (-1)^{k-i} \text{[Diagrammatic sum]}, \quad (\text{B.17})$$

and for $k = 0, j \neq 0$

$$\begin{aligned} & \Omega_{a_k,b_j}(\xi)\varphi^\tau(1,A)\varphi^\tau(0,B) \\ &= \sum_{l=1}^j (-1)^{j-l}\varphi^\tau(1,A)\varphi^\tau(0,B_{1l})\varphi^\tau(b_j,\tilde{B}_{l,j} \sqcup B_{j+1,q+1})\Omega_{1,b_j}(\xi)\Omega_{0,b_j}(\eta_{B_{l,q+1}}), \end{aligned} \quad (\text{B.18})$$

i.e.

$$= \sum_{l=1}^j (-1)^{j-l} \text{[Diagrammatic sum]}. \quad (\text{B.19})$$

At this point, we can apply the identity (B.4) in (B.14), (B.6) in (B.16) and (B.8) in (B.18) to the triangles or squares formed by the vertices 1, 0, a_k and/or b_j in the corresponding graphs, which leads to two (for $k = 0$ or $j = 0$) or three distinct sums. For $k, j \neq 0$, we obtain

$$\begin{aligned} & \Omega_{a_k,b_j}(\xi)\varphi^\tau(1,A)\varphi^\tau(0,B) \\ &= \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l}\varphi^\tau(1,A_{1i})\varphi^\tau(a_k,\tilde{A}_{i,k} \sqcup A_{k+1,p+1})\varphi^\tau(0,B_{1l})\varphi^\tau(b_j,\tilde{B}_{l,j} \sqcup B_{j+1,q+1}) \\ & \quad \left(\Omega_{01}(\eta_{B_{l,q+1}})\Omega_{1,a_k}(\eta_{A_i,p+1} + \eta_{B_{l,q+1}})\Omega_{a_k,b_j}(\eta_{B_{l,q+1}} + \xi) \right. \\ & \quad + \Omega_{01}(-\eta_{A_i,p+1})\Omega_{0,b_j}(\eta_{A_i,p+1} + \eta_{B_{l,q+1}})\Omega_{b_j,a_k}(\eta_{A_i,p+1} - \xi) \\ & \quad \left. + \Omega_{1,0}(\xi)\Omega_{1,a_k}(\eta_{A_i,p+1} - \xi)\Omega_{0,b_j}(\eta_{B_{l,q+1}} + \xi) \right), \end{aligned} \quad (\text{B.20})$$

i.e.

$$\begin{aligned}
& \left(\begin{array}{c} a_p \\ \vdots \\ a_k \\ \vdots \\ a_2 \\ a_1 \\ 1 \end{array} \leftarrow \xi \begin{array}{c} b_q \\ \vdots \\ b_j \\ \vdots \\ b_2 \\ b_1 \\ 0 \end{array} \right) = \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \\
& \times \left(\begin{array}{c} a_i \\ \vdots \\ a_{i-1} \\ a_1 \\ 1 \end{array} \begin{array}{c} a_k \\ \vdots \\ a_{k-1} \\ a_k \\ 1 \end{array} \begin{array}{c} a_p \\ \vdots \\ a_{k+1} \\ 0 \end{array} \left(\begin{array}{c} a_k \\ \vdots \\ 1 \end{array} \begin{array}{c} b_j \\ \vdots \\ 0 \end{array} \begin{array}{c} a_k \\ \vdots \\ 1 \end{array} \begin{array}{c} b_j \\ \vdots \\ 0 \end{array} \begin{array}{c} a_k \\ \vdots \\ 1 \end{array} \begin{array}{c} b_j \\ \vdots \\ 0 \end{array} \right) \begin{array}{c} b_q \\ \vdots \\ b_{j+1} \\ b_j \\ \vdots \\ b_{j-1} \\ b_{l-1} \\ b_l \\ \vdots \\ b_1 \\ 0 \end{array} \right) \quad (\text{B.21})
\end{aligned}$$

The last sum, with the factor $\Omega_{1,0}(\xi)\Omega_{1,a_k}(\eta_{A_i,p+1} - \xi)\Omega_{0,b_j}(\eta_{B_{l,q+1}} + \xi)$, can be rewritten in terms of the original chains, using eqs. (B.10) and (B.12) in the reverse direction, leaving a shift of $\mp\xi$ in the variables η_{a_k} and η_{b_j} , respectively,

$$\begin{aligned}
& \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \varphi^\tau(1, A_{1i}) \varphi^\tau(a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1}) \varphi^\tau(0, B_{1l}) \varphi^\tau(b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1}) \\
& \Omega_{1,0}(\xi) \Omega_{1,a_k}(\eta_{A_i,p+1} - \xi) \Omega_{0,b_j}(\eta_{B_{l,q+1}} + \xi) \\
& = \Omega_{1,0}(\xi) \varphi^\tau(1, A) |_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi} \varphi^\tau(0, B) |_{\eta_{b_j} \rightarrow \eta_{b_j} + \xi}. \quad (\text{B.22})
\end{aligned}$$

The remaining two sums in eq. (B.20) can either be written in terms of products of two chains, the first starting at 1 and the second at 0. This will yield the closed formula for the derivatives of $Z_{0,n}^\tau$. Or, they can be expressed in terms of the S-map. Both formulæ are derived in the next two subsections.

To summarize, we have so far for $k, j \neq 0$ the identity

$$\begin{aligned}
& \Omega_{a_k,b_j}(\xi) \varphi^\tau(1, A) \varphi^\tau(0, B) = \Omega_{1,0}(\xi) \varphi^\tau(1, A) |_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi} \varphi^\tau(0, B) |_{\eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\
& + \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \varphi^\tau(1, A_{1i}) \varphi^\tau(a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1}) \varphi^\tau(0, B_{1l}) \varphi^\tau(b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1}) \\
& \left(\Omega_{01}(\eta_{B_{l,q+1}}) \Omega_{1,a_k}(\eta_{A_i,p+1} + \eta_{B_{l,q+1}}) \Omega_{a_k,b_j}(\eta_{B_{l,q+1}} + \xi) \right. \\
& \left. + \Omega_{01}(-\eta_{A_i,p+1}) \Omega_{0,b_j}(\eta_{A_i,p+1} + \eta_{B_{l,q+1}}) \Omega_{b_j,a_k}(\eta_{A_i,p+1} - \xi) \right), \quad (\text{B.23})
\end{aligned}$$

i.e.

$$\begin{aligned}
 & \left(\begin{array}{c} \bullet a_p \\ \vdots \\ \bullet a_k \xleftarrow{\xi} \bullet b_j \\ \vdots \\ \bullet a_2 \\ \downarrow \eta_{a_{23\dots p}} \\ \bullet a_1 \\ \downarrow \eta_A \\ \bullet 1 \end{array} \begin{array}{c} \bullet b_q \\ \vdots \\ \bullet b_j \\ \vdots \\ \bullet b_2 \\ \downarrow \eta_{b_{23\dots q}} \\ \bullet b_1 \\ \downarrow \eta_B \\ \bullet 0 \end{array} \right) = \begin{array}{c} \bullet a_p \\ \vdots \\ \bullet a_{k+1} \\ \downarrow \eta_{a_{k+1\dots p}} \\ \bullet a_k \\ \downarrow \eta_{a_{k\dots p} - \xi} \\ \bullet a_{k-1} \\ \vdots \\ \bullet a_1 \\ \downarrow \eta_A - \xi \\ \bullet 1 \end{array} \begin{array}{c} \bullet b_q \\ \vdots \\ \bullet b_{j+1} \\ \downarrow \eta_{b_{j+1\dots q}} \\ \bullet b_j \\ \downarrow \eta_{b_{j\dots q} + \xi} \\ \bullet b_{j-1} \\ \vdots \\ \bullet b_1 \\ \downarrow \eta_B + \xi \\ \bullet 0 \end{array} + \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \\
 & \times \left(\begin{array}{c} \bullet a_i \quad \bullet a_p \quad \bullet b_q \quad \bullet b_l \\ \vdots \quad \vdots \quad \vdots \quad \vdots \\ \bullet a_{i-1} \quad \bullet a_{k-1} \quad \bullet a_{k+1} \quad \bullet b_{j+1} \quad \bullet b_{j-1} \quad \bullet b_{l-1} \\ \swarrow \quad \downarrow \eta_{b_{l\dots q} + \xi} \quad \swarrow \\ \bullet a_1 \quad \bullet a_k \quad \bullet b_j \quad \bullet b_1 \\ \downarrow \eta_{a_{i\dots p} + \eta_{b_{l\dots q}}} \quad \downarrow \eta_{a_{i\dots p} - \xi} \\ \bullet 1 \quad \bullet 0 \end{array} + \begin{array}{c} \bullet a_i \quad \bullet a_p \quad \bullet b_q \quad \bullet b_l \\ \vdots \quad \vdots \quad \vdots \quad \vdots \\ \bullet a_{i-1} \quad \bullet a_{k-1} \quad \bullet a_{k+1} \quad \bullet b_{j+1} \quad \bullet b_{j-1} \quad \bullet b_{l-1} \\ \swarrow \quad \downarrow \eta_{a_{i\dots p} - \xi} \quad \swarrow \\ \bullet a_1 \quad \bullet a_k \quad \bullet b_j \quad \bullet b_1 \\ \downarrow \eta_{a_{i\dots p} + \eta_{b_{l\dots q}}} \quad \downarrow -\eta_{a_{i\dots p}} \\ \bullet 1 \quad \bullet 0 \end{array} \right), \quad (\text{B.24})
 \end{aligned}$$

for $k \neq 0, j = 0$

$$\begin{aligned}
 \Omega_{a_k,0}(\xi) \varphi^\tau(1, A) \varphi^\tau(0, B) &= \Omega_{1,0}(\xi) \varphi^\tau(1, A) |_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi} \varphi^\tau(0, B) \\
 &+ \sum_{i=1}^k (-1)^{k-i} \varphi^\tau(1, A_{1i}) \varphi^\tau(a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1}) \varphi^\tau(0, B) \Omega_{01}(-\eta_{A_i,p+1}) \Omega_{0,a_k}(\eta_{A_i,p+1} - \xi), \quad (\text{B.25})
 \end{aligned}$$

i.e.

$$\begin{aligned}
 & \left(\begin{array}{c} \bullet a_p \\ \vdots \\ \bullet a_k \xrightarrow{\xi} \bullet b_j \\ \vdots \\ \bullet a_2 \\ \downarrow \eta_{a_{23\dots p}} \\ \bullet a_1 \\ \downarrow \eta_A \\ \bullet 1 \end{array} \begin{array}{c} \bullet b_q \\ \vdots \\ \bullet b_2 \\ \downarrow \eta_{b_{23\dots q}} \\ \bullet b_1 \\ \downarrow \eta_B \\ \bullet 0 \end{array} \right) = \begin{array}{c} \bullet a_p \\ \vdots \\ \bullet a_{k+1} \\ \downarrow \eta_{a_{k+1\dots p}} \\ \bullet a_k \\ \downarrow \eta_{a_{k\dots p} - \xi} \\ \bullet a_{k-1} \\ \vdots \\ \bullet a_1 \\ \downarrow \eta_A - \xi \\ \bullet 1 \end{array} \begin{array}{c} \bullet b_q \\ \vdots \\ \bullet b_j \\ \downarrow \eta_{b_{j\dots q} + \xi} \\ \bullet b_{j-1} \\ \vdots \\ \bullet b_1 \\ \downarrow \eta_B + \xi \\ \bullet 0 \end{array} + \sum_{i=1}^k (-1)^{k-i} \begin{array}{c} \bullet a_i \quad \bullet a_p \quad \bullet b_q \\ \vdots \quad \vdots \quad \vdots \\ \bullet a_{i-1} \quad \bullet a_{k-1} \quad \bullet a_{k+1} \\ \swarrow \quad \downarrow \eta_{a_{i\dots p} - \xi} \quad \swarrow \\ \bullet a_1 \quad \bullet a_k \quad \bullet b_j \\ \downarrow \eta_{a_{i\dots p} - \xi} \quad \downarrow -\eta_{a_{i\dots p}} \\ \bullet 1 \quad \bullet 0 \end{array}, \quad (\text{B.26})
 \end{aligned}$$

and for $k = 0, j \neq 0$

$$\begin{aligned}
 \Omega_{1,b_j}(\xi) \varphi^\tau(1, A) \varphi^\tau(0, B) &= \Omega_{1,0}(\xi) \varphi^\tau(1, A) \varphi^\tau(0, B) |_{\eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\
 &+ \sum_{l=1}^j (-1)^{j-l} \varphi^\tau(1, A) \varphi^\tau(0, B_{1l}) \varphi^\tau(b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1}) \Omega_{01}(\eta_{B_{l,q+1}}) \Omega_{1,b_j}(\eta_{B_{l,q+1}} + \xi). \quad (\text{B.27})
 \end{aligned}$$

i.e.

$$\begin{array}{c}
\bullet b_q \\
\vdots \\
\bullet b_j \\
\eta_{b_{j+1}\dots q} \\
\bullet b_j \\
\eta_{b_{j\dots q} + \xi} \\
\bullet b_{j-1} \\
\vdots \\
\bullet b_1 \\
\eta_B + \xi \\
\bullet 0
\end{array}
=
\begin{array}{c}
\bullet a_p \\
\vdots \\
\bullet a_2 \\
\vdots \\
\bullet a_1 \\
\vdots \\
\bullet 1
\end{array}
\begin{array}{c}
\bullet b_q \\
\vdots \\
\bullet b_j \\
\eta_{b_{23}\dots q} \\
\bullet b_2 \\
\vdots \\
\bullet b_1 \\
\eta_B \\
\bullet 0
\end{array}
+ \sum_{l=1}^j (-1)^{j-l}
\begin{array}{c}
\bullet a_p \\
\vdots \\
\bullet a_2 \\
\vdots \\
\bullet a_1 \\
\vdots \\
\bullet 1
\end{array}
\begin{array}{c}
\bullet b_q \\
\vdots \\
\bullet b_{j+1} \\
\vdots \\
\bullet b_{j-1} \\
\vdots \\
\bullet b_l \\
\vdots \\
\bullet b_j \\
\eta_{b_{l\dots q} + \xi} \\
\bullet b_{j-1} \\
\vdots \\
\bullet b_1 \\
\eta_{b_{l\dots q}} \\
\bullet 0
\end{array}
\quad (B.28)$$

B.2 Closed formula

The closed-form expression (4.21) is obtained from eqs. (B.23) to (B.27) by multiple applications of the shuffle identity (A.8) and the concatenation (A.6).

For $k, j \neq 1$, the first sum in eq. (B.23) is given by

$$\begin{aligned}
& \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \varphi^\tau(1, A_{1i}) \varphi^\tau(a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1}) \varphi^\tau(0, B_{1l}) \varphi^\tau(b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1}) \\
& \quad \Omega_{01}(\eta_{B_{l,q+1}}) \Omega_{1,a_k}(\eta_{A_{i,p+1}} + \eta_{B_{l,q+1}}) \Omega_{a_k,b_j}(\eta_{B_{l,q+1}} + \xi) \\
& = \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \Omega_{01}(\eta_{B_{l,q+1}}) \varphi^\tau(0, B_{1l}) \varphi^\tau(1, A_{1i}) \\
& \quad \Omega_{1,a_k}(\eta_{A_{i,p+1}} + \eta_{B_{l,q+1}}) \varphi^\tau(a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1}) \varphi^\tau(a_k, b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1})|_{\eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\
& = \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \Omega_{01}(\eta_{B_{l,q+1}}) \varphi^\tau(0, B_{1l}) \varphi^\tau(1, A_{1i}) \\
& \quad \varphi^\tau(1, a_k, (\tilde{A}_{i,k} \sqcup A_{k+1,p+1}) \sqcup (b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1}))|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\
& = \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \Omega_{01}(\eta_{B_{l,q+1}}) \varphi^\tau(0, B_{1l}) \\
& \quad \varphi^\tau(1, A_{1i} \sqcup (a_k, (\tilde{A}_{i,k} \sqcup A_{k+1,p+1}) \sqcup (b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1})))|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_{b_j} \rightarrow \eta_{b_j} + \xi} \quad (B.29)
\end{aligned}$$

and similarly for the second sum

$$\begin{aligned}
& \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \varphi^\tau(1, A_{1i}) \varphi^\tau(a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1}) \varphi^\tau(0, B_{1l}) \varphi^\tau(b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1}) \\
& \quad + \Omega_{01}(-\eta_{A_{i,p+1}}) \Omega_{0,b_j}(\eta_{A_{i,p+1}} + \eta_{B_{l,q+1}}) \Omega_{b_j,a_k}(\eta_{A_{i,p+1}} - \xi)
\end{aligned}$$

$$\begin{aligned}
&= \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \Omega_{01}(-\eta_{A_{i,p+1}}) \varphi^\tau(1, A_{1i}) \\
&\quad \varphi^\tau(0, B_{1l} \sqcup (b_j, (\tilde{B}_{l,j} \sqcup B_{j+1,q+1}) \sqcup (a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1})))|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_{b_j} \rightarrow \eta_{b_j} + \xi}. \quad (\text{B.30})
\end{aligned}$$

The sum in in eq. (B.25) for $k \neq 0$, $j = 0$ can be rewritten as

$$\begin{aligned}
&\sum_{i=1}^k (-1)^{k-i} \varphi^\tau(1, A_{1i}) \varphi^\tau(a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1}) \varphi^\tau(0, B) \Omega_{01}(-\eta_{A_{i,p+1}}) \Omega_{0,a_k}(\eta_{A_{i,p+1}} - \xi) \\
&= \sum_{i=1}^k (-1)^{k-i} \Omega_{01}(-\eta_{A_{i,p+1}}) \varphi^\tau(1, A_{1i}) \varphi^\tau(0, a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1})|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi} \varphi^\tau(0, B) \\
&= \sum_{i=1}^k (-1)^{k-i} \Omega_{01}(-\eta_{A_{i,p+1}}) \varphi^\tau(1, A_{1i}) \varphi^\tau(0, B \sqcup (a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1}))|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi} \quad (\text{B.31})
\end{aligned}$$

and, similarly, the one in eq. (B.27) for $k = 0$, $j \neq 0$ as follows

$$\begin{aligned}
&\sum_{l=1}^j (-1)^{j-l} \varphi^\tau(1, A) \varphi^\tau(0, B_{1l}) \varphi^\tau(b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1}) \Omega_{01}(\eta_{B_{l,q+1}}) \Omega_{1,b_j}(\eta_{B_{l,q+1}} + \xi) \\
&= \sum_{l=1}^j (-1)^{j-l} \Omega_{01}(\eta_{B_{l,q+1}}) \varphi^\tau(0, B_{1l}) \varphi^\tau(1, A \sqcup (b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1}))|_{\eta_{b_j} \rightarrow \eta_{b_j} + \xi} \quad (\text{B.32})
\end{aligned}$$

Plugging eqs. (B.29) and (B.30) into (B.23), we can conclude that for $k, j \neq 1$

$$\begin{aligned}
&\Omega_{a_k, b_j}(\xi) \varphi^\tau(1, A) \varphi^\tau(0, B) = \Omega_{1,0}(\xi) \varphi^\tau(1, A)|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi} \varphi^\tau(0, B)|_{\eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\
&+ \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \Omega_{01}(\eta_{B_{l,q+1}}) \varphi^\tau(0, B_{1l}) \\
&\quad \varphi^\tau(1, A_{1i} \sqcup (a_k, (\tilde{A}_{i,k} \sqcup A_{k+1,p+1}) \sqcup (b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1})))|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\
&+ \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \Omega_{01}(-\eta_{A_{i,p+1}}) \varphi^\tau(1, A_{1i}) \\
&\quad \varphi^\tau(0, B_{1l} \sqcup (b_j, (\tilde{B}_{l,j} \sqcup B_{j+1,q+1}) \sqcup (a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1})))|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_{b_j} \rightarrow \eta_{b_j} + \xi}, \quad (\text{B.33})
\end{aligned}$$

the corresponding graphical equation is obtained from eq. (B.24) by simply folding back any branch fork to a sum of single chains using the shuffle product, while all the η -variables and the corresponding shifts $\pm\xi$ stay the same (and will not be depicted in the following equation for

notational simplicity)

$$\begin{aligned}
& \left(\begin{array}{c} a_p \\ \vdots \\ a_k \\ \vdots \\ a_2 \\ a_1 \\ 1 \end{array} \begin{array}{c} b_q \\ \vdots \\ b_j \\ \vdots \\ b_2 \\ b_1 \\ 0 \end{array} \right) = \begin{array}{c} a_p \\ \vdots \\ a_{k+1} \\ a_k \\ \vdots \\ a_{k-1} \\ a_1 \\ 1 \end{array} \begin{array}{c} b_q \\ \vdots \\ b_{j+1} \\ b_j \\ \vdots \\ b_{j-1} \\ b_1 \\ 0 \end{array} + \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \\
& \times \left(\begin{array}{c} a_i \quad a_p \quad b_q \quad b_l \\ \vdots \quad \vdots \quad \vdots \quad \vdots \\ a_{i-1} \quad a_{k-1} \quad a_{k+1} \quad b_{j+1} \quad b_{j-1} \quad b_{l-1} \\ \vdots \quad \sqcup \quad \vdots \quad \vdots \quad \vdots \quad \vdots \\ a_1 \quad a_k \quad \vdots \quad b_j \quad \vdots \quad b_1 \\ \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \\ 1 \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad 0 \end{array} \begin{array}{c} a_i \quad a_p \quad b_q \quad b_l \\ \vdots \quad \vdots \quad \vdots \quad \vdots \\ a_{i-1} \quad a_{k-1} \quad a_{k+1} \quad b_{j+1} \quad b_{j-1} \quad b_{l-1} \\ \vdots \quad \sqcup \quad \vdots \quad \vdots \quad \vdots \quad \vdots \\ a_1 \quad a_k \quad \vdots \quad b_j \quad \vdots \quad b_1 \\ \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \\ 1 \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad 0 \end{array} \right), \quad (\text{B.34})
\end{aligned}$$

and similarly using eq. (B.31) in eq. (B.25) yields for $k \neq 0$, $j = 0$

$$\begin{aligned}
\Omega_{a_k,0}(\xi) \varphi^\tau(1, A) \varphi^\tau(0, B) &= \Omega_{1,0}(\xi) \varphi^\tau(1, A) |_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi} \varphi^\tau(0, B) \\
&+ \sum_{i=1}^k (-1)^{k-i} \Omega_{01}(-\eta_{A_i, p+1}) \varphi^\tau(1, A_{1i}) \varphi^\tau(0, B \sqcup (a_k, \tilde{A}_{i,k} \sqcup A_{k+1, p+1})) |_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi}, \quad (\text{B.35})
\end{aligned}$$

which is also obtained from the graphs in eq. (B.26) by folding back any branches to a single chain using the shuffle product

$$\begin{aligned}
& \left(\begin{array}{c} a_p \\ \vdots \\ a_k \\ \vdots \\ a_2 \\ a_1 \\ 1 \end{array} \begin{array}{c} b_q \\ \vdots \\ b_j \\ \vdots \\ b_2 \\ b_1 \\ 0 \end{array} \right) = \begin{array}{c} a_p \\ \vdots \\ a_{k+1} \\ a_k \\ \vdots \\ a_{k-1} \\ a_1 \\ 1 \end{array} \begin{array}{c} b_q \\ \vdots \\ b_{j+1} \\ b_j \\ \vdots \\ b_{j-1} \\ b_1 \\ 0 \end{array} + \sum_{i=1}^k (-1)^{k-i} \\
& \left(\begin{array}{c} a_i \quad a_p \quad b_q \\ \vdots \quad \vdots \quad \vdots \\ a_{i-1} \quad a_{k-1} \quad a_{k+1} \\ \vdots \quad \sqcup \quad \vdots \\ a_1 \quad a_k \quad \vdots \\ \vdots \quad \vdots \quad \vdots \\ 1 \quad \vdots \quad \vdots \end{array} \begin{array}{c} b_l \\ \vdots \\ b_{l-1} \\ \vdots \\ b_1 \\ 0 \end{array} \right), \quad (\text{B.36})
\end{aligned}$$

and eq. (B.27) in (B.32) for $k = 0$, $j \neq 0$

$$\begin{aligned}
\Omega_{1,b_j}(\xi) \varphi^\tau(1, A) \varphi^\tau(0, B) &= \Omega_{1,0}(\xi) \varphi^\tau(1, A) \varphi^\tau(0, B) |_{\eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\
&+ \sum_{l=1}^j (-1)^{j-l} \Omega_{01}(\eta_{B_{l,q+1}}) \varphi^\tau(0, B_{1l}) \varphi^\tau(1, A \sqcup (b_j, \tilde{B}_{l,j} \sqcup B_{j+1, q+1})) |_{\eta_{b_j} \rightarrow \eta_{b_j} + \xi}, \quad (\text{B.37})
\end{aligned}$$

i.e. eq. (B.28) folded back

The above formulæ (B.33) to (B.37) yield the closed expressions for the partial derivatives of $Z_{0,n}^\tau((1, A), (0, B))$, since they contain two chains beginning at zero and one. For the z_0 -derivative, we can continue from eq. (B.1) using the fact that $f_{a_k, b_j}^{(1)}$ is the order zero ξ^0 -term of $\Omega_{a_k, b_j}(\xi)$, see eq. (B.2). Thus, eqs. (B.33) to (B.37) can be applied to extract the ξ^0 -term in

$$\partial_0 Z_{0,n}^\tau((1, A), (0, B)) = \sum_{k=0}^p \sum_{j=0}^q s_{a_k, b_j} \int_\gamma \prod_{i=2}^n dz_i \text{KN}_{01\dots n}^\tau \left(\Omega_{a_k, b_j}(\xi) \varphi^\tau(1, A) \varphi^\tau(0, B) \right) \Big|_{\xi^0}. \quad (\text{B.39})$$

The non-trivial extraction of the ξ^0 -term occurs in the term proportional to $\Omega_{10}(\xi)$ in eqs. (B.33) to (B.37), i.e. $\Omega_{1,0}(\xi) \varphi^\tau(1, A) \varphi^\tau(0, B)$ with some shifts in the η -variables, and can be treated using the expansion

$$\Omega_{1,0}(\xi) = \frac{1}{\xi} + f_{1,0}^{(1)} + \mathcal{O}(\xi) \quad (\text{B.40})$$

in ξ of the single factors to project out differential operators from the chains. The extraction in the remaining terms can be done by (expanding factors of the form $\Omega_{ij}(\eta + \xi)$ around ξ and simply setting $\xi = 0$. For a single factor of the Kronecker–Eisenstein series, we find for $k \neq 0$

$$\begin{aligned} & (\Omega_{1,0}(\xi) \Omega_{a_{k-1}, a_k}(\eta_{a_k} - \xi)) \Big|_{\xi^0} \\ &= \left(\left(\frac{1}{\xi} + f_{1,0}^{(1)} + \mathcal{O}(\xi) \right) \left(\Omega_{a_{k-1}, a_k}(\eta_{a_k}) - \xi \partial_{\eta_{a_k}} \Omega_{a_{k-1}, a_k}(\eta_{a_k}) + \mathcal{O}(\xi) \right) \right) \Big|_{\xi^0} \\ &= - \left(f_{01}^{(1)} + \partial_{\eta_{a_k}} \right) \Omega_{a_{k-1}, a_k}(\eta_{a_k}). \end{aligned} \quad (\text{B.41})$$

For a whole product, i.e. a chain, this procedure exactly reproduces the product rule due to the cross-terms and leads to

$$\begin{aligned} & \left(\Omega_{1,0}(\xi) \varphi^\tau(1, A) \Big|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi} \varphi^\tau(0, B) \Big|_{\eta_{b_j} \rightarrow \eta_{b_j} + \xi} \right) \Big|_{\xi^0} \\ &= - \left(f_{01}^{(1)} + \partial_{\eta_{a_k}} - \partial_{\eta_{b_j}} \right) \varphi^\tau(1, A) \varphi^\tau(0, B) \end{aligned} \quad (\text{B.42})$$

for $k, j \neq 0$. Putting everything together, one indeed arrives at the closed formula eq. (4.21) for $\partial_0 Z_{0,n}^\tau((1, A), (0, B))$.

B.3 S-map formula

Alternatively, the derivatives of $Z_{0,n}^\tau((1, A), (0, B))$ can be expressed in terms of the S -map as in eq. (4.26). For this purpose, we proceed from eq. (B.23) for $k, j \neq 0$ again using the shuffle identity (A.8) and the reflection property (A.12), but slightly differently than in the previous subsection: we want to keep a factor of $\Omega_{a_k, b_j}(\eta_{B_{l, q+1}} + \xi)$ or $\Omega_{b_j, a_k}(\eta_{A_{i, p+1}} - \xi)$ as a bridge between the chains of A and B . For the first sum in eq. (B.23), the calculation amounts to

$$\begin{aligned}
& \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \varphi^\tau(1, A_{1i}) \varphi^\tau(a_k, \tilde{A}_{i,k} \sqcup A_{k+1, p+1}) \varphi^\tau(0, B_{1l}) \varphi^\tau(b_j, \tilde{B}_{l,j} \sqcup B_{j+1, q+1}) \\
& \quad \Omega_{01}(\eta_{B_{l, q+1}}) \Omega_{1, a_k}(\eta_{A_{i, p+1}} + \eta_{B_{l, q+1}}) \Omega_{a_k, b_j}(\eta_{B_{l, q+1}} + \xi) \\
& = \sum_{l=1}^j (-1)^{j-l} \Omega_{01}(\eta_{B_{l, q+1}}) \varphi^\tau(0, B_{1l}) \varphi^\tau(a_k, b_j, \tilde{B}_{l,j} \sqcup B_{j+1, q+1})|_{\eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\
& \quad \sum_{i=1}^k (-1)^{k-i} \varphi^\tau(1, A_{1i}) \Omega_{1, a_k}(\eta_{A_{i, p+1}} + \eta_{B_{l, q+1}}) \varphi^\tau(a_k, \tilde{A}_{i,k}) \varphi^\tau(a_k, A_{k+1, p+1}) \\
& = \sum_{l=1}^j (-1)^{j-l} \Omega_{01}(\eta_{B_{l, q+1}}) \varphi^\tau(0, B_{1l}) \varphi^\tau(a_k, b_j, \tilde{B}_{l,j} \sqcup B_{j+1, q+1})|_{\eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\
& \quad \sum_{i=1}^k (-1)^{k-i} \varphi^\tau(1, A_{1i}) \varphi^\tau(1, a_k, \tilde{A}_{i,k})|_{\eta_{a_k} \rightarrow \eta_{A_{k, p+1}} + \eta_{B_{l, q+1}}} \varphi^\tau(a_k, A_{k+1, p+1}) \\
& = \sum_{l=1}^j (-1)^{j-l} \Omega_{01}(\eta_{B_{l, q+1}}) \varphi^\tau(0, B_{1l}) \varphi^\tau(a_k, b_j, \tilde{B}_{l,j} \sqcup B_{j+1, q+1})|_{\eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\
& \quad (-1)^{p-k} \varphi^\tau(1, A_{1,k}, a_k)|_{\eta_{a_k} \rightarrow \eta_{A_{k, p+1}} + \eta_{B_{l, q+1}}} \varphi^\tau(\tilde{A}_{k+1, p+1}, a_k)|_{\eta_{a_k} \rightarrow -\eta_{A_{k+1, p+1}}} \\
& = \sum_{l=1}^j (-1)^{p-k+j-l} \Omega_{01}(\eta_{B_{l, q+1}}) \varphi^\tau(0, B_{1l}) \varphi^\tau(a_k, b_j, \tilde{B}_{l,j} \sqcup B_{j+1, q+1})|_{\eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\
& \quad \varphi^\tau((1, A_{1,k}) \sqcup \tilde{A}_{k+1, p+1}, a_k)|_{\eta_{a_k} \rightarrow \eta_{a_k} + \eta_{B_{l, q+1}}} \\
& = \sum_{l=1}^j (-1)^{p-k+j-l} \Omega_{01}(\eta_{B_{l, q+1}}) \varphi^\tau(0, B_{1l}) \\
& \quad \varphi^\tau((1, A_{1,k}) \sqcup \tilde{A}_{k+1, p+1}, a_k, b_j, \tilde{B}_{l,j} \sqcup B_{j+1, q+1})|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_{b_j} \rightarrow \eta_{b_j} + \xi}, \tag{B.43}
\end{aligned}$$

where we applied the shuffle identity (A.8) and eq. (A.14) in the reverse direction in the first and third equality, respectively. The same calculation leads to a similar result for the second sum in eq. (B.23)

$$\begin{aligned}
& \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \varphi^\tau(1, A_{1i}) \varphi^\tau(a_k, \tilde{A}_{i,k} \sqcup A_{k+1, p+1}) \varphi^\tau(0, B_{1l}) \varphi^\tau(b_j, \tilde{B}_{l,j} \sqcup B_{j+1, q+1}) \\
& \quad \Omega_{01}(-\eta_{A_{i, p+1}}) \Omega_{0, b_j}(\eta_{A_{i, p+1}} + \eta_{B_{l, q+1}}) \Omega_{b_j, a_k}(\eta_{A_{i, p+1}} - \xi)
\end{aligned}$$

$$\begin{aligned}
&= \sum_{i=1}^k (-1)^{q-j+k-i} \Omega_{01}(-\eta_{A_i, p+1}) \varphi^\tau(1, A_{1i}) \\
&\quad \varphi^\tau((0, B_{1,j}) \sqcup \tilde{B}_{j+1, q+1}, b_j, a_k, \tilde{A}_{i,k} \sqcup A_{k+1, p+1})|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_{b_j} \rightarrow \eta_{b_j} + \xi}. \tag{B.44}
\end{aligned}$$

Similarly, we find for the sum in (B.25) for $k \neq 0, j = 0$

$$\begin{aligned}
&\sum_{i=1}^k (-1)^{k-i} \varphi^\tau(1, A_{1i}) \varphi^\tau(a_k, \tilde{A}_{i,k} \sqcup A_{k+1, p+1}) \varphi^\tau(0, B) \Omega_{01}(-\eta_{A_i, p+1}) \Omega_{0, a_k}(\eta_{A_i, p+1} - \xi) \\
&= \sum_{i=1}^k (-1)^{q+k-i} \varphi^\tau(\tilde{B}, 0, 1, A_{1i})|_{\eta_0 \rightarrow \eta_0 + A_i, p+1} \varphi^\tau(0, a_k, \tilde{A}_{i,k} \sqcup A_{k+1, p+1})|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi} \\
&= \sum_{i=1}^k (-1)^{q+k-i} \varphi^\tau(0, 1, A_{1i}) \varphi^\tau(\tilde{B}, 0, a_k, \tilde{A}_{i,k} \sqcup A_{k+1, p+1})|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_0 \rightarrow \eta_0 + \xi} \\
&= \sum_{i=1}^k (-1)^{q+k-i} \Omega_{01}(-\eta_{A_i, p+1}) \varphi^\tau(1, A_{1i}) \\
&\quad \varphi^\tau(\tilde{B}, 0, a_k, \tilde{A}_{i,k} \sqcup A_{k+1, p+1})|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_0 \rightarrow \eta_0 + \xi} \tag{B.45}
\end{aligned}$$

and for the sum in eq. (B.27) with $k = 0, j \neq 0$

$$\begin{aligned}
&\sum_{l=1}^j (-1)^{j-l} \varphi^\tau(1, A) \varphi^\tau(0, B_{1l}) \varphi^\tau(b_j, \tilde{B}_{l,j} \sqcup B_{j+1, q+1}) \Omega_{01}(\eta_{B_{l, q+1}}) \Omega_{1, b_j}(\eta_{B_{l, q+1}} + \xi) \\
&= \sum_{l=1}^j (-1)^{p+j-l} \Omega_{01}(\eta_{B_{l, q+1}}) \varphi^\tau(0, B_{1l}) \varphi^\tau(\tilde{A}, 1, b_j, \tilde{B}_{l,j} \sqcup B_{j+1, q+1})|_{\eta_1 \rightarrow \eta_1 - \xi, \eta_{b_j} \rightarrow \eta_{b_j} + \xi}. \tag{B.46}
\end{aligned}$$

Thus, the identity (B.23), valid for $k, j \neq 0$ can be rewritten as follows

$$\begin{aligned}
&\Omega_{a_k, b_j}(\xi) \varphi^\tau(1, A) \varphi^\tau(0, B) = \Omega_{1, 0}(\xi) \varphi^\tau(1, A)|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi} \varphi^\tau(0, B)|_{\eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\
&\quad + \sum_{l=1}^j (-1)^{p+1-k+j-l} \Omega_{01}(\eta_{B_{l, q+1}}) \varphi^\tau(0, B_{1l}) \\
&\quad \quad \varphi^\tau((1, A_{1,k}) \sqcup \tilde{A}_{k+1, p+1}, a_k, b_j, \tilde{B}_{l,j} \sqcup B_{j+1, q+1})|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\
&\quad + \sum_{i=1}^k (-1)^{q+1-j+k-i} \Omega_{01}(-\eta_{A_i, p+1}) \varphi^\tau(1, A_{1i}) \\
&\quad \quad \varphi^\tau((0, B_{1,j}) \sqcup \tilde{B}_{j+1, q+1}, b_j, a_k, \tilde{A}_{i,k} \sqcup A_{k+1, p+1})|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_{b_j} \rightarrow \eta_{b_j} + \xi}. \tag{B.47}
\end{aligned}$$

Graphically this equation is obtained from eq. (B.24) by absorbing the sum over i into the second term and the sum over j into the third term, to connect the vertices a_i with a_{i-1} and b_l with

b_{l-1} , respectively, leading to

$$\begin{aligned}
& + \sum_{l=1}^j (-1)^{p+1-k+j-l} \text{Diagram} \\
& + \sum_{i=1}^k (-1)^{q+1-j+k-i} \text{Diagram} \cdot
\end{aligned} \tag{B.48}$$

Similarly, the identity (B.25) for $k \neq 0$, $j = 0$ is given by

$$\begin{aligned}
\Omega_{a_k,0}(\xi) \varphi^\tau(1, A) \varphi^\tau(0, B) &= \Omega_{1,0}(\xi) \varphi^\tau(1, A) |_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi} \varphi^\tau(0, B) \\
&+ \sum_{i=1}^k (-1)^{q+k-i} \Omega_{01}(-\eta_{A_i, p+1}) \varphi^\tau(1, A_{1i}) \varphi^\tau(\tilde{B}, 0, a_k, \tilde{A}_{i,k} \sqcup A_{k+1, p+1}) |_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_0 \rightarrow \eta_0 + \xi},
\end{aligned} \tag{B.49}$$

i.e. obtained from eq. (B.26) by reverting the chain $\varphi^\tau(0, B)$

$$+ \sum_{i=1}^k (-1)^{q+k-i} \text{Diagram} \tag{B.50}$$

and eq. (B.27) for $k = 0, j \neq 0$ by

$$\begin{aligned} \Omega_{1,b_j}(\xi)\varphi^\tau(1, A)\varphi^\tau(0, B) &= \Omega_{1,0}(\xi)\varphi^\tau(1, A)\varphi^\tau(0, B)|_{\eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\ &+ \sum_{l=1}^j (-1)^{p+j-l} \Omega_{01}(\eta_{B_{l,q+1}})\varphi^\tau(0, B_{1l})\varphi^\tau(\tilde{A}, 1, b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1})|_{\eta_1 \rightarrow \eta_1 - \xi, \eta_{b_j} \rightarrow \eta_{b_j} + \xi}, \end{aligned} \quad (\text{B.51})$$

i.e.

$$\begin{aligned} & \left[\begin{array}{c} a_p \dots a_2 \downarrow \xi \nearrow b_j \dots b_2 \downarrow \eta_{b_{23\dots q}} \downarrow \eta_B \\ 1 \downarrow \xi \nearrow 0 \end{array} \right] = \left[\begin{array}{c} a_p \dots a_2 \downarrow \xi \nearrow 0 \\ 1 \downarrow \xi \nearrow 0 \end{array} \right] + \sum_{l=1}^j (-1)^{p+j-l} \left[\begin{array}{c} a_p \dots a_2 \downarrow \eta_{b_{l\dots q}} + \xi \nearrow b_j \dots b_{j-1} \downarrow \eta_B + \xi \\ 1 \downarrow \xi \nearrow 0 \end{array} \right]. \end{aligned} \quad (\text{B.52})$$

Note that these three identities indeed all have a factor of Ω_{a_k, b_j} , which is the backbone in the formulation in terms of the S -map. This can be seen by summing these identities over all $0 \leq k \leq p$ and $0 \leq j \leq q$

$$\begin{aligned} & \sum_{k=0}^p \sum_{j=0}^q s_{a_k, b_j} \Omega_{a_k, b_j}(\xi)\varphi^\tau(1, A)\varphi^\tau(0, B) \\ &= \sum_{k=0}^p \sum_{j=0}^q s_{a_k, b_j} \Omega_{1,0}(\xi)\varphi^\tau(1, A)|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi} \varphi^\tau(0, B)|_{\eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\ &+ \sum_{k=0}^p \sum_{j=1}^q s_{a_k, b_j} \sum_{l=1}^j (-1)^{p-k+j-l} \Omega_{01}(\eta_{B_{l,q+1}})\varphi^\tau(0, B_{1l}) \\ &\quad \varphi^\tau(A_{0,k} \sqcup \tilde{A}_{k+1,p+1}, a_k, b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1})|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\ &+ \sum_{k=1}^p \sum_{j=0}^q s_{a_k, b_j} \sum_{i=1}^k (-1)^{q-j+k-i} \Omega_{01}(-\eta_{A_{i,p+1}})\varphi^\tau(1, A_{1i}) \\ &\quad \varphi^\tau(B_{0,j} \sqcup \tilde{B}_{j+1,q+1}, b_j, a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1})|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\ &= \left(\sum_{k=0}^p \sum_{j=0}^q s_{a_k, b_j} \Omega_{1,0}(\xi)\varphi^\tau(1, A)\varphi^\tau(0, B) \right) |_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_{b_j} \rightarrow \eta_{b_j} + \xi} \\ &+ \sum_{l=1}^q \Omega_{01}(\eta_{B_{l,q+1}})\varphi^\tau(0, B_{1l}) \sum_{k=0}^p \sum_{j=l}^q (-1)^{p-k+j-l} s_{a_k, b_j} \\ &\quad \varphi^\tau(A_{0,k} \sqcup \tilde{A}_{k+1,p+1}, a_k, b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1})|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_{b_j} \rightarrow \eta_{b_j} + \xi} \end{aligned}$$

$$\begin{aligned}
& + \sum_{i=1}^p \Omega_{01}(-\eta_{A_i, p+1}) \varphi^\tau(1, A_{1i}) \sum_{k=i}^p \sum_{j=0}^q (-1)^{q-j+k-i} s_{a_k, b_j} \\
& \varphi^\tau(B_{0,j} \sqcup \tilde{B}_{j+1, q+1}, b_j, a_k, \tilde{A}_{i,k} \sqcup A_{k+1, p+1})|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_{b_j} \rightarrow \eta_{b_j} + \xi}. \tag{B.53}
\end{aligned}$$

Comparing with eq. (4.23), we see that the second and third sum explicitly involve the definition of the S -map, except for the shift $\mp \xi$ in the variables η_{a_k} and η_{b_j} .

In order to obtain the S -map representation of the z_0 -derivative eq. (B.39) we simply need to extract the ξ^0 part of eq. (B.53), where we immediately recover the S -map formula (4.26).

C Derivation of the n -point τ -derivative

In this section, we determine the action of $2\pi i \partial_\tau$ on the integrals $Z_{0,n}^\tau$ in eq. (4.6) to derive the corresponding formulæ (4.42) and (4.44). The techniques in this appendix generalize those in [1, 79], where the τ -derivatives of Z^τ -integrals without augmentation were studied²⁰. First, we recall that the τ -derivative of the Koba–Nielsen factor is given by eq. (4.40). Second, the action (up to integration by parts) on a chain

$$\varphi^\tau(C) = \prod_{i=2}^m \Omega_{c_{i-1}, i}(\eta_{c_i \dots c_m}), \quad \eta_{c_i \dots c_m} = \sum_{j=i}^m \eta_{c_j}, \tag{C.1}$$

with $C = (c_1, c_2, \dots, c_m)$ can be expressed using the mixed heat equation

$$2\pi i \partial_\tau \Omega_{ij}(\eta) = \partial_i \partial_\eta \Omega_{ij}(\eta) = -\partial_j \partial_\eta \Omega_{ij}(\eta) \tag{C.2}$$

for real z_i, z_j as follows:

$$\begin{aligned}
& 2\pi i \partial_\tau \varphi^\tau(C) \\
& = \sum_{i=2}^m \prod_{\substack{j=2 \\ j \neq i}}^m \Omega_{c_{j-1}, c_j}(\eta_{c_j \dots c_m}) 2\pi i \partial_\tau \Omega_{c_{i-1}, c_i}(\eta_{c_i \dots c_m}) \\
& = - \sum_{i=2}^m \prod_{\substack{j=2 \\ j \neq i}}^m \Omega_{c_{j-1}, c_j}(\eta_{c_j \dots c_m}) \partial_{c_i} \partial_{\eta_{c_i \dots c_m}} \Omega_{c_{i-1}, c_i}(\eta_{c_i \dots c_m}) \\
& = - \sum_{i=2}^m \left(\partial_{\eta_{c_i}} - \theta_{i \geq 3} \partial_{\eta_{c_{i-1}}} \right) \prod_{\substack{j=2 \\ j \neq i}}^m \Omega_{c_{j-1}, c_j}(\eta_{c_j \dots c_m}) \partial_{c_i} \Omega_{c_{i-1}, c_i}(\eta_{c_i \dots c_m}) \\
& = \sum_{i=2}^m \left(\partial_{\eta_{c_i}} - \theta_{i \geq 3} \partial_{\eta_{c_{i-1}}} \right) \prod_{\substack{j=2 \\ j \neq i+1}}^m \Omega_{c_{j-1}, c_j}(\eta_{c_j \dots c_m}) \left(\partial_{c_i} \Omega_{c_i, c_{i+1}}(\eta_{c_i \dots c_m}) + \Omega_{c_i, c_{i+1}}(\eta_{c_i \dots c_m}) \partial_{c_i} \right) \\
& = \sum_{i=2}^m \left(\partial_{\eta_{c_i}} - \theta_{i \geq 3} \partial_{\eta_{c_{i-1}}} \right) \prod_{\substack{j=2 \\ j \neq i+1}}^m \Omega_{c_{j-1}, c_j}(\eta_{c_j \dots c_m}) \left(-\partial_{c_{i+1}} \Omega_{c_i, c_{i+1}}(\eta_{c_i \dots c_m}) + \Omega_{c_i, c_{i+1}}(\eta_{c_i \dots c_m}) \partial_{c_i} \right) \\
& = \sum_{i=2}^m \left(\partial_{\eta_{c_i}} - \theta_{i \geq 3} \partial_{\eta_{c_{i-1}}} \right) \prod_{j=2}^m \Omega_{c_{j-1}, c_j}(\eta_{c_j \dots c_m}) \left(\sum_{k=i}^m \partial_{c_k} \right)
\end{aligned}$$

²⁰See in particular section 4 and appendix A of [1] as well as section 4 and appendix E of [79].

$$= \sum_{i=2}^m \left((\partial_{\eta_{c_i}} - \theta_{i \geq 3} \partial_{\eta_{c_{i-1}}}) \varphi^\tau(C) \right) \left(\sum_{k=i}^m \partial_{c_k} \right). \quad (\text{C.3})$$

We again use a step function $\theta_{j \geq k}$ which is taken to be 1 for $j \geq k$ and zero for $j < k$. Therefore, denoting $(1, A) = (a_0, a_1, \dots, a_p)$ and $(0, B) = (b_0, b_1, \dots, b_q)$ we find

$$\begin{aligned} & 2\pi i \partial_\tau (\text{KN}_{01\dots n}^\tau \varphi^\tau(1, A) \varphi^\tau(0, B)) \\ &= - \sum_{0 \leq i < j \leq n} s_{ij} \left(f_{ij}^{(2)} + 2\zeta_2 \right) \text{KN}_{01\dots n}^\tau \varphi^\tau(1, A) \varphi^\tau(0, B) \\ & \quad + \sum_{i=1}^p \left(\sum_{k=i}^p \partial_{a_k} \text{KN}_{01\dots n}^\tau \right) \varphi^\tau(0, B) \left(\partial_{\eta_{a_i}} - \theta_{i \geq 2} \partial_{\eta_{a_{i-1}}} \right) \varphi^\tau(1, A) \\ & \quad + \sum_{i=1}^q \left(\sum_{k=i}^q \partial_{b_k} \text{KN}_{01\dots n}^\tau \right) \varphi^\tau(1, A) \left(\partial_{\eta_{b_i}} - \theta_{i \geq 2} \partial_{\eta_{b_{i-1}}} \right) \varphi^\tau(0, B) \\ &= - \sum_{0 \leq i < j \leq n} s_{ij} \left(f_{ij}^{(2)} + 2\zeta_2 \right) \text{KN}_{01\dots n}^\tau \varphi^\tau(1, A) \varphi^\tau(0, B) \\ & \quad - \text{KN}_{01\dots n}^\tau \sum_{i=1}^p \left(\sum_{k=i}^p \sum_{j=0}^{i-1} s_{a_k, a_j} f_{a_k, a_j}^{(1)} + \sum_{k=i}^p \sum_{j=0}^q s_{a_k, b_j} f_{a_k, b_j}^{(1)} \right) \varphi^\tau(0, B) \left(\partial_{\eta_{a_i}} - \theta_{i \geq 2} \partial_{\eta_{a_{i-1}}} \right) \varphi^\tau(1, A) \\ & \quad - \text{KN}_{01\dots n}^\tau \sum_{i=1}^q \left(\sum_{k=i}^q \sum_{j=0}^{i-1} s_{b_k, b_j} f_{b_k, b_j}^{(1)} + \sum_{k=i}^q \sum_{j=0}^p s_{b_k, a_j} f_{b_k, a_j}^{(1)} \right) \varphi^\tau(1, A) \left(\partial_{\eta_{b_i}} - \theta_{i \geq 2} \partial_{\eta_{b_{i-1}}} \right) \varphi^\tau(0, B) \\ &= - \sum_{0 \leq i < j \leq n} s_{ij} \left(f_{ij}^{(2)} + 2\zeta_2 \right) \text{KN}_{01\dots n}^\tau \varphi^\tau(1, A) \varphi^\tau(0, B) \\ & \quad - \text{KN}_{01\dots n}^\tau \left(\sum_{k=1}^p \sum_{j=0}^{k-1} s_{a_k, a_j} f_{a_k, a_j}^{(1)} \sum_{i=j+1}^k + \sum_{k=1}^p \sum_{j=0}^q s_{a_k, b_j} f_{a_k, b_j}^{(1)} \sum_{i=1}^k \right) \\ & \quad \quad \times \varphi^\tau(0, B) \left(\partial_{\eta_{a_i}} - \theta_{i \geq 2} \partial_{\eta_{a_{i-1}}} \right) \varphi^\tau(1, A) \\ & \quad - \text{KN}_{01\dots n}^\tau \left(\sum_{k=1}^q \sum_{j=0}^{k-1} s_{b_k, b_j} f_{b_k, b_j}^{(1)} \sum_{i=j+1}^k + \sum_{k=1}^q \sum_{j=0}^p s_{b_k, a_j} f_{b_k, a_j}^{(1)} \sum_{i=1}^k \right) \\ & \quad \quad \times \varphi^\tau(1, A) \left(\partial_{\eta_{b_i}} - \theta_{i \geq 2} \partial_{\eta_{b_{i-1}}} \right) \varphi^\tau(0, B) \\ &= - \sum_{0 \leq i < j \leq n} s_{ij} \left(f_{ij}^{(2)} + 2\zeta_2 \right) \text{KN}_{01\dots n}^\tau \varphi^\tau(1, A) \varphi^\tau(0, B) \\ & \quad - \text{KN}_{01\dots n}^\tau \left(\sum_{k=1}^p \sum_{j=0}^{k-1} s_{a_k, a_j} f_{a_k, a_j}^{(1)} \left(\partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{a_j}} \right) \right) \varphi^\tau(0, B) \varphi^\tau(1, A) \\ & \quad - \text{KN}_{01\dots n}^\tau \left(\sum_{k=1}^q \sum_{j=0}^{k-1} s_{b_k, b_j} f_{b_k, b_j}^{(1)} \left(\partial_{\eta_{b_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} \right) \right) \varphi^\tau(0, B) \varphi^\tau(1, A) \\ & \quad - \text{KN}_{01\dots n}^\tau \left(\sum_{k=0}^p \sum_{j=0}^q s_{a_k, b_j} f_{a_k, b_j}^{(1)} \left(\theta_{k \geq 1} \partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} \right) \right) \varphi^\tau(1, A) \varphi^\tau(0, B) \\ &= - s_{01\dots n} 2\zeta_2 \text{KN}_{01\dots n}^\tau \varphi^\tau(1, A) \varphi^\tau(0, B) \\ & \quad - \text{KN}_{01\dots n}^\tau \sum_{k=1}^p \sum_{j=0}^{k-1} s_{a_k, a_j} \left(f_{a_k, a_j}^{(1)} \left(\partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{a_j}} \right) + f_{a_k, a_j}^{(2)} \right) \varphi^\tau(0, B) \varphi^\tau(1, A) \end{aligned}$$

$$\begin{aligned}
& - \text{KN}_{01\dots n}^\tau \sum_{k=1}^q \sum_{j=0}^{k-1} s_{b_k, b_j} \left(f_{b_k, b_j}^{(1)} \left(\partial_{\eta_{b_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} \right) + f_{b_k, b_j}^{(2)} \right) \varphi^\tau(0, B) \varphi^\tau(1, A) \\
& - \text{KN}_{01\dots n}^\tau \sum_{k=0}^p \sum_{j=0}^q s_{a_k, b_j} \left(f_{a_k, b_j}^{(1)} \left(\theta_{k \geq 1} \partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} \right) - f_{a_k, b_j}^{(2)} \right) \varphi^\tau(1, A) \varphi^\tau(0, B), \tag{C.4}
\end{aligned}$$

which implies eq. (4.41). As for eq. (B.1) in the calculation of the z_0 -derivative, this equation is the starting point to determine the τ -derivative of $Z_{0,n}^\tau((1, A), (0, B))$. In the following two subsections, we give the corresponding formula in terms of the S -map and a closed expression.

C.1 S -map formula

Let us start with deriving the S -map formula, continuing from eq. (C.4) similar to the calculation of the z_0 -derivative. In order to rewrite the last sum, the operator in front of the product $\varphi^\tau(1, A) \varphi^\tau(0, B)$ is expressed as follows

$$\begin{aligned}
& \left(f_{a_k, b_j}^{(1)} \left(\theta_{k \geq 1} \partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} \right) - f_{b_j, a_k}^{(2)} \right) \varphi^\tau(1, A) \varphi^\tau(0, B) \\
& = \left(\theta_{k \geq 1} \partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} - \partial_\xi \right) \Omega_{a_k, b_j}(\xi) \varphi^\tau(1, A) \varphi^\tau(0, B) \Big|_{\xi^0}, \tag{C.5}
\end{aligned}$$

such that eq. (B.53) can be used again. Due to the shifts $\mp \xi$ in the variables $\eta_{a_k} - \xi$ and $\eta_{b_j} + \xi$, the additional differential operator $\partial_{\eta_{a_k}} - \partial_{\eta_{b_j}} - \partial_\xi$ acts only non-trivially on the factor Ω_{01} in eq. (B.53). For the first sum in eq. (B.53), this amounts to projecting out a second derivative in analogy to eq. (B.41), since for $k \neq 0$

$$\begin{aligned}
& \left(\partial_{\eta_{a_k}} - \partial_{\eta_{b_j}} - \partial_\xi \right) \left(\Omega_{1,0}(\xi) \Omega_{a_{k-1}, a_k}(\eta_{a_k} - \xi) \right) \Big|_{\xi^0} \\
& = \left(-\frac{1}{\xi^2} + f_{1,0}^{(2)} + \mathcal{O}(\xi) \right) \left(\Omega_{a_{k-1}, a_k}(\eta_{a_k}) - \xi \partial_{\eta_{a_k}} \Omega_{a_{k-1}, a_k}(\eta_{a_k}) + \frac{\xi^2}{2} \partial_{\eta_{a_k}}^2 \Omega_{a_{k-1}, a_k}(\eta_{a_k}) + \mathcal{O}(\xi) \right) \Big|_{\xi^0} \\
& = \left(f_{01}^{(2)} - \frac{1}{2} \partial_{\eta_{a_k}}^2 \right) \Omega_{a_{k-1}, a_k}(\eta_{a_k}), \tag{C.6}
\end{aligned}$$

and more generally

$$\begin{aligned}
& \left(\theta_{k \geq 1} \partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} - \partial_\xi \right) \left(\Omega_{1,0}(\xi) \varphi^\tau(1, A) \Big|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi} \varphi^\tau(0, B) \Big|_{\eta_{b_j} \rightarrow \eta_{b_j} + \xi} \right) \Big|_{\xi^0} \\
& = \left(f_{01}^{(2)} - \frac{1}{2} \left(\theta_{k \geq 1} \partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} \right)^2 \right) \varphi^\tau(1, A) \varphi^\tau(0, B). \tag{C.7}
\end{aligned}$$

Thus, if we apply $(\theta_{k \geq 1} \partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} - \partial_\xi)$ on the first sum in eq. (B.53), its ξ^0 -part is given by

$$\begin{aligned}
& \left(\sum_{k=0}^p \sum_{j=0}^q s_{a_k, b_j} \left(\theta_{k \geq 1} \partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} - \partial_\xi \right) \Omega_{1,0}(\xi) \varphi^\tau(1, A) \varphi^\tau(0, B) \Big|_{\eta_{a_k} \rightarrow \eta_{a_k} - \xi, \eta_{b_j} \rightarrow \eta_{b_j} + \xi} \right) \Big|_{\xi^0} \\
& = \left(s_{(1,A),(0,B)} f_{01}^{(2)} - \frac{1}{2} \sum_{k=0}^p \sum_{j=0}^q s_{a_k, b_j} \left(\theta_{k \geq 1} \partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} \right)^2 \right) \varphi^\tau(1, A) \varphi^\tau(0, B), \tag{C.8}
\end{aligned}$$

such that the identity (B.53) implies

$$\sum_{k=0}^p \sum_{j=0}^q s_{a_k, b_j} \left(f_{a_k, b_j}^{(1)} \left(\theta_{k \geq 1} \partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} \right) - f_{b_j, a_k}^{(2)} \right) \varphi^\tau(1, A) \varphi^\tau(0, B)$$

$$\begin{aligned}
&= \left(\frac{1}{2} \sum_{k=0}^p \sum_{j=0}^q s_{a_k, b_j} \left(\theta_{k \geq 1} \partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} \right)^2 - s_{(1,A), (0,B)} f_{01}^{(2)} \right) \varphi^\tau(1, A) \varphi^\tau(0, B) \\
&\quad - \sum_{l=1}^q \Omega_{01}^+(\eta_{B_{l,q+1}}) \varphi^\tau(0, B_{1l}) \varphi^\tau(S[(1, A), B_{l,q+1}]) \\
&\quad - \sum_{i=1}^p \Omega_{01}^-(\eta_{A_{i,p+1}}) \varphi^\tau(1, A_{1i}) \varphi^\tau(S[(0, B), A_{l,q+1}]), \tag{C.9}
\end{aligned}$$

where

$$\Omega_{01}^\pm(\pm\xi) = \pm \partial_\xi \Omega_{01}(\pm\xi). \tag{C.10}$$

The second and third sum in eq. (C.4) can be calculated similarly. We find for example

$$\begin{aligned}
&\sum_{k=1}^p \sum_{j=0}^{k-1} s_{a_k, a_j} \left(f_{a_k, a_j}^{(1)} \left(\partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{a_j}} \right) + f_{a_k, a_j}^{(2)} \right) \varphi^\tau(1, A) \varphi^\tau(0, B) \\
&= \varphi^\tau(0, B) \sum_{k=1}^p \sum_{j=0}^{k-1} s_{a_k, a_j} \left(\left(\partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{a_j}} + \partial_\xi \right) \Omega_{a_k, a_j}(\xi) \varphi^\tau(1, A) \right) |_{\xi^0}, \tag{C.11}
\end{aligned}$$

where using eq. (A.14) gives

$$\begin{aligned}
&\Omega_{a_k, a_j}(\xi) \varphi^\tau(1, A) \\
&= \Omega_{a_k, a_j}(\xi) \varphi^\tau(A_{0,j+1}) |_{\eta_j \rightarrow \eta_{A_{j,p+1}}} \varphi^\tau(a_j, A_{j+1,k}, a_k, A_{k+1,p+1}) \\
&= \Omega_{a_k, a_j}(\xi) \varphi^\tau(A_{0,j+1}) |_{\eta_j \rightarrow \eta_{A_{j,p+1}}} \sum_{l=j+1}^k (-1)^{k-l} \varphi^\tau(a_j, A_{j+1,l}) \varphi^\tau(a_j, a_k, \tilde{A}_{l,k} \sqcup A_{k+1,p+1}) \\
&= \varphi^\tau(A_{0,j+1}) |_{\eta_j \rightarrow \eta_{A_{j,p+1}}} \sum_{l=j+1}^k (-1)^{k-l} \varphi^\tau(a_j, A_{j+1,l}) \\
&\quad \times \Omega_{a_k, a_j}(\xi) \Omega_{a_j, a_k}(\eta_{A_{l,p+1}}) \varphi^\tau(a_k, \tilde{A}_{l,k} \sqcup A_{k+1,p+1}). \tag{C.12}
\end{aligned}$$

With the identity [17, 18]

$$(\partial_\eta + \partial_\xi) \Omega_{k,j}(\xi) \Omega_{j,k}(\eta) = (\wp(\eta) - \wp(\xi)) \Omega_{j,k}(\eta - \xi) \tag{C.13}$$

and extracting its ξ^0 contribution

$$((\partial_\eta + \partial_\xi) \Omega_{k,j}(\xi) \Omega_{j,k}(\eta)) |_{\xi^0} = \left(\wp(\eta) - \frac{1}{2} \partial_\eta^2 \right) \Omega_{j,k}(\eta) \tag{C.14}$$

we can continue to find

$$\begin{aligned}
&\left(\left(\partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{a_j}} + \partial_\xi \right) \Omega_{a_k, a_j}(\xi) \varphi^\tau(1, A) \right) |_{\xi^0} \\
&= \varphi^\tau(A_{0,j+1}) |_{\eta_j \rightarrow \eta_{A_{j,p+1}}} \sum_{l=j+1}^k (-1)^{k-l} \varphi^\tau(a_j, A_{j+1,l}) \\
&\quad \left(\left(\partial_{\eta_{a_k}} + \partial_\xi \right) \Omega_{a_k, a_j}(\xi) \Omega_{a_j, a_k}(\eta_{A_{l,p+1}}) \right) |_{\xi^0} \varphi^\tau(a_k, \tilde{A}_{l,k} \sqcup A_{k+1,p+1}) \\
&= \varphi^\tau(A_{0,j+1}) |_{\eta_j \rightarrow \eta_{A_{j,p+1}}} \sum_{l=j+1}^k (-1)^{k-l} \varphi^\tau(a_j, A_{j+1,l})
\end{aligned}$$

$$\begin{aligned}
& \left(\wp(\eta_{A_{l,p+1}}) - \frac{1}{2} \partial_{\eta_{a_k}}^2 \right) \Omega_{a_j, a_k}(\eta_{A_{l,p+1}}) \varphi^\tau(a_k, \tilde{A}_{l,k} \sqcup A_{k+1,p+1}) \\
&= -\frac{1}{2} \left(\partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{a_j}} \right)^2 \varphi^\tau(1, A) \\
& \quad + \sum_{l=j+1}^k \wp(\eta_{A_{l,p+1}}) (-1)^{k-l} \varphi^\tau(A_{0,j+1})|_{\eta_j \rightarrow \eta_{A_{j,p+1}}} (-1)^{l-j-1} \varphi^\tau(\tilde{A}_{j+1,l}, a_j)|_{\eta_{a_j} \rightarrow -\eta_{A_{j+1,l}}} \\
& \quad \varphi^\tau(a_j, a_k, \tilde{A}_{l,k} \sqcup A_{k+1,p+1}) \\
&= -\frac{1}{2} \left(\partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{a_j}} \right)^2 \varphi^\tau(1, A) \\
& \quad + \sum_{l=j+1}^k \wp(\eta_{A_{l,p+1}}) (-1)^{k-j-1} \varphi^\tau(A_{0,j} \sqcup \tilde{A}_{j+1,l}, a_j, a_k, \tilde{A}_{l,k} \sqcup A_{k+1,p+1}), \tag{C.15}
\end{aligned}$$

where we have used the reflection property (A.12) and again the identity (A.14) in the reverse direction, to pull out the appropriate second derivative for the second last equality. Thus, we finally obtain

$$\begin{aligned}
& \left(\left(\partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{a_j}} + \partial_\xi \right) \Omega_{a_k, a_j}(\xi) \varphi^\tau(1, A) \right)|_{\xi^0} = -\frac{1}{2} \left(\partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{a_j}} \right)^2 \varphi^\tau(1, A) \\
& \quad + \sum_{l=j+1}^k \wp(\eta_{A_{l,p+1}}) (-1)^{k-j-1} \varphi^\tau(A_{0,j} \sqcup \tilde{A}_{j+1,l}, a_j, a_k, \tilde{A}_{l,k} \sqcup A_{k+1,p+1}). \tag{C.16}
\end{aligned}$$

Therefore, plugging the above identity into the sum (C.11) yields

$$\begin{aligned}
& \sum_{k=1}^p \sum_{j=0}^{k-1} s_{a_k, a_j} \left(f_{a_k, a_j}^{(1)} \left(\partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{a_j}} \right) + f_{a_k, a_j}^{(2)} \right) \varphi^\tau(1, A) \varphi^\tau(0, B) \\
&= -\sum_{k=1}^p \sum_{j=0}^{k-1} \frac{1}{2} \left(\partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{a_j}} \right)^2 s_{a_k, a_j} \varphi^\tau(1, A) \varphi^\tau(0, B) \\
& \quad + \sum_{k=1}^p \sum_{j=0}^{k-1} s_{a_k, a_j} \sum_{l=j+1}^k \wp(\eta_{A_{l,p+1}}) (-1)^{k-j-1} \varphi^\tau(A_{0,j} \sqcup \tilde{A}_{j+1,l}, a_j, a_k, \tilde{A}_{l,k} \sqcup A_{k+1,p+1}) \varphi^\tau(0, B) \\
&= -\sum_{k=1}^p \sum_{j=0}^{k-1} \frac{1}{2} \left(\partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{a_j}} \right)^2 s_{a_k, a_j} \varphi^\tau(1, A) \varphi^\tau(0, B) \\
& \quad + \sum_{l=1}^p \wp(\eta_{A_{l,p+1}}) \varphi^\tau(0, B) \varphi^\tau(S[(1, A_{1,l}), A_{l,p+1}]). \tag{C.17}
\end{aligned}$$

Analogously, the third term in the sum in eq. (C.4) is

$$\begin{aligned}
& \sum_{k=1}^q \sum_{j=0}^{k-1} s_{b_k, b_j} \left(f_{b_k, b_j}^{(1)} \left(\partial_{\eta_{b_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} \right) + f_{b_k, b_j}^{(2)} \right) \varphi^\tau(0, B) \varphi^\tau(1, A) \\
&= -\sum_{k=1}^q \sum_{j=0}^{k-1} \frac{1}{2} \left(\partial_{\eta_{b_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} \right)^2 s_{b_k, b_j} \varphi^\tau(1, A) \varphi^\tau(0, B) \\
& \quad + \sum_{l=1}^q \wp(\eta_{B_{l,p+1}}) \varphi^\tau(1, A) \varphi^\tau(S[(0, B_{1,l}), B_{l,p+1}]), \tag{C.18}
\end{aligned}$$

which was the last term missing, such that the whole eq. (C.4) is expressed in terms of the S -map leading to eq. (4.42). This formula is similar to the S -map formula (4.26) for the z_0 -derivative:

the differences are the diagonal term, i.e. the first sum proportional to $Z_{0,n}^\tau((1, A), (0, B))$, the derivatives $\Omega_{01}^+(\eta_{B_{l,q+1}})$, $\Omega_{01}^-(-\eta_{A_{l,p+1}})$ instead of $\Omega_{01}(\eta_{B_{l,q+1}})$, $\Omega_{01}(-\eta_{A_{l,p+1}})$, respectively, and the appearance of the terms including the Weierstraß \wp -function.

C.2 Closed formula

Similarly, we obtain a closed formula for the τ -derivative continuing from eq. (C.4). The last sum can be rewritten using the results in eqs. (B.33) to (B.37) from the z_0 -derivative

$$\begin{aligned}
& \sum_{k=0}^p \sum_{j=0}^q s_{a_k, b_j} \left(f_{a_k, b_j}^{(1)} \left(\theta_{k \geq 1} \partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} \right) - f_{a_k, b_j}^{(2)} \right) \varphi^\tau(1, A) \varphi^\tau(0, B) \\
&= \sum_{k=0}^p \sum_{j=0}^q s_{a_k, b_j} \left(\theta_{k \geq 1} \partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} - \partial_\xi \right) \Omega_{a_k, b_j}(\xi) \varphi^\tau(1, A) \varphi^\tau(0, B) \Big|_{\xi^0} \\
&= \left(\frac{1}{2} \sum_{k=0}^p \sum_{j=0}^q s_{a_k, b_j} \left(\theta_{k \geq 1} \partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} \right)^2 - s_{(1, A), (0, B)} f_{01}^{(2)} \right) \varphi^\tau(1, A) \varphi^\tau(0, B) \\
&\quad - \sum_{k=0}^p \sum_{j=0}^q s_{a_k, b_j} \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \Omega_{01}^+(\eta_{B_{l,q+1}}) \varphi^\tau(0, B_{1l}) \\
&\quad \quad \times \varphi^\tau(1, A_{1i} \sqcup (a_k, (\tilde{A}_{i,k} \sqcup A_{k+1,p+1}) \sqcup (b_j, \tilde{B}_{l,j} \sqcup B_{j+1,q+1}))) \\
&\quad - \sum_{k=0}^p \sum_{j=0}^q s_{a_k, b_j} \sum_{i=1}^k \sum_{l=1}^j (-1)^{k+j-i-l} \Omega_{01}^-(-\eta_{A_{i,p+1}}) \varphi^\tau(1, A_{1i}) \\
&\quad \quad \times \varphi^\tau(0, B_{1l} \sqcup (b_j, (\tilde{B}_{l,j} \sqcup B_{j+1,q+1}) \sqcup (a_k, \tilde{A}_{i,k} \sqcup A_{k+1,p+1}))). \tag{C.19}
\end{aligned}$$

The second sum can be expressed from eq. (C.12) using a similar calculation as in eq. (C.15) as follows:

$$\begin{aligned}
& \left(\left(\partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{a_j}} + \partial_\xi \right) \Omega_{a_k, a_j}(\xi) \varphi^\tau(1, A) \right) \Big|_{\xi^0} \\
&= \varphi^\tau(A_{0,j+1}) \Big|_{\eta_j \rightarrow \eta_{A_{j,p+1}}} \sum_{l=j+1}^k (-1)^{k-l} \varphi^\tau(A_{j,l}) \\
& \quad \left(\left(\partial_{\eta_{a_k}} + \partial_\xi \right) \Omega_{a_k, a_j}(\xi) \Omega_{a_j, a_k}(\eta_{A_{l,p+1}}) \right) \Big|_{\xi^0} \varphi^\tau(a_k, \tilde{A}_{l,k} \sqcup A_{k+1,p+1}) \\
&= \varphi^\tau(A_{0,j+1}) \Big|_{\eta_j \rightarrow \eta_{A_{j,p+1}}} \sum_{l=j+1}^k (-1)^{k-l} \varphi^\tau(A_{j,l}) \\
& \quad \left(\wp(\eta_{A_{l,p+1}}) - \frac{1}{2} \partial_{\eta_{a_k}}^2 \right) \Omega_{a_j, a_k}(\eta_{A_{l,p+1}}) \varphi^\tau(a_k, \tilde{A}_{l,k} \sqcup A_{k+1,p+1}) \\
&= -\frac{1}{2} \left(\partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{a_j}} \right)^2 \varphi^\tau(1, A) \\
& \quad + \sum_{l=j+1}^k \wp(\eta_{A_{l,p+1}}) (-1)^{k-l} \varphi^\tau(A_{0,j+1}) \Big|_{\eta_{a_j} \rightarrow \eta_{A_{j,p+1}}} \varphi^\tau(a_j, A_{j+1,l} \sqcup (a_k, \tilde{A}_{l,k} \sqcup A_{k+1,p+1})) \\
&= -\frac{1}{2} \left(\partial_{\eta_{a_k}} - \theta_{j \geq 1} \partial_{\eta_{a_j}} \right)^2 \varphi^\tau(1, A)
\end{aligned}$$

$$+ \sum_{l=j+1}^k \wp(\eta_{A_{l,p+1}}) (-1)^{k-l} \varphi^\tau(1, A_{1,j}, a_j, A_{j+1,l} \sqcup (a_k, \tilde{A}_{l,k} \sqcup A_{k+1,p+1})), \quad (\text{C.20})$$

while the third sum in eq. (C.4) is given by

$$\begin{aligned} & \left(\left(\partial_{\eta_{b_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} + \partial_\xi \right) \Omega_{b_k, b_j}(\xi) \varphi^\tau(0, B) \right) |_{\xi^0} = -\frac{1}{2} \left(\partial_{\eta_{b_k}} - \theta_{j \geq 1} \partial_{\eta_{b_j}} \right)^2 \varphi^\tau(0, B) \\ & + \sum_{l=j+1}^k \wp(\eta_{B_{l,q+1}}) (-1)^{k-l} \varphi^\tau(0, B_{1,j}, b_j, B_{j+1,l} \sqcup (b_k, \tilde{B}_{l,k} \sqcup B_{k+1,q+1})). \end{aligned} \quad (\text{C.21})$$

Altogether, this leads to the closed expression of the τ -derivative as given in eq. (4.44). Note that as for the S -map formula, the only difference compared to the closed z_0 -derivative (4.21) are the diagonal term (first sum), the derivatives $\Omega_{01}^+(\eta_{B_{l,q+1}})$, $\Omega_{01}^-(-\eta_{A_{l,p+1}})$ instead of $\Omega_{01}(\eta_{B_{l,q+1}})$, $\Omega_{01}(-\eta_{A_{l,p+1}})$, respectively, and the appearance of the terms including the Weierstraß \wp -function (the second and third sum).

C.3 Three-point example

This appendix complements the discussion of the three-point τ -derivative in section 4.3.3 by expressing $\partial_\tau \mathbf{Z}_{0,3}^\tau$ in terms of Weierstraß \wp -functions and Kronecker–Eisenstein series. The τ -derivative following from eqs. (4.42) and (4.44) is given by

$$\begin{aligned} 2\pi i \partial_\tau \mathbf{Z}_{0,3}^\tau &= \left(\frac{1}{2} (s_{02} + s_{12}) \partial_{\eta_2}^2 + \frac{1}{2} (s_{03} + s_{13}) \partial_{\eta_3}^2 + \frac{1}{2} s_{23} (\partial_{\eta_2} - \partial_{\eta_3})^2 - 2\zeta_2 s_{0123} \right) \mathbf{Z}_{0,3}^\tau \\ &- \text{diag}(s_{0,123}, s_{0,123}, s_{03,12}, s_{02,13}, s_{023,1}, s_{023,1}) f_{01}^{(2)} \mathbf{Z}_{0,3}^\tau + \begin{pmatrix} d_{11}^\tau & d_{12}^\tau & d_{13}^\tau \\ d_{21}^\tau & d_{22}^\tau & d_{23}^\tau \\ d_{31}^\tau & d_{32}^\tau & d_{33}^\tau \end{pmatrix} \mathbf{Z}_{0,3}^\tau, \end{aligned} \quad (\text{C.22})$$

where d_{ij}^τ denote 2×2 blocks: while the diagonal blocks depend on η_2, η_3 via Weierstraß functions,

$$\begin{aligned} d_{11}^\tau &= \begin{pmatrix} -s_{12} \wp(\eta_{23}) - (s_{13} + s_{23}) \wp(\eta_3) & s_{13} [\wp(\eta_{23}) - \wp(\eta_3)] \\ s_{12} [\wp(\eta_{23}) - \wp(\eta_2)] & -s_{13} \wp(\eta_{23}) - (s_{12} + s_{23}) \wp(\eta_2) \end{pmatrix}, \\ d_{22}^\tau &= \begin{pmatrix} -s_{12} \wp(\eta_2) - s_{03} \wp(\eta_3) & 0 \\ 0 & -s_{13} \wp(\eta_3) - s_{02} \wp(\eta_2) \end{pmatrix}, \\ d_{33}^\tau &= \begin{pmatrix} -s_{03} \wp(\eta_{23}) - (s_{02} + s_{23}) \wp(\eta_2) & s_{02} [\wp(\eta_{23}) - \wp(\eta_2)] \\ s_{03} [\wp(\eta_{23}) - \wp(\eta_3)] & -s_{02} \wp(\eta_{23}) - (s_{03} + s_{23}) \wp(\eta_3) \end{pmatrix}, \end{aligned} \quad (\text{C.23})$$

the off-diagonal ones involve the derivatives (4.43) of the Kronecker–Eisenstein series

$$\begin{aligned} d_{12}^\tau &= \begin{pmatrix} s_{03} \Omega_{01}^-(-\eta_3) & 0 \\ 0 & s_{02} \Omega_{01}^-(-\eta_2) \end{pmatrix}, \\ d_{13}^\tau &= \Omega_{01}^-(-\eta_{23}) \begin{pmatrix} -s_{03} & s_{02} \\ s_{03} & -s_{02} \end{pmatrix}, \\ d_{21}^\tau &= \begin{pmatrix} (s_{13} + s_{23}) \Omega_{01}^+(\eta_3) & s_{13} \Omega_{01}^+(\eta_3) \\ s_{12} \Omega_{01}^+(\eta_2) & (s_{12} + s_{23}) \Omega_{01}^+(\eta_2) \end{pmatrix}, \\ d_{23}^\tau &= \begin{pmatrix} (s_{02} + s_{23}) \Omega_{01}^-(-\eta_2) & s_{02} \Omega_{01}^-(-\eta_2) \\ s_{03} \Omega_{01}^-(-\eta_3) & (s_{03} + s_{23}) \Omega_{01}^-(-\eta_3) \end{pmatrix}, \end{aligned} \quad (\text{C.24})$$

$$d_{31}^\tau = \Omega_{01}^+(\eta_{23}) \begin{pmatrix} -s_{12} & s_{13} \\ s_{12} & -s_{13} \end{pmatrix},$$

$$d_{32}^\tau = \begin{pmatrix} s_{12}\Omega_{01}^+(\eta_2) & 0 \\ 0 & s_{13}\Omega_{01}^+(\eta_3) \end{pmatrix}.$$

Based on (C.22) and the η -expansion of (C.23) and (C.24), one arrives at the expressions for $r_{0,3}(\epsilon_k)$ and $r_{0,3}(b_k)$ given in section 4.3.3.

D Recovering genus-one Selberg integrals

In this appendix, we relate the language used in section 4 to the genus-one Selberg integrals (3.32) employed in ref. [2].

D.1 Recovering genus-one Selberg integrals

Let us begin with defining the generating series of genus-one Selberg integrals with expansion variables ξ_ℓ :

$$T_{0,n}^\tau \left[\begin{matrix} \xi_2, \xi_3, \dots, \xi_n \\ i_2, i_3, \dots, i_n \end{matrix} \right] = \int_{0 < z_2 < z_3 < \dots < z_n < z_0} dz_2 \cdots dz_n \text{KN}_{012\dots n}^\tau \Omega_{i_2 2}(\xi_2) \Omega_{i_3 3}(\xi_3) \cdots \Omega_{i_n n}(\xi_n)$$

$$= e^{s_{01\dots n} \omega(1,0|\tau)} \sum_{k_2, \dots, k_n \geq 0} (-1)^{k_2 + \dots + k_n} \xi_2^{k_2-1} \cdots \xi_n^{k_n-1} \text{S}_n^E \left[\begin{matrix} k_n, \dots, k_2 \\ i_n, \dots, i_2 \end{matrix} \right] (z_0), \quad (\text{D.1})$$

where the i_ℓ satisfy the admissibility condition (3.33), i.e. $i_\ell \in \{0, 1, \ell+1, \ell+2, \dots, n\}$. The integrals $T_{0,n}^\tau$ are related to the augmented Z -integrals $Z_{0,n}^\tau$ by Fay identities.

This connection can be understood from the graphical approach in section 4.1 since the integrand $\Omega_{i_2 2}(\xi_2) \cdots \Omega_{i_n n}(\xi_n)$ of eq. (D.1) with admissible i_ℓ agrees precisely with the one in eq. (4.8). Once the ξ_ℓ are identified as suitable linear combinations of $\eta_2, \eta_3, \dots, \eta_n$ to be denoted by $\eta_{C_\ell(\vec{i})}$, one can use Fay identities to expand

$$T_{0,n}^\tau \left[\begin{matrix} \eta_{C_2(\vec{i})} & \eta_{C_3(\vec{i})} & \cdots & \eta_{C_n(\vec{i})} \\ i_2 & i_3 & \cdots & i_n \end{matrix} \right] = \sum_{A,B} m_{A,B}^{\vec{i}} Z_{0,n}^\tau((1,A), (0,B)) \quad (\text{D.2})$$

with coefficients $m_{A,B}^{\vec{i}} \in \mathbb{Z}$, and the sum runs over all disjoint sequences $A = (a_1, a_2, \dots, a_p)$ and $B = (b_1, b_2, \dots, b_q)$ such that $A \cup B = \{2, 3, \dots, n\}$. The linear combinations $\xi_\ell = \eta_{C_\ell(\vec{i})}$ are fixed from the discussion in section 4.1.1: the labels $\vec{i} = (i_2, i_3, \dots, i_n)$ of the integrand $\Omega_{i_2 2}(\xi_2) \cdots \Omega_{i_n n}(\xi_n)$ in eq. (D.1) define a graph which in turn identifies $\xi_\ell = \eta_{C_\ell(\vec{i})}$ with a linear combination of $\eta_2, \eta_3, \dots, \eta_n$ through the weights of its edges as explained below eq. (4.8).

In the same way as the $Z_{0,n}^\tau((1,A), (0,B))$ are gathered in the $n!$ -component vector $\mathbf{Z}_{0,n}^\tau$ in eq. (4.3), we introduce an $n!$ -component vector of admissible integrals eq. (D.1),

$$\mathbf{T}_{0,n}^\tau = \left(T_{0,n}^\tau \left[\begin{matrix} \eta_{C_2(\vec{i})} & \eta_{C_3(\vec{i})} & \cdots & \eta_{C_n(\vec{i})} \\ i_2 & i_3 & \cdots & i_n \end{matrix} \right] \right) \text{ for } i_\ell \in \{0, 1, \ell+1, \ell+2, \dots, n\}. \quad (\text{D.3})$$

In this setting, eq. (D.2) defines an $n! \times n!$ transformation matrix M_n with integer entries,

$$\mathbf{T}_{0,n}^\tau = M_n \mathbf{Z}_{0,n}^\tau. \quad (\text{D.4})$$

This basis transformation relates the component integrals of the augmented Z -integrals to the

genus-one Selberg integrals by means of eq. (D.1).

D.1.1 Two-point example

Let us illustrate the above definitions and the calculation of the transformation matrix M_n on the two- and three-point examples. In the two-point case, the two integrals are

$$T_{0,n}^\tau \begin{bmatrix} \xi_2 \\ i_2 \end{bmatrix} = \int_0^{z_0} dz_2 \text{KN}_{012}^\tau \Omega_{i_2 2}(\xi_2) \quad (\text{D.5})$$

whose ξ_2 -variable is identified with η_2 for both of $i_2 = 0, 1$. The two vector components then trivially agree with $Z_{0,2}^\tau(1, 2)$ and $Z_{0,2}^\tau(0, 2)$, respectively,

$$\mathbf{T}_{0,2}^\tau = \begin{pmatrix} T_{0,2}^\tau \begin{bmatrix} \xi_2 \\ 1 \end{bmatrix} \\ T_{0,2}^\tau \begin{bmatrix} \xi_2 \\ 0 \end{bmatrix} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \mathbf{Z}_{0,2}^\tau. \quad (\text{D.6})$$

D.1.2 Three-point example

In the case of $n = 3$, the generating series eq. (D.1) specializes to

$$T_{0,3}^\tau \begin{bmatrix} \xi_2 & \xi_3 \\ i_2 & i_3 \end{bmatrix} = \int_0^{z_0} dz_3 \Omega_{i_3 3}(\xi_3) \int_0^{z_3} dz_2 \Omega_{i_2 2}(\xi_2) \text{KN}_{0123}^\tau, \quad (\text{D.7})$$

and features six components $(i_2, i_3) \in \{0, 1, 3\} \times \{0, 1\}$ compatible with the admissibility condition. Those with $(i_2, i_3) \in \{(3, 1), (3, 0), (0, 1), (1, 0)\}$ immediately yield the Kronecker-Eisenstein series seen in a component of the $\mathbf{Z}_{0,3}^\tau$ -vector eq. (4.32) which settles the respective identifications of ξ_2, ξ_3 with the η_j -variables:

$$\begin{aligned} T_{0,3}^\tau \begin{bmatrix} \eta_2 & \eta_{2,3} \\ 3 & 1 \end{bmatrix} &= Z_{0,3}^\tau(1, 3, 2), \\ T_{0,3}^\tau \begin{bmatrix} \eta_2 & \eta_{2,3} \\ 3 & 0 \end{bmatrix} &= Z_{0,3}^\tau(0, 3, 2), \\ T_{0,3}^\tau \begin{bmatrix} \eta_2 & \eta_3 \\ 0 & 1 \end{bmatrix} &= Z_{0,3}^\tau((1, 3), (0, 2)), \\ T_{0,3}^\tau \begin{bmatrix} \eta_2 & \eta_3 \\ 1 & 0 \end{bmatrix} &= Z_{0,3}^\tau((1, 2), (0, 3)). \end{aligned} \quad (\text{D.8})$$

The remaining entries of eq. (D.7) with $(i_2, i_3) = (1, 1)$ and $(i_2, i_3) = (0, 0)$ yield Kronecker-Eisenstein series $\Omega_{12}(\xi_2)\Omega_{13}(\xi_3)$ and $\Omega_{02}(\xi_2)\Omega_{03}(\xi_3)$, respectively. Their expansion in terms of entries of $Z_{0,3}^\tau((1, A), (0, B))$ via Fay relations uniquely selects $\xi_2 = \eta_2$ and $\xi_3 = \eta_3$,

$$T_{0,3}^\tau \begin{bmatrix} \eta_2 & \eta_3 \\ 1 & 1 \end{bmatrix} = Z_{0,3}^\tau(1, 2, 3) + Z_{0,3}^\tau(1, 3, 2) \quad (\text{D.9})$$

$$T_{0,3}^\tau \begin{bmatrix} \eta_2 & \eta_3 \\ 0 & 0 \end{bmatrix} = Z_{0,3}^\tau(0, 2, 3) + Z_{0,3}^\tau(0, 3, 2), \quad (\text{D.10})$$

such that the full basis transformation is given by

$$\mathbf{T}_{0,3}^\tau = \begin{pmatrix} T_{0,3}^\tau \begin{bmatrix} \eta_2 & \eta_3 \\ 1 & 1 \end{bmatrix} \\ T_{0,3}^\tau \begin{bmatrix} \eta_2 & \eta_{2,3} \\ 3 & 1 \end{bmatrix} \\ T_{0,3}^\tau \begin{bmatrix} \eta_2 & \eta_3 \\ 1 & 0 \end{bmatrix} \\ T_{0,3}^\tau \begin{bmatrix} \eta_2 & \eta_3 \\ 0 & 1 \end{bmatrix} \\ T_{0,3}^\tau \begin{bmatrix} \eta_2 & \eta_{2,3} \\ 3 & 0 \end{bmatrix} \\ T_{0,3}^\tau \begin{bmatrix} \eta_2 & \eta_3 \\ 0 & 0 \end{bmatrix} \end{pmatrix} = \begin{pmatrix} 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{pmatrix} \mathbf{Z}_{0,3}^\tau. \quad (\text{D.11})$$

D.2 Recovering the representation of $\mathbf{x}_{n,w}$

In ref. [2], it was shown that the differential equation of the vector of all admissible genus-one Selberg integrals (3.32) of a certain weight $w = k_2 + k_3 + \dots + k_n$, i.e.

$$\mathbf{S}_{n,w}^{\text{E}}(z_0|\tau) = \left(\mathbf{S}_n^{\text{E}} \begin{bmatrix} k_n, \dots, k_2 \\ i_n, \dots, i_2 \end{bmatrix} (z_0) \right) \text{ for } \begin{cases} k_2 + k_3 + \dots + k_n = w \\ i_\ell \in \{0, 1, \ell+1, \ell+2, \dots, n\} \end{cases} \quad (\text{D.12})$$

satisfies a differential equation of the form

$$\partial_0 \mathbf{S}_{n,w}^{\text{E}}(z_0|\tau) = \sum_{k=0}^{w+1} f_{01}^{(k)} r_{0,n}^{\text{E}}(x_{k,w}) \mathbf{S}_{n,w+1-k}^{\text{E}}(z_0|\tau), \quad (\text{D.13})$$

where the matrices $r_{0,n}^{\text{E}}(x_{k,w})$ are linear in the Mandelstam variables and play a crucial role in the associator construction proposed therein. These matrices are the finite, non-vanishing blocks of the matrices $r_{0,n}^{\text{E}}(x_k)$ in eq. (3.35). In this subsection, we show how these matrices can be related to the matrices $r_{0,n}(x_k)$ in the KZB equation (4.14).

The basis transformation (D.4) along with eq. (4.14) imply that the vector of integrals $\mathbf{T}_{0,n}^\tau$ satisfies the KZB equation

$$\partial_0 \mathbf{T}_{0,n}^\tau = \sum_{k=0}^{\infty} f_{01}^{(k)} M_n r_{0,n}(x_k) M_n^{-1} \mathbf{T}_{0,n}^\tau. \quad (\text{D.14})$$

On the one hand, according to the definition (D.1) the vector $\mathbf{T}_{0,n}^\tau$ can be expressed as a linear combination of vectors $\mathbf{S}_w^{\text{E}}(z_0|\tau)$ as follows

$$\begin{aligned} \mathbf{T}_{0,n}^\tau &= e^{s_{01\dots n}\omega(1,0|\tau)} \sum_{k_2, \dots, k_n \geq 0} (-1)^{k_2 + \dots + k_n} \xi_2^{k_2-1} \dots \xi_n^{k_n-1} \\ &\quad \times \left(\mathbf{S}_n^{\text{E}} \begin{bmatrix} k_n, \dots, k_2 \\ i_n, \dots, i_2 \end{bmatrix} (z_0) \right) \text{ for } i_\ell \in \{0, 1, \ell+1, \ell+2, \dots, n\} \\ &= e^{s_{01\dots n}\omega(1,0|\tau)} \sum_{w=0}^{\infty} (-1)^w M_{n,w} \mathbf{S}_{n,w}^{\text{E}}(z_0|\tau), \end{aligned} \quad (\text{D.15})$$

where $M_{n,w}$ is a matrix of homogeneous degree $w+1-n$ in the variables ξ . The entries of $M_{n,w}$ are engineered to reproduce the linear combination of the length- $n!$ vector of admissible

genus-one Selberg integrals in the first line of eq. (D.15) for a certain sequence (k_2, \dots, k_n) :

$$M_{n,w} \mathbf{S}_{n,w}^E(z_0|\tau) = \sum_{\substack{k_2, \dots, k_n \geq 0 \\ k_2 + \dots + k_n = w}} \xi_2^{k_2-1} \dots \xi_n^{k_n-1} \left(\mathbf{S}_n^E \left[\begin{matrix} k_n, \dots, k_2 \\ i_n, \dots, i_2 \end{matrix} \right] (z_0) \right) \text{ for } i_\ell \in \{0, 1, \ell+1, \ell+2, \dots, n\}. \quad (\text{D.16})$$

Thus, we obtain

$$\partial_0 \mathbf{T}_{0,n}^\tau = e^{s_{01} \dots \omega(1,0|\tau)} \sum_{k=0}^{\infty} \sum_{w=0}^{\infty} (-1)^w f_{01}^{(k)} M_n r_{0,n}^E(x_k) M_n^{-1} M_{n,w} \mathbf{S}_{n,w}^E(z_0|\tau). \quad (\text{D.17})$$

On the other hand, the derivative $\partial_0 \mathbf{T}_{0,n}^\tau$ can also be calculated using eq. (D.13), which leads to

$$\begin{aligned} \partial_0 \mathbf{T}_{0,n}^\tau &= e^{s_{01} \dots \omega(1,0|\tau)} \sum_{w=0}^{\infty} (-1)^w M_{n,w} \partial_0 \mathbf{S}_{n,w}^E(z_0|\tau) \\ &= e^{s_{01} \dots \omega(1,0|\tau)} \sum_{w=0}^{\infty} (-1)^w M_{n,w} \sum_{k=0}^{w+1} f_{01}^{(k)} r_{0,n}^E(x_{k,w}) \mathbf{S}_{n,w+1-k}^E(z_0|\tau) \\ &= e^{s_{01} \dots \omega(1,0|\tau)} \sum_{k=0}^{\infty} \sum_{w \geq \max(0, k-1)} (-1)^w f_{01}^{(k)} M_{n,w} r_{0,n}^E(x_{k,w}) \mathbf{S}_{n,w+1-k}^E(z_0|\tau) \\ &= e^{s_{01} \dots \omega(1,0|\tau)} \sum_{k=0}^{\infty} \sum_{v=0}^{\infty} (-1)^{v+k-1} f_{01}^{(k)} (1 - \delta_{v,0} \delta_{k,0}) M_{n,v+k-1} r_{0,n}^E(x_{k,v+k-1}) \mathbf{S}_{n,v}^E(z_0|\tau), \end{aligned} \quad (\text{D.18})$$

where we have used the change of variables $v = w+1-k$. Comparing this with eq. (D.17) and using the independence of $f_{01}^{(k)}$ and $\mathbf{S}_{n,w}^E(z_0|\tau)$ for different k and w , respectively, we can conclude that for any $k, w \geq 0$

$$M_n r_{0,n}^E(x_k) M_n^{-1} M_{n,w} = (-1)^{k-1} (1 - \delta_{w,0} \delta_{k,0}) M_{n,w+k-1} r_{0,n}^E(x_{k,w+k-1}). \quad (\text{D.19})$$

This equation expresses the relation between the matrices $r_{0,n}(x_k)$ from section 4.2 and the submatrices $r_{0,n}^E(x_{k,w})$ of $r_{0,n}^E(x_k)$ appearing in the KZB equation in ref. [2].

D.2.1 Two-point example

Let us illustrate and check the formula (D.19) for the two-point example and the block-matrices given in eqs. (3.42) and (3.43). The latter encode the matrices $r_{0,n}^E(x_{k,w})$ for $k = 0, 1$ at weight $w = 0$

$$r_{0,2}^E(x_{0,0}) = -s_{12}, \quad r_{0,2}^E(x_{1,0}) = -s_{01}, \quad (\text{D.20})$$

for $k = 0, 1, 2$ at weight $w = 1$

$$r_{0,2}^E(x_{0,1}) = \begin{pmatrix} s_{02} & s_{02} \end{pmatrix}, \quad r_{0,2}^E(x_{1,1}) = -s_{012}, \quad r_{0,2}^E(x_{2,1}) = s_{02} \quad (\text{D.21})$$

and for $k = 1, 2$ at weight $w = 2$

$$r_{0,2}^E(x_{1,2}) = \begin{pmatrix} -(s_{01} + s_{02}) & s_{02} \\ s_{12} & -(s_{01} + s_{12}) \end{pmatrix}, \quad r_{0,2}^E(x_{2,2}) = \begin{pmatrix} -s_{12} \\ -s_{12} \end{pmatrix}. \quad (\text{D.22})$$

Moreover, comparing the first four entries of the two-point vector $\mathbf{S}_2^E(z_0)$ in eq. (3.41) with the defining eq. (D.12) of its constant weight subvectors $\mathbf{S}_{n,w}^E(z_0|\tau)$, we find that

$$\mathbf{S}_{2,0}^E(z_0|\tau) = \mathbf{S}_2^E \begin{bmatrix} 0 \\ 1 \end{bmatrix} (z_0), \quad \mathbf{S}_{2,1}^E(z_0|\tau) = \mathbf{S}_2^E \begin{bmatrix} 1 \\ 1 \end{bmatrix} (z_0), \quad \mathbf{S}_{2,2}^E(z_0|\tau) = \begin{pmatrix} \mathbf{S}_2^E \begin{bmatrix} 2 \\ 1 \end{bmatrix} (z_0) \\ \mathbf{S}_2^E \begin{bmatrix} 2 \\ 0 \end{bmatrix} (z_0) \end{pmatrix}. \quad (\text{D.23})$$

According to eq. (D.16), for $n = 2$ the matrices $M_{2,w}$ are defined by the equation

$$M_{2,w} \mathbf{S}_{2,w}^E(z_0|\tau) = \xi^{w-1} \begin{pmatrix} \mathbf{S}_n^E \begin{bmatrix} w \\ 1 \end{bmatrix} (z_0) \\ \mathbf{S}_n^E \begin{bmatrix} w \\ 0 \end{bmatrix} (z_0) \end{pmatrix} \quad (\text{D.24})$$

and, thus, for $w = 0, 1, 2$ they are given by

$$M_{2,0} = \eta^{-1} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad M_{2,1} = \begin{pmatrix} 1 \\ -\frac{s_{12}}{s_{02}} \end{pmatrix}, \quad M_{2,2} = \eta \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}. \quad (\text{D.25})$$

Now, we have all we need to check some configurations of k and w for eq. (D.19). We begin with $(k, w) = (0, 0)$ and $r_{0,2}(x_k)$ (for $k = 0, 1, 2$) from eq. (4.31), which leads to the equation

$$r_{0,2}(x_0)M_{2,0} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Leftrightarrow \begin{pmatrix} -s_{02}\partial_\eta & -s_{02}/\eta \\ s_{12}/\eta & s_{12}\partial_\eta \end{pmatrix} \eta^{-1} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \quad (\text{D.26})$$

which is indeed satisfied since $(\partial_\eta + \eta^{-1})\eta^{-1} = 0$. For $(k, w) = (0, 1)$ the right-hand side of eq. (D.19) is not vanishing and the full equation takes the form

$$r_{0,2}(x_0)M_{2,1} = -M_{2,0}r_{0,2}^E(x_{0,0}) \Leftrightarrow \begin{pmatrix} -s_{02}\partial_\eta & -s_{02}/\eta \\ s_{12}/\eta & s_{12}\partial_\eta \end{pmatrix} \begin{pmatrix} 1 \\ -\frac{s_{12}}{s_{02}} \end{pmatrix} = \eta^{-1} \begin{pmatrix} 1 \\ 1 \end{pmatrix} s_{12}, \quad (\text{D.27})$$

while for $(k, w) = (0, 2)$

$$r_{0,2}(x_0)M_{2,2} = -M_{2,1}r_{0,2}^E(x_{0,1}) \Leftrightarrow \begin{pmatrix} -s_{02}\partial_\eta & -s_{02}/\eta \\ s_{12}/\eta & s_{12}\partial_\eta \end{pmatrix} \eta \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} -1 \\ \frac{s_{12}}{s_{02}} \end{pmatrix} \begin{pmatrix} s_{02} & s_{02} \end{pmatrix}. \quad (\text{D.28})$$

The lowest-weight configurations for $k = 1$ are $(k, w) = (1, 0)$ leading to

$$r_{0,2}(x_1)M_{2,0} = M_{2,0}r_{0,2}^E(x_{1,0}) \Leftrightarrow \begin{pmatrix} -(s_{01}+s_{02}) & s_{02} \\ s_{12} & -(s_{01}+s_{12}) \end{pmatrix} \eta^{-1} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = -\eta^{-1} \begin{pmatrix} 1 \\ 1 \end{pmatrix} s_{01}, \quad (\text{D.29})$$

and $(k, w) = (1, 1)$ such that

$$r_{0,2}(x_1)M_{2,1} = M_{2,1}r_{0,2}^E(x_{1,1}) \Leftrightarrow \begin{pmatrix} -(s_{01}+s_{02}) & s_{02} \\ s_{12} & -(s_{01}+s_{12}) \end{pmatrix} \begin{pmatrix} 1 \\ -\frac{s_{12}}{s_{02}} \end{pmatrix} = -\begin{pmatrix} 1 \\ -\frac{s_{12}}{s_{02}} \end{pmatrix} s_{012}. \quad (\text{D.30})$$

Finally, $(k, w) = (1, 2)$ yields the equation

$$r_{0,2}(x_1)M_{2,2} = M_{2,2}r_{0,2}^E(x_{1,2}) \quad (\text{D.31})$$

which holds by $r_{0,2}(x_1) = r_{0,2}^E(x_{1,2})$ and $M_{2,2} = \eta \mathbf{1}_{2 \times 2}$.

For $k = 2$, we can check the following two configuration with the explicit examples given above: the weight-zero case $(k, w) = (2, 0)$

$$r_{0,2}(x_2)M_{2,0} = -M_{2,1}r_{0,2}^E(x_{2,1}) \Leftrightarrow \eta \begin{pmatrix} 0 & -s_{02} \\ s_{12} & 0 \end{pmatrix} \eta^{-1} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = - \begin{pmatrix} 1 \\ -\frac{s_{12}}{s_{02}} \end{pmatrix} s_{02} \quad (\text{D.32})$$

and weight one $(k, w) = (2, 1)$

$$r_{0,2}(x_2)M_{2,1} = -M_{2,2}r_{0,2}^E(x_{2,2}) \Leftrightarrow \eta \begin{pmatrix} 0 & -s_{02} \\ s_{12} & 0 \end{pmatrix} \begin{pmatrix} 1 \\ -\frac{s_{12}}{s_{02}} \end{pmatrix} = -\eta \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} -s_{12} \\ -s_{12} \end{pmatrix}. \quad (\text{D.33})$$

Thus, we have explicitly approved eq. (D.19) for the lowest-weight configurations involving the objects (D.20) to (D.22) and (D.25) at two points.

E Subleading terms in $C_{1,n}^\tau$

In this section, we address the claim above eq. (5.34). We argue that subleading terms appear in the limit $z_0 \rightarrow 1$ of $Z_{0,n}^\tau((1, A), (0, B))$ and estimate their order in $1-z_0$ by first giving the two-point example and afterwards generalizing to n points.

E.1 Two-point example

As seen in eq. (5.30), the integrand of

$$Z_{0,2}^\tau(1, 2) = \int_0^{z_0} dz_2 e^{-s_{01}\mathcal{G}_{01}^\tau - s_{02}\mathcal{G}_{02}^\tau - s_{12}\mathcal{G}_{12}^\tau} \Omega_{12}(\eta) \quad (\text{E.1})$$

has a leading singularity of order $(1-z_0)^{-s_{01}}$ as $z_0 \rightarrow 1$:

$$e^{-s_{01}\mathcal{G}_{01}^\tau - s_{02}\mathcal{G}_{02}^\tau - s_{12}\mathcal{G}_{12}^\tau} \Omega_{12}(\eta) = (-2\pi i(1-z_0))^{-s_{01}} e^{s_{01}\omega(1,0|\tau)} e^{-\tilde{s}_{12}\mathcal{G}_{12}^\tau} \Omega_{12}(\eta) + \mathcal{O}((1-z_0)^{-s_{01}+1}). \quad (\text{E.2})$$

This singularity appears due to the merging of the punctures $z_0 \rightarrow 1 \cong 0 = z_1$. However, in order to calculate the limit $z_0 \rightarrow 1$ of the integral, we can not simply set $z_0 = 1$ in eq. (E.1), which can be deduced using the following integral decomposition

$$Z_{0,2}^\tau(1, 2) = \int_0^1 dz_2 e^{-s_{01}\mathcal{G}_{01}^\tau - s_{02}\mathcal{G}_{02}^\tau - s_{12}\mathcal{G}_{12}^\tau} \Omega_{12}(\eta) - \int_{z_0}^1 dz_2 e^{-s_{01}\mathcal{G}_{01}^\tau - s_{02}\mathcal{G}_{02}^\tau - s_{12}\mathcal{G}_{12}^\tau} \Omega_{12}(\eta). \quad (\text{E.3})$$

Thus, taking $z_0 \rightarrow 1$ involves a subleading term given by the latter integral above, where the three punctures $z_0 < z_2 < 1 \cong z_1$ merge. Similar to the estimate (5.7) for the lower boundary value, this leads to a term of order $(1-z_0)^{-s_{012}}$,

$$\int_{z_0}^1 dz_2 e^{-s_{01}\mathcal{G}_{01}^\tau - s_{02}\mathcal{G}_{02}^\tau - s_{12}\mathcal{G}_{12}^\tau} \Omega_{12}(\eta) = \mathcal{O}((-2\pi i(1-z_0))^{-s_{012}}), \quad (\text{E.4})$$

as can for instance be checked through a change of variables $1-z_2 = x_2(1-z_0)$ with $x_2 \in (0, 1)$. Altogether, we find the estimate that for $z_0 \rightarrow 1$

$$Z_{0,2}^\tau(1, 2) = (-2\pi i(1-z_0))^{-s_{01}} e^{s_{01}\omega(1,0|\tau)} Z_2^\tau|_{\tilde{s}_{12}} + \mathcal{O}((1-z_0)^{-s_{01}+1}, (1-z_0)^{-s_{012}}). \quad (\text{E.5})$$

Therefore, if we follow the assumption (2.3), which implies $\text{Re}(s_{012}) < \text{Re}(s_{01}) < 0$, one can extract the finite value

$$\lim_{z_0 \rightarrow 1} (-2\pi i(1-z_0))^{s_{01}} Z_{0,2}^T(1,2) = e^{s_{01}\omega(1,0|\tau)} Z_2^T|_{\tilde{s}_{12}}, \quad (\text{E.6})$$

which reproduces the first component of eq. (5.46).

E.2 n -point generalization

The above argument can be applied to the n -point case by generalizing eq. (E.3) to the decomposition of the integration domain of the Z^τ integrals without augmentations

$$\{z_2, z_3, \dots, z_n \in \mathbb{R} \mid 0 = z_1 < z_2 < z_3 < \dots < z_n < 1\} = \gamma_{12\dots n0} \cup \left(\bigcup_{k=1}^{n-1} \gamma_{12\dots k,0,k+1\dots n} \right) \quad (\text{E.7})$$

with the following generalization of the integration domain $\gamma_{12\dots n0}$ in eq. (4.5):

$$\gamma_{12\dots k,0,k+1\dots n} = \{z_2, z_3, \dots, z_n \in \mathbb{R} \mid 0 = z_1 < z_2 < z_3 < \dots < z_k < z_0 < z_{k+1} < \dots < z_n < 1\}. \quad (\text{E.8})$$

These domains $\gamma_{12\dots k,0,k+1\dots n}$ with $k = 1, 2, \dots, n-1$ cause the $z_0 \rightarrow 1$ limit of $Z_{0,n}^\tau$ to deviate from the non-augmented Z_n^τ at arguments \tilde{s}_{ij} in eq. (5.32), see e.g. the second term in eq. (E.3) at $n = 2$. The scaling behaviour of $\gamma_{12\dots k,0,k+1\dots n}$ integrals in the limit $z_0 \rightarrow 1$ can be conveniently extracted by substituting $z_0 = 1-w_0$ and $z_j = 1-w_j$ for $j = k+1, \dots, n$ followed by the rescaling $w_j = w_0 x_j$, see eq. (E.4) for the two-point result. For a generic function F of z_2, z_3, \dots, z_n in the integrand, this amounts to parametrizing the merging of $n-k+2$ consecutive punctures $z_0 < z_{k+1} < \dots < z_n < 1 \cong z_1$ in the limit $z_0 \rightarrow 1$ or $w_0 \rightarrow 0$ via

$$\begin{aligned} \int_{\gamma_{12\dots k,0,k+1\dots n}} dz_2 \dots dz_n F(z_2, \dots, z_n) &= \int_{0 < z_2 < \dots < z_k < z_0} dz_2 \dots dz_k \int_{z_0 < z_{k+1} < \dots < z_n < 1} dz_{k+1} \dots dz_n F(z_2, \dots, z_n) \quad (\text{E.9}) \\ &= w_0^{n-k} \int_{0 < z_2 < \dots < z_k < z_0} dz_2 \dots dz_k \int_{0 < x_{k+1} < \dots < x_{k+1} < 1} dx_{k+1} \dots dx_n F(z_2, \dots, z_k, 1-x_{k+1}w_0, \dots, 1-x_nw_0). \end{aligned}$$

The integrands F relevant to $Z_{0,n}^\tau$ involve the augmented Koba-Nielsen factor which scales as $w_0^{-s_{01(k+1)\dots n}} = (1-z_0)^{-s_{01(k+1)\dots n}}$ in this limit. This can be seen by repeating the analysis of the $z_0 \rightarrow 0$ limit in eq. (5.7) with $w_0 = 1-z_0$ in the place of z_0 and employing the arguments seen on the right-hand side of eq. (E.9). Then, as for the two-point example, the condition (2.3), such that $\text{Re}(s_{01(k+1)\dots n}) < \text{Re}(s_{01}) < 0$, ensures that eq. (E.9) vanishes for $k = 1, 2, \dots, n-1$ if the $z_0 \rightarrow 1$ limit is taken in presence of the regulating factor $(-2\pi i(1-z_0))^{s_{01}}$ in front of $Z_{0,n}^\tau((1,A), (0,B))$ in eq. (5.34). Hence, the $w_0^{-s_{01(k+1)\dots n}}$ scaling of the Koba-Nielsen factor entering the F in eq. (E.9) implies our claim (5.34) for the regularized limit defining $\mathbf{C}_{1,n}^\tau$.

E.3 Further comments on subleading terms

Note that the additional scaling $\sim w_0^{n-k}$ in eq. (E.9) by integer powers does not affect the derivation of eq. (5.34) based on the scaling of the Koba-Nielsen factor: the prefactor w_0^{n-k} is either compensated by the Ω_{ij} in some of the vector components of $Z_{0,n}^\tau((1,A), (0,B))$, or it may suppress the contribution of $\gamma_{12\dots k,0,k+1\dots n}$ to eq. (E.7) in other vector components. At $n = 3$ points, for instance, the integrand of $Z_{0,3}^\tau$ in eq. (4.32) involves Kronecker-Eisenstein series with

the following scaling as $z_0 \rightarrow 1$ in the domains γ_{1023} and γ_{1203} of eq. (E.8):

$$\begin{aligned}
& \int_{\gamma_{1023}} dz_2 dz_3 \text{KN}_{0123}^\tau \begin{pmatrix} \Omega_{12}(\eta_{23})\Omega_{23}(\eta_3) \\ \Omega_{13}(\eta_{23})\Omega_{32}(\eta_2) \\ \Omega_{12}(\eta_2)\Omega_{03}(\eta_3) \\ \Omega_{13}(\eta_3)\Omega_{02}(\eta_2) \\ \Omega_{03}(\eta_{23})\Omega_{32}(\eta_2) \\ \Omega_{02}(\eta_{23})\Omega_{23}(\eta_3) \end{pmatrix} \xrightarrow{z_0 \rightarrow 1} w_0^2 \int_{0 < x_3 < x_2 < 1} dx_2 dx_3 \text{KN}_{0123}^\tau \begin{pmatrix} (w_0^2 x_2 x_3)^{-1} \\ (w_0^2 x_3 x_2)^{-1} \\ (w_0^2 x_2 (x_3 - 1))^{-1} \\ (w_0^2 x_3 (x_2 - 1))^{-1} \\ (w_0^2 x_2 x_3 (x_3 - 1))^{-1} \\ (w_0^2 x_3 x_2 (x_2 - 1))^{-1} \end{pmatrix} \quad (\text{E.10}) \\
& \int_{\gamma_{1203}} dz_2 dz_3 \text{KN}_{0123}^\tau \begin{pmatrix} \Omega_{12}(\eta_{23})\Omega_{23}(\eta_3) \\ \Omega_{13}(\eta_{23})\Omega_{32}(\eta_2) \\ \Omega_{12}(\eta_2)\Omega_{03}(\eta_3) \\ \Omega_{13}(\eta_3)\Omega_{02}(\eta_2) \\ \Omega_{03}(\eta_{23})\Omega_{32}(\eta_2) \\ \Omega_{02}(\eta_{23})\Omega_{23}(\eta_3) \end{pmatrix} \xrightarrow{z_0 \rightarrow 1} w_0 \int_0^{z_0} dz_2 \int_0^1 dx_3 \text{KN}_{0123}^\tau \begin{pmatrix} \Omega_{12}(\eta_{23})\Omega_{23}(\eta_3) \\ (w_0 x_3)^{-1} \Omega_{32}(\eta_2) \\ (w_0 (x_3 - 1))^{-1} \Omega_{12}(\eta_2) \\ (w_0 x_3)^{-1} \Omega_{02}(\eta_2) \\ (w_0 (x_3 - 1))^{-1} \Omega_{32}(\eta_2) \\ \Omega_{02}(\eta_{23})\Omega_{23}(\eta_3) \end{pmatrix}
\end{aligned}$$

In the first case of γ_{1023} , i.e. eq. (E.9) at $k = 1$, the Kronecker–Eisenstein series in all the six vector entries have a singular term that scales as w_0^{-2} and compensates the prefactor from w_0^{n-k} . In the second case of γ_{1203} , i.e. eq. (E.9) at $k = 2$, only the middle four vector components feature a Kronecker–Eisenstein series with most singular term w_0^{-1} . Accordingly, the first and last vector entry are suppressed by one additional power of w_0 as $w_0 \rightarrow 0$.

Still, this example illustrates that the analysis of vector entries with additional suppression by powers of w_0 does not play any role for the above conclusion: all components of eq. (E.9) vanish when the limit $w_0 \rightarrow 0$ is performed in presence of the regulating factor $(-2\pi i(1-z_0))^{s_{01}}$.

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